

INSTRUCTION MANUAL

3541

RESISTANCE HITESTER

HIOKI E.E. CORPORATION

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Introduction

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Thank you for purchasing the HIOKI "Model 3541 RESISTANCE HITESTER". To obtain maximum performance from the instrument, please read this manual carefully, and keep it handy for future reference.

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Inspection

| • | |
|--|---|
| Confirming package contents | When you receive the instrument, inspect it carefully to ensure that no damage occurred during shipping. In particular, check the accessories, panel switches, and connectors. If damage is evident, or if it fails to operate according to the specifications, contact your dealer or Hioki representative. |
| Instrument | 3541 RESISTANCE HITESTER |
| Accessories | 9287 CLIP TYPE LEAD |
| Shipping precautions | Use the original packing materials when transporting the instrument, if possible. |
| Options Test-Lead-Related (Page 176) | |
| Interface Cable | 9637 RS-232C CABLE (9-pin to 9-pin/cross cable) 9638 RS-232C CABLE (9-pin to 25-pin/cross cable) 9151-02 GP-IB CONNECTOR CABLE (2 m) 9151-04 GP-IB CONNECTOR CABLE (4 m) |
| Printer-Related | 9670 PRINTER (BL-80RS II, made by SANEI ELECTRIC INC.) 9671 AC ADAPTER (for the 9670, BL-100W, made by SANEI ELECTRIC INC.) 9672 BATTERY PACK (for the 9670) 9673 BATTERY CHARGER (for the 9672) 9237 RECORDING PAPER (80 mm x 25 m, 4 rolls, for the 9670) 9638 RS-232C CABLE (for 3541-9670) |

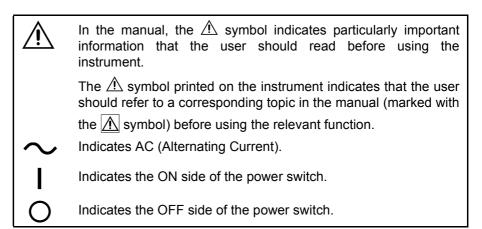
Safety Information



This instrument is designed to comply with IEC 61010 Safety Standards, and has been thoroughly tested for safety prior to shipment. However, mishandling during use could result in injury or death, as well as damage to the instrument. Be certain that you understand the instructions and precautions in the manual before use. We disclaim any responsibility for accidents or injuries not resulting directly from product defects.

This manual contains information and warnings essential for safe operation of the instrument and for maintaining it in safe operating condition. Before using it, be sure to carefully read the following safety precautions.

Safety Symbols



The following symbols in this manual indicate the relative importance of cautions and warnings.

| <u> Awarning</u> | Indicates that incorrect operation presents a significant hazard that could result in serious injury or death to the user. |
|------------------|--|
| <u>ACAUTION</u> | Indicates that incorrect operation presents a possibility of injury to the user or damage to the instrument. |
| NOTE | Indicates advisory items related to performance or correct operation of the instrument. |

Other Symbols

| \bigcirc | Indicates a prohibited action. |
|------------|--|
| * | Indicates the location of reference information. |
| ? | Indicates quick references for operation and remedies for troubleshooting. |
| * | Indicates that descriptive information is provided below. |

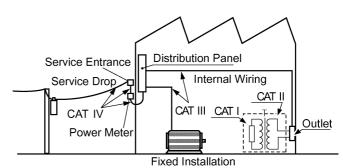
Overvoltage Categories (CAT)

Accuracy

This instrument complies with CAT II (power supply section) safety requirements.

To ensure safe operation of measurement instruments, IEC 60664 establishes safety standards for various electrical environments, categorized as CAT I to CAT IV, and called overvoltage categories. These are defined as follows.

| CAT I | Secondary electrical circuits connected to an AC electrical outlet through a transformer or similar device. |
|---------|--|
| CAT II | Primary electrical circuits in equipment connected to an AC electrical outlet by a power cord (portable tools, household appliances, etc.) |
| CAT III | Primary electrical circuits of heavy equipment (fixed installations) connected directly to the distribution panel, and feeders from the distribution panel to outlets. |
| CAT IV | The circuit from the service drop to the service entrance, and to the power meter and primary overcurrent protection device (distribution panel). |



Higher-numbered categories correspond to electrical environments with greater momentary energy. So a measurement device designed for CAT III environments can endure greater momentary energy than a device designed for CAT II.

Using a measurement instrument in an environment designated with a higher-numbered category than that for which the instrument is rated could result in a severe accident, and must be carefully avoided.

We define measurement tolerances in terms of f.s. (full scale), rdg. (reading) and dgt. (digit) values, with the following meanings:

| f.s. | (maximum display value or scale length) The maximum displayable value or scale length. This is usually the name of the currently selected range. |
|------|--|
| rdg. | (reading, displayed or indicated value) The value currently being measured and indicated on the measuring instrument. |
| dgt. | (resolution) The smallest displayable unit on a digital measuring instrument, i.e., the input value that causes the digital display to show a "1" as the least-significant digit. |

Operating Precautions

Follow these precautions to ensure safe operation and to obtain the full benefits of the various functions.

Before Use

- Before using the instrument the first time, verify that it operates normally to ensure that the no damage occurred during storage or shipping. If you find any damage, contact your dealer or Hioki representative.
- Before using the instrument, make sure that the insulation on the probes and cables is undamaged and that no bare conductors are improperly exposed. Using the instrument in such conditions could cause an electric shock, so contact your dealer or Hioki representative for replacements.

Handling the Instrument



- Do not allow the instrument to get wet, and do not take measurements with wet hands. This may cause an electric shock.
 - Never modify the instrument. Only Hioki service engineers should disassemble or repair the instrument. Failure to observe these precautions may result in fire, electric shock, or injury.
 - Do not use the instrument where it may be exposed to corrosive or combustible gases. The instrument may be damaged or cause an explosion.



To avoid damage to the instrument, protect it from physical shock when transporting and handling. Be especially careful to avoid physical shock from dropping.

Handling the Cords and Probes

- Avoid stepping on or pinching cables, which could damage the cable insulation.
- To avoid breaking the cables and test leads, do not bend or pull them.
- To avoid damaging the power cord, grasp the plug, not the cord, when unplugging it from the power outlet.
- The sensor used in the temperature probe is a thin, precision platinum film. Be aware that excessive voltage pulses or static discharges can destroy the film.
- Avoid subjecting the temperature probe tip to physical shock, and avoid sharp bends in the leads. These may damage the probe or break a wire.
- When measuring high temperatures, do not let the handle of the temperature probe or the compensation lead wire exceed the temperature range.

Use only the specified test leads and cables. Using a non-specified cable may result in incorrect measurements due to poor connection or other reasons.

Instrument Installation and Operating Environment



NOTE

- Do not install the instrument upside-down, or stand it on its side.
- Do not store or use the instrument where it could be exposed to direct sunlight, high temperature or humidity, or condensation. Under such conditions, the instrument may be damaged and insulation may deteriorate so that it no longer meets specifications.
- This instrument is designed for use indoors. It can be operated at temperatures between 0 and 40°C without degrading safety.
- This instrument is not designed to be entirely water- or dust-proof. Do not use it in an especially dusty environment, nor where it might be splashed with liquid. This may cause damage.
- Do not use the instrument near a source of strong electromagnetic radiation, or near a highly electrically charged object. These may cause a malfunction.

NOTE

- Correct measurement may be impossible in the presence of strong magnetic fields, such as near transformers and high-current conductors, or in the presence of strong electromagnetic fields such as near radio transmitters.
- In an electrically noisy environment, noise may impinge upon the measured object, resulting in unstable measurements. The instrument should not be used in such places.

Before Connecting and Powering On



Power and Grounding

- Before turning the instrument on, make sure the supply voltage matches that indicated on the its power connector. Connection to an improper supply voltage may damage the instrument and present an electrical hazard.
- To avoid electrical accidents and to maintain the safety specifications of this instrument, connect the power cord only to a 3-contact (two-conductor + ground) outlet.

Connections

To avoid electric shock or damage to the equipment, always observe the following precautions when connecting to external terminals or connectors.

- Always turn off the power to the instrument and to any devices to be connected before making connections.
- Be careful to avoid exceeding the ratings of external terminals and connectors.
- During operation, a wire becoming dislocated and contacting another conductive object can be serious hazard. Make sure that connections are secure and use screws to secure the external connectors.



To suppress noise, the instrument needs to be set to match the frequency of the power source.

Before operating, set the instrument to the frequency of your commercial power. If the line frequency is not set properly, measurements will be unstable.

2.8 Selecting the Line Frequency (Page 25)

<u> MARNING</u>

Observe the following to avoid electric shock and damage to the

Measurement Precautions

instrument.

- Do not apply voltage to the input terminals (INPUT A and INPUT B). Also, to avoid electrical accidents, only take measurements after turning off the power to the circuit being measured.
- Do not allow voltage of 2 V DC or more to be applied to the TC SENSOR jack.

- Never attempt to measure at a point where voltage is present. In particular, be careful to avoid damaging the instrument from inductor discharge when attempting to measure a transformer or motor immediately after a temperature increase test or withstandvoltage test.
- The input terminals incorporate a circuit protection fuse. Measurement is not possible when the fuse is blown.
- In the 20 mΩ and 200 mΩ ranges, the test object can be loaded with one watt or more. Also, in the 100 kΩ range and above, 10 volts or more may be applied. Therefore, when measuring delicate components, use the Low-Power Resistance Measurement mode.
- Allowable input voltage from an analog thermometer is 0 to 2 V (between terminal contacts). Do not apply voltage exceeding this range.
- Battery internal resistance cannot be measured with this instrument. It will sustain damage. To measure battery internal resistance, we recommend the HIOKI 3550, 3551 and 3555 BATTERY HITESTERs or the 3560 AC m Ω HITESTER.

NOTE

• To ensure certified measurement accuracy, allow at least 60 minutes warm-up. Within the 30- to 60-minute warm-up period, please double specified accuracy values. After warm-up, be sure to execute self-calibration.

5.8 Self-Calibration (Page 66)

- This instrument internally stores (backs up) all settings (except measurement values), such as measurement range, comparator settings and etc., but only when no operation is performed for a certain time. Therefore, to preserve settings, do not turn the power off for a short time (about five seconds) after changing a setting. However, measurement settings made through the RS-23<u>2C or</u> GP-IB interface and measurement settings loaded by LOAD signals of the external I/O terminal are not memorized.
- The direct current that this instrument uses for measuring is affected by thermoelectromotive force, which can cause measurement aberrations. In such cases, use the Offset Voltage Compensation function.
 - 5.7 Offset Voltage Compensation (OVC) (Page 65)
 - Appendix 4 Effect of Thermoelectromotive Force (Page 173)
- When measuring objects with a large inductance (L-content) such as power transformers, the measured value may be unstable. In such cases, contact your dealer or Hioki representative.

Using the Temperature Probe

- Holding the temperature probe in a bare hand can cause enough noise pickup to destabilize measurements.
- Temperature Correction does not work if the temperature probe is allowed to touch the test object. Only the ambient temperature of the immediate locale should be used.
- Before measuring, install the temperature probe and allow at least 60 minutes warm-up before measurement. Unless the test object and temperature probe used for temperature correction measurement have been allowed to completely stabilize at ambient temperature, large measurement errors may occur.
- Unless the temperature probe is inserted all the way into the TC SENSOR jack on the rear panel of the instrument, large measurement errors may occur.

Overview

Chapter 1

1.1 Product Overview

The 3541 employs a four-terminal measurement method that is ideal for measuring the resistance of motor and transformer windings, relay/ switch and connector contacts, PCB patterns, chip inductor DC resistance and for ohmmeter shipping inspection tests. The instrument includes functions for temperature correction, comparator decisions and data output, making it particularly suitable for production and inspection lines, as well as for system applications.

1.2 Features

High Precision, Fine Resolution and Fast Resistance Measurement

The 4-terminal method enables precise, fast measurement of resistances as small as 0.1 $\mu\Omega$.

In addition, resistance measurements can be made as in as little as 0.6 ms.

◆

Offset Voltage Compensation

Removes the effects of thermoelectromotive force on measurements.

Low-Power Measurement Function

Minimizes stress on test objects.

Multipolar Connector

A multipolar connector (INPUT B) shielded from thermoelectromotive force is provided to facilitate fast measurements.



Broad Temperature Correction Support

By connecting a temperature probe, temperature correction of resistance measurements is available for practically any temperature and thermal coefficient. A thermometer with analog output can be used in place of the supplied 9451 TEMPERATURE PROBE.

◆

Temperature Conversion

The temperature increase (Δt) of a test object can be obtained by conversion of its measured resistance.



Statistical Calculation Functions

Maximum value (Max), minimum value (Min), mean value (Average), overall standard deviation (σ), and process capability indices (Cp and Cpk) can be calculated.



Comparator and BIN Functions

The Comparator function provides product pass/fail decisions. And the BIN function provides classification into up to ten categories.



Save and Load up to 30 Sets of Measurement Setting States

Store up to 30 sets of measurement settings such as comparator tables, measurement ranges and sampling rates for later recall.



External I/O

Various trigger inputs and comparator, BIN and BCD outputs are provided to support production line applications.



Equipped with GP-IB and RS-232C Standard Interfaces

Full remote control is available through the GP-IB and RS-232C interfaces.

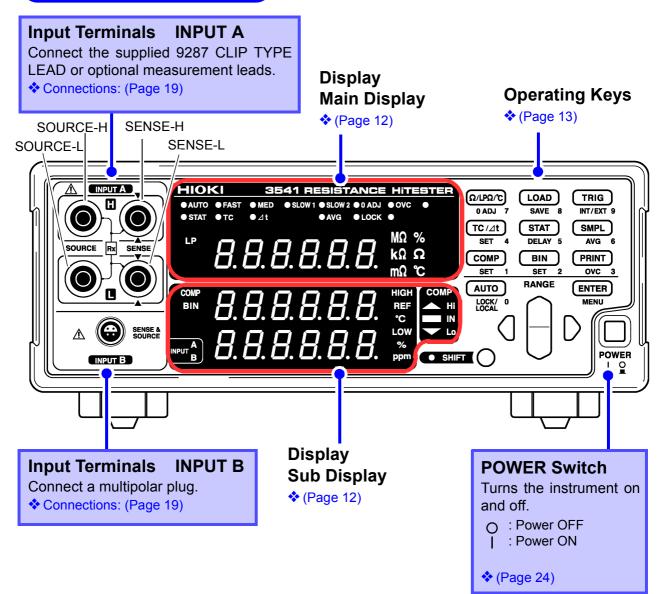


Prints Measurement Values and Calculation Results (Printer Optional)

Connect the optional HIOKI 9670 PRINTER to print out measurement values and statistical calculation results.

1.3 Names and Functions of Parts

Front Panel



Main Display

Displays the current measurement function, measured value (while measuring) or setting item (while setting).

| (while sett | ing). | | |
|--|---|--------------------------|---|
| (Upper row) (Lower row) | | | () |
| Αυτο | Lit when measuring with Auto-Ranging. | STAT | Lit when the Statistical Calculation |
| FAST, ME | D, SLOW1, SLOW2 | тс | function is enabled. Lit when the Temperature Correction |
| | The selected sampling rate is lit. | | function is enabled. |
| 0 ADJ | Lit when measuring in a range for which zero-adjustment has been performed. | Δ t | Lit when the Temperature Conversion function is enabled. |
| ovc | Lit when measuring with the Offset Voltage Compensation function | AVG | Lit when measuring with the Averaging setting enabled. |
| | enabled. | LOCK | Lit when the keys are locked. |
| EXITRIG | Lit when the manual trigger mode is enabled. | REMOTE | Lit during communications. |
| LP Indicates I measurem mode. Shows me value or se item. | Low-Power hent easured | SLOW 1 O SLOW 2 O AVG | ANCE HITESTER $e \oplus adj \oplus ovc \oplus EXT TRIG \oplus Lock \oplus REMOTE$ $hlock \oplus REMOTE \oplus Units of displayed measurement$ |
| Sub Dis | play | | |
| COMP While mea indicates th function is BIN While mea indicates th function is INPUT Indicates th | BIN | . 8. 8. . 8. 8. | |
| HIGH / LO | DW Indicates that absolute value compa operation is enabled (while measuring also when setting. | | i Indicates that the measured value is above the upper threshold. |
| REF / % | Indicates that relative value compar operation is enabled (while measurin also when setting. | | |
| °C / ppm | Indicates that the temperature corre | ction or | |

compensation value is displayed (while

measuring), and also when setting.

Indicates that the measured value Lo is below the lower threshold.

| Operatin | g Keys | | | |
|---|--|-----------------|--|--|
| To use a function marked on a key, just press the key. To use a function printed under a key (blue letter), press the SHIFT key first (and confirm the SHIFT lamp is lit), and then the key. SHIFT Lamp SHIFT Lamp SHIFT Lamp | | | | |
| Operating Ke | Ifter pressing the SHIFT key (SHIFT lar Description | Operating Ke | Description | |
| Ω/LPΩ/°C | Select the measurement function (4- terminal resistance, low-power 4- terminal resistance or temperature | PRINT | ey Description Sends measurement values and statistical calculation results to the printer. | |
| [0 ADJ] | measurement). Executes zero-adjustment. | [OVC] |] Switches the Offset Voltage Compensation function on and off. | |
| LOAD | Loads saved settings. | AUTO | Switches between automatic and manual range selection. | |
| [SAVE] | Saves settings. | [LOCAL/ | LOCAL: Reverts from the | |
| | Use for manual triggering. | LOCK] | communications state. LOCK: Switches the Key-Lock | |
| [INT/EXT] TC/∆t | Selects internal/external triggering. Switches Temperature Correction or | | function on and off. | |
| ΤΟ/Δι | Temperature Conversion on and off. | ENTER | Applies settings. Selects various items. | |
| [SET] | Sets parameters for Temperature Correction or Temperature Conversion. | [MENU] | (Selects temperature correction/ conversion, calibration on/off, key- click on/off, interface, line frequency | |
| STAT | Displays and sets statistical calculation results. | | and setting/system reset) | |
| [DELAY] | Sets the trigger delay. | RANGE | Up/Down:Changes setting value or numerical value, and range | |
| SMPL | Selects the sampling rate. | | selection. | |
| [AVG] | Activates Averaging function settings. | | Left/Right: Moves the setting item or digit. | |
| СОМР | Switches the Comparator function on and off. | SHIFT | Enables the functions of the operating keys marked in blue. The lamp is lit when the SHIFT | |
| [SET] | Activates Comparator function setting. | | state is active.Cancels settings in various setting | |
| BIN | Switches the BIN function on and off. | | displays. (Returns to the Measurement display without | |
| [SET] | Activates BIN function setting. | | applying settings.) However, this does not apply to Menu display. | |
| | | | | |

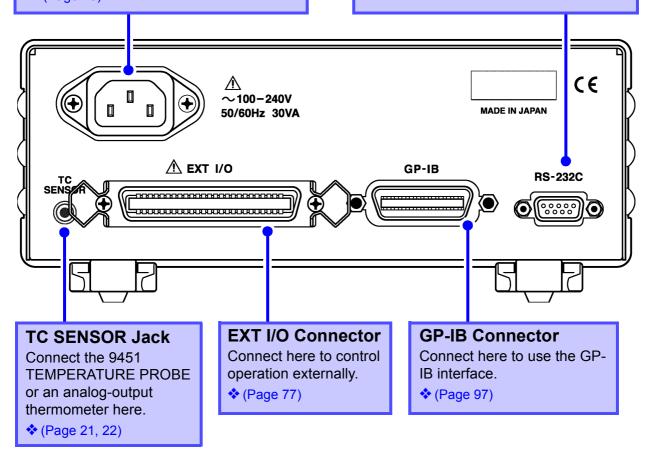
Rear Panel

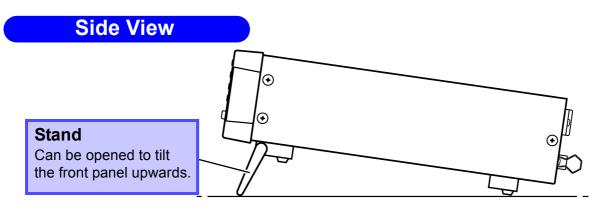
Power Inlet

RS-232C Connector

Connection for the printer or RS-232C interface.

Printer (Page 88), RS-232C (Page 97), Temperature HiTester (Page 23)





<u>ACAUTION</u>

Do not apply heavy downward pressure with the stand extended. The stand could be damaged.

SHIFT (SHIFT Lamp lit) The Menu display appears. ENTER MENU (Main Display) The up/down RANGE key changes the setting shown on the Sub Display. Rdu F RL ļ Ь Zero-Adjust Clear Temperature Interface Self-Calibration Setting Display Correction/Conversion Selection Display Setting Display Selection Display (Page 41) (Page 99) (Page 66) (Page 58) <u>Err.</u>oU nPU \mathbf{O} Οί Measurement Terminal **BIN/BNC Output** Measurement Fault Output Selection Display **Timing Setting Display** Selection Display (Page 26) (Page 82) (Page 82) EqKey Beeper Line Frequency Reset Display Setting Display Setting Display (Page 73) (Page 67) (Page 25) NOTE Adjustment Display Press twice The Adjust Display is intended for use only by a service technician. Accuracy cannot be guaranteed if the user makes adjustments with this display. Press to return to previous display.

Menu Display Sequence

NOTE

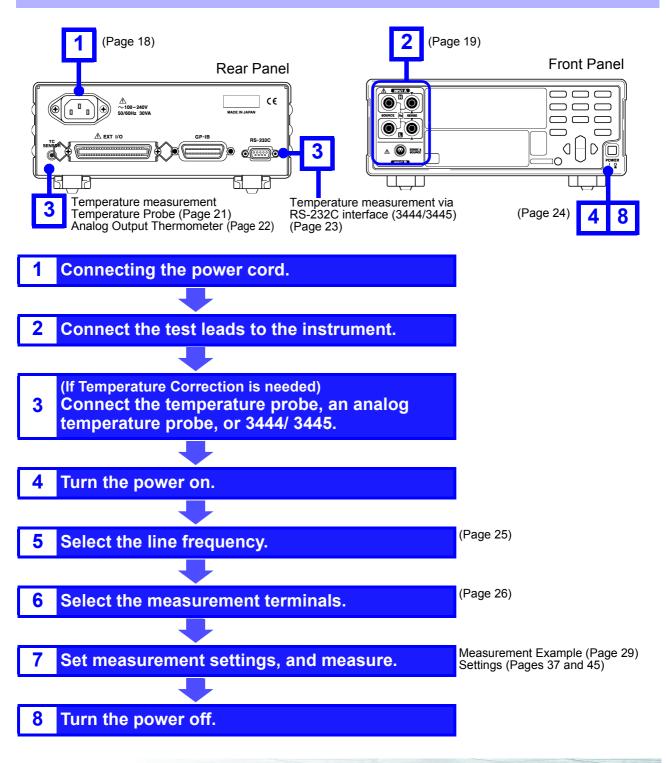
Settings made from the Menu Display are saved internally when you press ENTER or SHIFT to return to the Measurement Display.

1.3 Names and Functions of Parts

Measurement Preparations

Chapter 2

2.1 Procedure



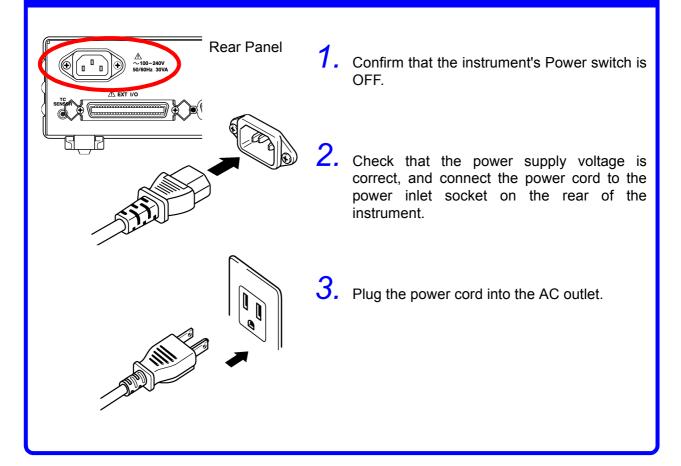
2.2 Connecting the Power Cord



- Before turning the instrument on, make sure the supply voltage matches that indicated on the its power connector. Connection to an improper supply voltage may damage the instrument and present an electrical hazard.
- To avoid electrical accidents and to maintain the safety specifications of this instrument, connect the power cord only to a 3-contact (two-conductor + ground) outlet.

To avoid damaging the power cord, grasp the plug, not the cord, when unplugging it from the power outlet.

Connecting the Power Cord



2.3 Connecting the Test Leads

This instrument is equipped with an input with four separate bananajack terminals (INPUT A) and another input with a multipolar socket (INPUT B).

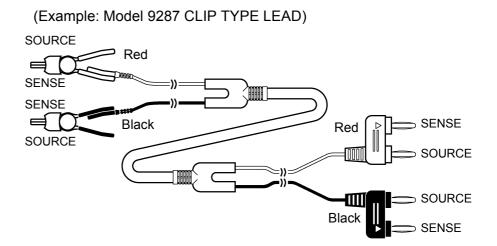
The supplied Model 9287 CLIP TYPE LEAD and Hioki's various optional measurement leads connect to the INPUT A terminals.

Appendix 6 Test Lead Options (page 176)

For high-resistance and low-power measurements, the high noise immunity of INPUT B offers advantages for high speed measurements.

2.9 Selecting the Measurement Terminals (page 26)

About Test Leads



| @ | | | |
|-----------------------|--|--|--|
| Rubber Replacement | The 9287 CLIP TYPE LEAD is available as a service part (Rubber for 9099). Please contact your supplier or Hioki representative. When replacing the rubber, lubricate the inside by moistening with water before inserting the clip. | | |
| Making your own cable | The cable of our test leads is shielded. When making your own cable, please bear in mind the following. SOURCE SENSE SOURCE SOURCE SOURCE SOURCE SOURCE SOURCE SOURCE | | |
| | SENSE SENSE Shield | | |
| | Connect the shield to the SOURCE-L lead. | | |
| | Cable length must not exceed 5 m. (Conductor resistance should be | | |

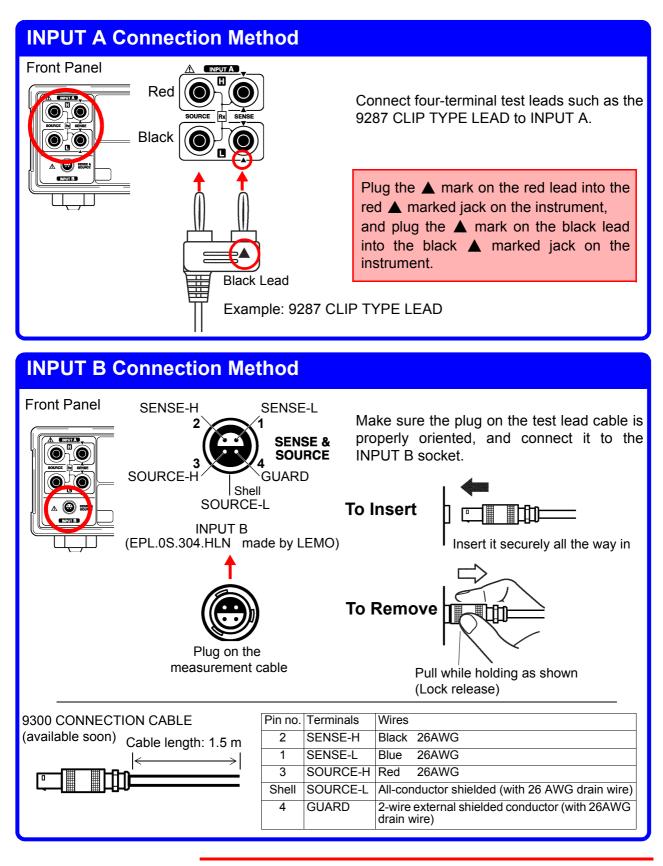
Cable length must not exceed 5 m. (Conductor resistance should be no more than 100 m Ω /m)

However, for the 20 m Ω and 200 m Ω ranges, resistance should be no more than 300 m Ω per circuit.



Connecting to the terminals _

CAUTION



The cable connector (for INPUT B) is a locking type. Always grasp the plug when removing the cable. Pulling on the cable will damage the connector.

2.4 Connecting the Temperature Probe

<u> MARNING</u>

<u> ACAUTION</u>

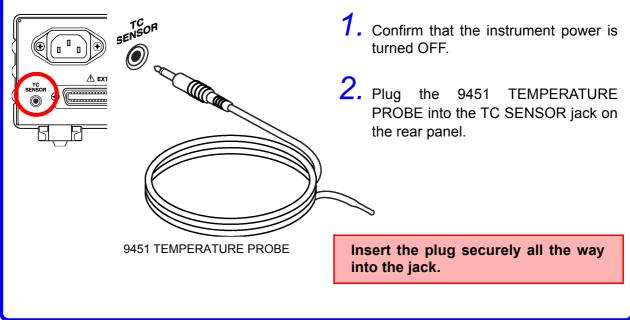
Do not apply voltage to the TC SENSOR jack, to avoid electric shock accidents or damage to the instrument.

To avoid damage to the instrument or temperature probe, observe the following precautions:

- Turn the instrument off before plugging or unplugging the temperature probe.
- The temperature probe is not waterproof. Do not submerse it in water or other liquid.

9451 TEMPERATURE PROBE Connection

Rear Panel



2.5 Connecting an Analog Output Thermometer

To measure temperature, connect the analog output thermometer to the instrument.

The connection requires a standard 3.5-mm monaural mini-phone plug.

The following TEMPERATURE HITESTERs are available from Hioki:

- The Model 3444 TEMPERATURE HITESTER (for long-focus, narrow-visual-field measurements) + 3909 INTERFACE PACK
- The Model 3445 TEMPERATURE HITESTER (for short-focus, microscopic surface measurements) + 3909 INTERFACE PACK



Note that thermometer circuit is grounded. To avoid electric shock accidents or damage to the instrument, do not connect an analog output thermometer to the TC SENSOR jack that has any potential offset from ground.

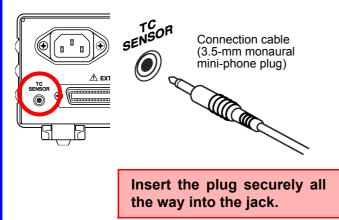


Note the following precautions to avoid damaging the instrument:

- Before connecting a thermometer to the instrument, confirm that any power to the instrument and thermometer is turned OFF.
- Allowable input voltage from an analog thermometer is 0 to 2 V (between terminal contacts). Do not apply voltage exceeding this range.
- With thermometers providing 4 to 20 mA output, connect a shunt resistance of about 100 Ω before connecting, and convert the resulting voltage.

Analog Output Thermometer Connection Method

Rear Panel



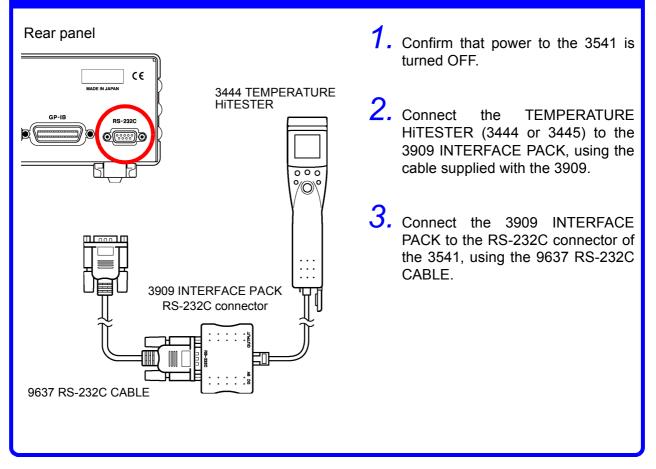
- Confirm that the instrument power is turned OFF.
- 2. Connect the thermometer's analog output connector to the TC SENSOR jack on the rear panel, using a generic connection cable (3.5-mm monaural mini-phone plug).

2.6 Connecting the Temperature HiTester via RS-232C

Using the RS-232C interface, you can connect the HIOKI 3444/ 3445 TEMPERATURE HITESTERs to the unit for temperature measurement. The connection requires the 9637 RS-232C CABLE (option).

- The Model 3444 TEMPERATURE HITESTER (for long-focus, narrow-visual-field measurements) + 3909 INTERFACE PACK
- The Model 3445 TEMPERATURE HITESTER (for short-focus, microscopic surface measurements) + 3909 INTERFACE PACK

Connection Method



2.7 Turning the Power On and Off

Turning the Power On



Power ON

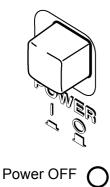
Turn the POWER switch ON (|).

After Power-On

- The model name, software version, line frequency selection and interface selection appear before the measurement state is displayed.
- The measurement setting state is the same as when the power was previously turned off (backup).
- To preserve changes to settings, wait a short time (about five seconds) after changing a setting before turning power off. However, measurement settings made through the <u>RS-23</u>2C or GP-IB interface and measurement settings loaded by LOAD signals of the external I/O terminal are not memorized.
- Before starting to measure, allow 60 minutes for warm-up.
 Within the 30- to 60-minute warm-up period, please note that specified accuracy values are double.
 After warm-up, be sure to perform a self-calibration.

5.8 Self-Calibration (page 66)

Turning the Power Off

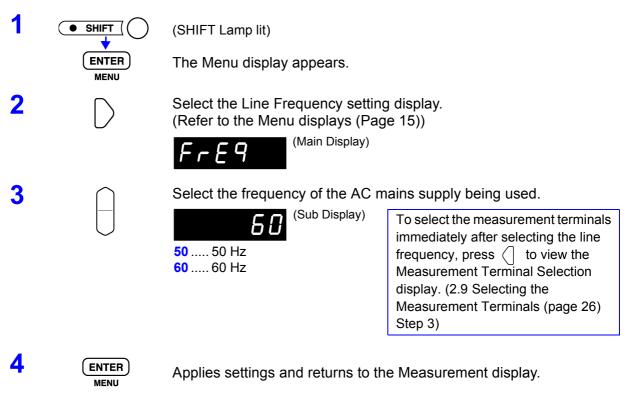


Turn the POWER switch $OFF(\bigcirc)$.

24

2.8 Selecting the Line Frequency

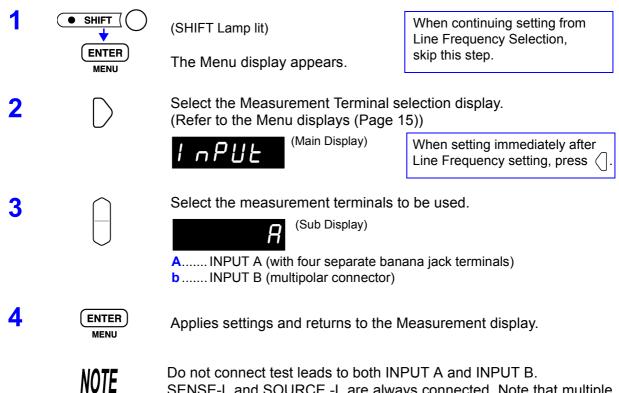
NOTE



To suppress noise, the instrument needs to be set to match the frequency of the AC power source.

Before operating, set the instrument to the frequency of your commercial mains power. If the line frequency is not set properly, measurements will be unstable.

2.9 **Selecting the Measurement Terminals**



Do not connect test leads to both INPUT A and INPUT B. SENSE-L and SOURCE -L are always connected. Note that multiple measurements cannot be performed simultaneously.

About Input Terminal Usage_

The factory-default input terminal selection is INPUT A, the four (banana jack) terminals, enabling use of Hioki's various test-lead options.

INPUT A A 10 nF capacitor is connected between the H-L terminals of INPUT A. This capacitance is intended to improve the stability of high-resistance measurements and measurements of inductive loads. However, this also slows the response time for high-resistance measurements.

The approximate response time required to display about 95% of the resistance of a test object is:

Response time [s] = 3 x Resistance [Ω] x 10 x 10⁻⁹ [F]

Even with the 10 nF capacitor, stability cannot be assured with all inductive loads. Inductance of 10 H or more may cause instability. In such cases, connect a 0.1- μ F or larger capacitor between H and L, or contact your supplier or Hioki representative for other solutions.

For fast response with high-resistance measurements, use INPUT B (the multipolar connector), which has no 10-nF capacitor. However, because INPUT B has no (10 nF) capacitor, measurements may be unstable with some inductive test objects.

INPUT B INPUT B offers the advantages of being less affected by thermoelectromotive force than the four separate terminals of INPUT A, and is more suitable for high-speed measurements due to the shielding. When you need to take measurements faster than once per PLC (power line cycle) without OVC (Offset Voltage Compensation), use INPUT B.

2.9 Selecting the Measurement Terminals

Chapter 3

Measurement

Before starting measurement, please read Safety Information (Page 2) and Chapter 2 Measurement Preparations (Page 17).

3.1 Resistance Measurement

The following example describes the resistance measurement process.

Example: Measuring a 10 m Ω shunt resistance

| Required items: | 10 m Ω shunt resistance 9287 CLIP TYPE LEAD | |
|-------------------------|---|--------------------|
| Measurement conditions: | Sampling Zero adjust Offset Voltage Compensation Range | Enabled Enabled |

Preparations

1

2

Connect the 9287 CLIP TYPE LEAD to the instrument, and turn it on.
 2.3 Connecting the Test Leads (Page 19)

Select the appropriate line frequency and measurement terminals.

- 2.8 Selecting the Line Frequency (Page 25)
- 2.9 Selecting the Measurement Terminals (Page 26)

Instrument Settings

Before setting, confirm that the SHIFT lamp is not lit.

Select the Resistance Measurement function.

4.1 Selecting Measurement Functions (Page 37)

Ω/LPΩ/℃ 0 ADJ 7



(Main Display)

The Resistance Measurement display appears. (Ω unit indicator lit, LP off)



(Main Display) The position of the decimal and the unit indicator change with each key-press. (m Ω lit, AUTO off)

3.1 Resistance Measurement



5.5 Temperature Conversion Function (Δt) (Page 60)

Measurement

Connect the 9287 CLIP TYPE LEAD to the shunt resistance, and read the value.





- In the 20 m Ω and 200 m Ω ranges, the sample can consume one watt or more. Also, in the 100 k Ω range and above, up to 10 volts may be applied. Therefore, when measuring delicate components, use the Low-Power Resistance Measurement mode.
- In the following cases, the measured value may be displayed with a "-" sign.
 - If SOURCE and SENSE leads are reversed.
 - If zero-adjust is performed by two-terminal measurement, and contact resistance later decreases.
 - If the thermoelectromotive force changes, or the offset voltage of the instrument changes.

3.2 Temperature Measurement (Temperature Correction & Conversion)

| Temperature | Using the temperature at time of measurement, temperature |
|-------------|--|
| Correction | correction is applied to convert the measured resistance value to the |
| | value it would have at a specified reference temperature. |
| | 5.4 Temperature Correction Function (TC) (Page 58) |
| Temperature | Temperature increase is derived by the temperature conversion |
| Conversion | principle. |
| | ◆ 5.5 Temperature Conversion Function (∆t) (Page 60) |

Appendix 3 Temperature Conversion Function (∆t) (Page 172)

Temperature Measurement with the 9451 TEMPERATURE PROBE

Preparations

2

1 Connect the test leads and the 9451 TEMPERATURE PROBE to the instrument, and turn it on.

- 2.3 Connecting the Test Leads (Page 19),
 2.4 Connecting the Temperature Probe (Page 21)
- Select the appropriate line frequency and measurement terminals.
 - 2.8 Selecting the Line Frequency (Page 25),
 2.9 Selecting the Measurement Terminals (Page 26)

Instrument Settings

Before setting, confirm that the SHIFT lamp is not lit.

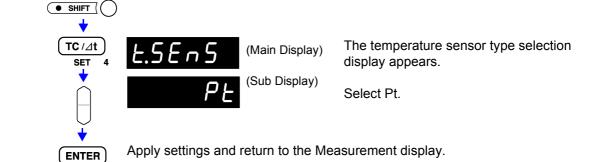
- **1** Select the Temperature Measurement function.
 - 4.1 Selecting Measurement Functions (Page 37)

Ω/LPΩ/℃ 0 ADJ 7

MENH

(Main Display) The Temperature Measurement display appears. (°C unit indicator lit) The current temperature appears.

2 Select Pt for the temperature sensor type.



3.2 Temperature Measurement (Temperature Correction & Conversion)

Temperature Measurement Place the 9451 TEMPERATURE PROBE near the point to measure, and read the temperature. (Main Display) Read the current temperature. <u>26.</u>6 **Temperature Correction & Conversion Settings**

Select resistance or low power measurement, and select temperature correction or conversion.

For temperature correction: 5.4 Temperature Correction Function (TC) (Page 58)

For temperature conversion: 5.5 Temperature Conversion Function (Δt) (Page 60)

Measurement

Connect the test leads to the sample, and measure.



With temperature correction: The corrected resistance value at the specified reference temperature is displayed.

With temperature conversion: The temperature increase Δt relative to ambient temperature is displayed.

About the temperature probe



- If the temperature probe is held in the bare hand, body temperature will interfere with temperature measurement.
 - The temperature probe is not waterproof.Do not submerse it in water or other liquid.
 - · If the temperature probe is not inserted all the way into the TC SENSOR jack on the rear panel, large measurement errors may occur.

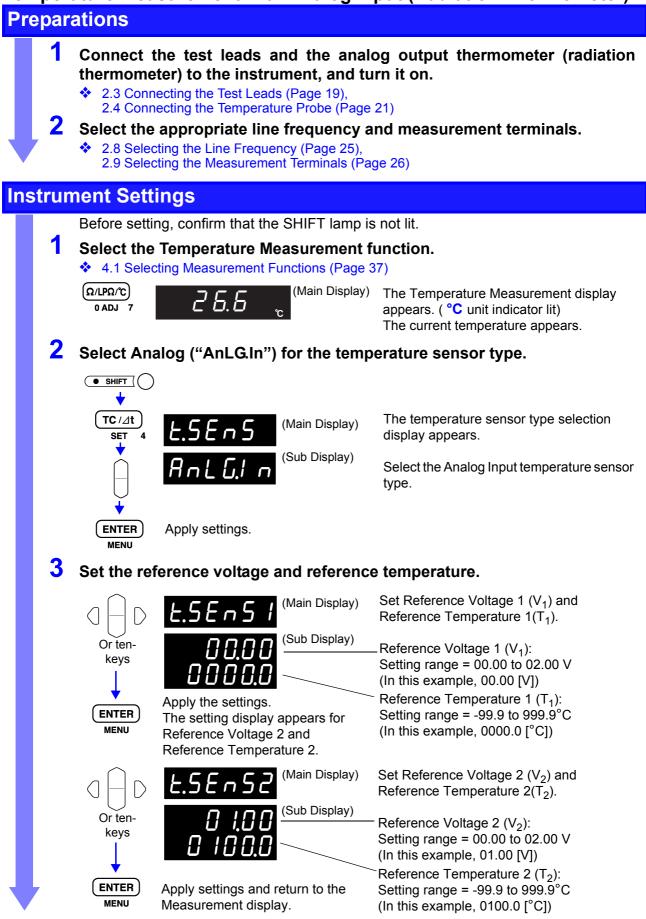


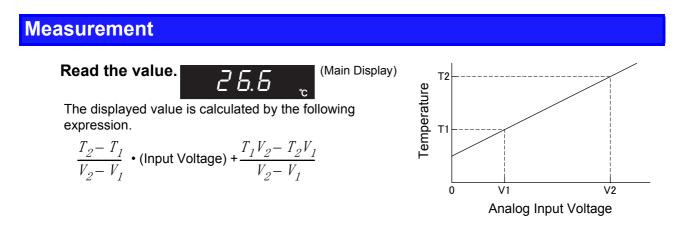
If the OF indicator measurement

Check whether the temperature probe is connected properly. **appears with temperature** If it is not, temperature cannot be measured.

If the tC SnS error indicator appears with resistance measurement Check whether the temperature probe is connected properly. If it is not, the TC/ Δ t function is not usable.

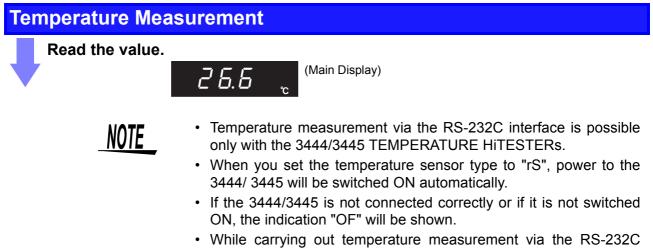
Temperature Measurement with Analog Input (Radiation Thermometer)





Temperature measurement via RS-232C interface (using the 3444/3445 TEMPERATURE HITESTER+ 3909 INTERFACE PACK)

| Prepar | ations | |
|---------|---|--|
| 1 | Connect the test leads and the 3444/ 34 instrument, and turn it on. 2.3 Connecting the Test Leads (Page 19), 2.6 Connecting the Temperature HiTester via R | |
| 2 | Select the appropriate line frequency at 2.8 Selecting the Line Frequency (Page 25), 2.9 Selecting the Measurement Terminals (Page 25) | |
| Instrun | nent Settings | |
| 1 | Before setting, confirm that the SHIFT lamp is Select the Temperature Measurement f 4.1 Selecting Measurement Functions (Page 3) | unction. |
| | | The Temperature Measurement display appears. (°C unit indicator lit) The current temperature appears. |
| 2 | Select rS for the temperature sensor ty | /pe. |
| | | . |
| | (Main Display) | The temperature sensor type selection display appears. |
| | (Sub Display) | Select rS. The 3444/ 3445 will be switched ON automatically. |
| | ENTER Apply settings and return to the Me MENU | asurement display. |



While carrying out temperature measurement via the RS-232C interface, the RS-232C/GP-IB communication and printing functions are not available.

Basic Function Settings

Chapter 4

4.1 Selecting Measurement Functions

Settings Select the Resistance, Low-Power Resistance or Temperature measurement function.

Switching the Measurement Function

Confirm the SHIFT lamp is not lit. Switches the displayed measurement function. Ω/LPΩ/°C Each key-press switches the measurement function. 0 ADJ 7 (Main Display) Resistance Measurement display (Ω unit indicator lit, LP indicator 9.9258 off) Low-Power Resistance LP Measurement display 992.58 (Ω unit indicator lit, LP indicator lit) **Temperature Measurement** 26.6 display (°C unit indicator lit) ĉ



1

2

If the OF indicator appears with temperature measurement. If the temperature sensor is set to Pt: 3.2 Temperature Measurement (Temperature Correction & Conversion) (Page 31)
 Check whether the temperature probe is connected properly.
 If it is not, temperature cannot be measured.

4.2 Measurement Range Setting

Settings

Select the measurement range. Auto-ranging (the AUTO range) can also be selected.

Manual Range Setting

| Select the range to use. (AUTO off) | |
|--|------|
| The decimal point location and unit indicator change with each | key- |
| press. | |

Auto-Ranging

AUTO

Press this while a manual range is selected. (**AUTO** lights) The optimum measurement range is automatically selected.



Switching from Autoranging back to Manual range selection Press the **AUTO** key again. The range can now be changed manually.



- Temperature measurement has only one range. The range cannot be changed.
- Depending on the state of the sample, auto-ranging may be unstable. In this case, select the range manually, or increase the Delay time.

5.11.2 Trigger Delay (Page 69)

- In the low resistance ranges (200 Ω and below) a relatively high load is placed on the sample. In the 20 m Ω and 200 m Ω ranges, up to about one watt may be applied. Therefore, confirm the measurement range before connecting to delicate samples.
- When measuring delicate samples, use the Low Power measurement mode.
- Refer to 9.2 Accuracy; Resistance Measurement Function (Page 164), Low Power Resistance Measurement Function (Page 165) for information on range accuracy.

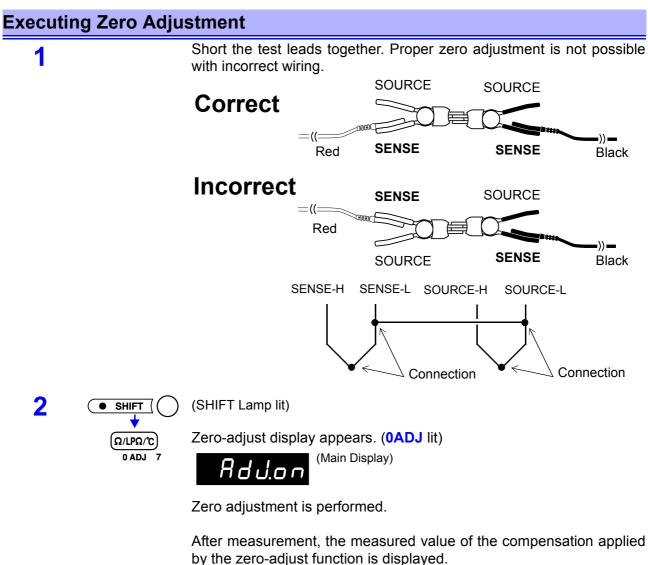
| Range | Displayed Values | | Resistance Measurement Function | | Low Power Resistance Measurement Function | |
|-------------------------|--------------------|------------------------|------------------------------------|------------------------|--|----------|
| Trange Displayed values | | Measurement Current | Open-Terminal Voltage | Measurement Current | Open-Terminal Voltage* | |
| 20mΩ | 20.0000 to -0.2000 | mΩ | 1 A ±5% | 5 Vmax | | |
| $200 \text{m}\Omega$ | 200.000 to -2.000 | mΩ | 1 A ±5% | 5 Vmax | | |
| 2 Ω | 2000.00 to -20.00 | mΩ | 100 mA ±5% | 2.6 Vmax | 10 mA ±5% | 60 mVmax |
| 20Ω | 20.0000 to -0.2000 | Ω | 10 mA ±5% | 2.6 Vmax | 1 mA ±5% | 60 mVmax |
| 200Ω | 200.000 to -2.000 | Ω | 10 mA ±5% | 2.6 Vmax | 100 μA ±5% | 60 mVmax |
| 2kΩ | 2000.00 to -20.00 | Ω | 1 mA ±5% | 2.6 Vmax | 10 μA ±5% | 60 mVmax |
| 20k Ω | 20.0000 to -0.2000 | kΩ | 100 μA ±5% | 2.6 Vmax | | |
| 100k Ω | 110.000 to -2.000 | kΩ | 100 μA ±5% | 13 Vmax | | |
| 1MΩ | 1100.00 to -20.00 | kΩ | 10 μA ±5% | 13 Vmax | | · |
| 10MΩ | 11.0000 to -0.2000 | MΩ | 1 μA ±5% | 13 Vmax | | |
| 100MΩ | 110.000 to -2.000 | MΩ | 100 nA ±5% | 13 Vmax | | |

* When using external triggering, open-terminal voltage is limited to 20 mV maximum from when INDEX goes High until the next trigger input.

4.3 Zero-Adjust Function

Settings

To nullify the instrument's offset voltage and effects of thermoelectromotive force, perform zero adjustment before measuring. Specified measurement accuracy applies only after zero adjustment has been performed.



The range of zero adjustment is up to 1,000 dgt.

NOTE

- Zero adjustment should be executed in each range to be used. When auto-ranging is selected, zero adjustment is executed in all ranges.
- When zero adjustment is executed with auto-ranging, correct zero adjustment may not be possible if the Delay time is too short. In this case, execute zero adjustment manually, or lengthen the Delay time.
 - 5.11.2 Trigger Delay (Page 69)
- Zero adjustment values are retained internally even when the instrument is turned off.
- Zero adjustment can be performed even when the 0ADJ pin of the EXT I/O connector is shorted to ground.
- Always perform zero adjustment after switching the Offset Voltage Compensation (OVC) function ON or OFF.

The zero adjust function is canceled, so repeat the operation after

Clearing Zero Adjustment (SHIFT Lamp lit) 1 • SHIFT The Menu display appears. ENTER (Main Display) MENU (Sub Display) flashing The zero-adjust value is cleared.(0ADJ off) 2 ENTER (Main Display) MENU If OF is displayed Appears when the value is outside of the following range. The measurement value minus the zero-adjust value must be greater or equal to -2000 dgt and less than or equal to +200000dgt (20 m Ω to 20 k Ω), +110000dgt (100 k Ω to 100 M Ω) The measurement value when attempting zero adjustment was more If Err02 is displayed than 1000 dgt, or a measurement fault condition exists.

correcting the cause of the error.

4.4 Sampling Rate Setting

Settings

The sampling rate can be selected from FAST, MEDIUM, SLOW1 and SLOW2. Slower sampling rates generally provide greater measurement precision.

Selecting the Sampling Rate



The sampling rate changes as follows with each key-press.

| HIO | <i< th=""><th>35</th><th>41 RESIST</th><th>ANCE</th><th>HITESTER</th></i<> | 35 | 41 RESIST | ANCE | HITESTER |
|--------|--|-------|-------------------|--------|----------|
| ● AUTO | ● FAST | • MED | ● SLOW 1 ● SLOW 2 | 0 ADJ | |
| ● STAT | ●тс | ●⊿t | ● AVG | • LOCK | ● REMOTE |
| FAS | r → | MED | → SLOW1 | - | SLOW2 |

NOTE

- When AUTO self-calibration is enabled and FAST or MED sampling is selected, self-calibration is performed for about 55 ms once every 30 minutes.
 - ✤ 5.8 Self-Calibration (Page 66)
- With FAST sampling selected, measurements can be easily affected by the external environment, so countermeasures such as shielding of the sample and test leads are recommended. Shields should be connected to the SOURCE-L side.

4.5 Measurement Fault Detection Function

If a measurement does not execute properly, a measurement fault is indicated on the display.

In addition, a measurement fault signal (ERR) is output at the EXT I/O connector.

Chapter 6 External Control (Page 77)

A measurement fault is displayed in the following cases.

- When the resistance of the measured object is over-range Example: Attempting to measure 20 Ω with the 20 m Ω range selected.
- If any of the following is open, or has a bad connection: SOURCE H, SOURCE L, SENSE H, SENSE L
- If the circuit protection fuse is blown
 10.1 Inspection, Repair and Cleaning (Page 167)
- · If the temperature probe is connected incorrectly

| | Error Display Cause | | |
|---|---------------------|---------------------------|--|
| 1 | ErrCur | Constant-current fault | |
| 2 | ErrHi | SENSE-H line is open | |
| 3 | ErrLo | SENSE-L line is open | |
| 4 | | Any combination of 1 to 3 | |



The following cases are detected as measurement faults. However, if the capacitance of the test leads is 1 nF or higher, the measurement fault may not be detected.

- When the resistance between SOURCE-H and SENSE-H is greater than about 50 Ω
- When the resistance between SOURCE-L and SENSE-L has the following values: Low Power function and 20 mΩ to 20 Ω range: about 5 Ω 200 Ω or higher range: about 40 Ω
- After the probes contact the test object, at least about 500 μ s is required for measurement stabilization. This instrument's measurement fault detection function begins detecting measurement faults about 500 μ s before INDEX goes Low (OFF).

Therefore, if the Delay is set to 0.000 s, measurement faults that may occur before INDEX goes Low cannot be detected. To ensure reliable measurement, we suggest setting the Delay to at least 1 ms.

4.6 Overflow Display

Overflow ("OF" or "-OF") is displayed when any of the following conditions are present.

| Display | Condition |
|---------|---|
| OF | When the measured value before temperature correction exceeds the current measurement range. When the result of temperature correction calculation or ∆t exceeds 999,999 dgt. When the result of relative value calculation is larger than +99.999%. When the temperature sensor (with the Pt setting selected) is open-circuit. |
| -OF | When the measurement value before temperature correction is smaller than -2000 dgt. When the result temperature correction calculation or ∆t exceeds -99,999 dgt. When the result of relative value calculation is smaller than -99.999%. |

Applied Function Settings Chapter 5

5.1 Comparator Measurement Function

Function Description

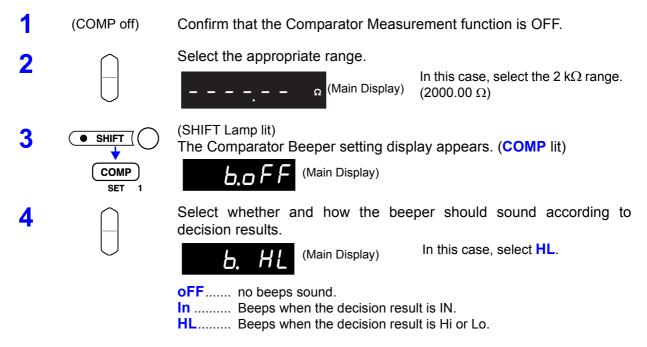
The comparator function compares measured values to preset upper and lower thresholds, judges the measurements according to their relative levels within the preset range, and indicates the results of the comparisons.

Comparator results can be indicated by the Hi, IN and Lo LEDs, beeper sound and signal output at the EXT I/O connector.

For details about comparator signal outputs at the EXT I/O connector, refer to Chapter 6 External Control (Page 77).

Setting upper and lower thresholds to judge measured values (Comparator Measurement Function)

Example:Within the 2 k Ω range, set the upper threshold to 1 k Ω and the lower threshold to 800 Ω , and judge whether measured values exceed the upper or lower threshold.



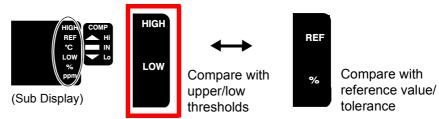
5.1 Comparator Measurement Function



6

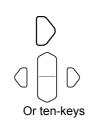
Switches to selection of the comparison method for the comparator.

Select the comparison method for the comparator. Each key-press changes the displayed selection.

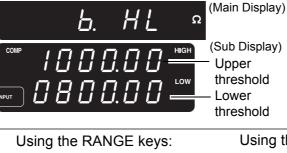


In this case, select HIGH/LOW.

Switches the display to upper/lower threshold setting.



Set the upper and lower thresholds.



In this case, set the upper threshold to 1000 Ω and the lower threshold to 800 Ω .

| Using the RANGE keys: | Using the ten-keys: | |
|--|---|--|
| Select a digit to change by moving the blinking location, then select the new numerical value. | Press the numeric keys corresponding to the digits to be entered. | |
| Select a digit | Ω/LPΩ/C LOAD TRIG 0 ADJ 7 SAVE 8 INT/EXT 9 (TC /⊿t) (STAT) (SMPL) | |

Select numerical value

| | De ente | ieu. | | |
|-------|--|-----------------|-------------------|--|
| | Ω/LPΩ/℃ 0 ADJ 7 | LOAD SAVE 8 | TRIG INT/EXT 9 | |
| | $\underbrace{ \begin{array}{c} \textbf{TC} / \varDelta t \\ \textbf{SET} \textbf{4} \end{array} }_{\textbf{SET} \textbf{4}}$ | STAT DELAY 5 | SMPL AVG 6 | |
| value | COMP SET 1 | BIN SET 2 | PRINT ovc 3 | |
| | AUTO LOCK/ 0 LOCAL 0 | | | |

7

Applies setting and returns to the Measurement display. The comparator function is enabled.

To cancel the settings: • SHIFT

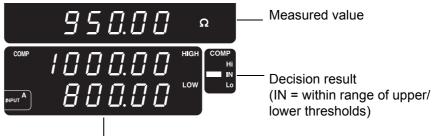


8

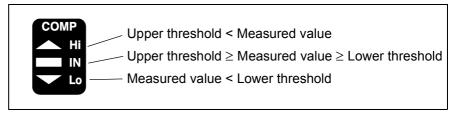
COMP

Connect to a test object, and judge the measured value.

The measured value appears on the Main Display, and the decision result is indicated in the decision result section of the Sub Display.



Preset upper and lower thresholds





Upper and lower thresholds are stored as the actual entered digits, independent of measurement function and range.

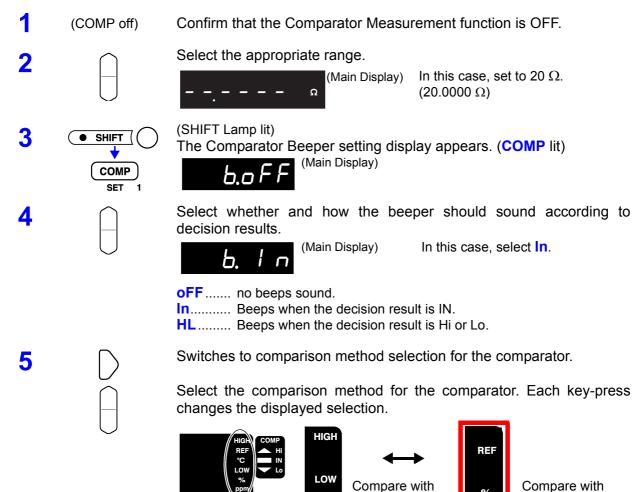
When the measurement function or range is changed, the absolute value represented by the entered digits changes accordingly.

Example: To set the lower threshold to 3.8 Ω in the 20 Ω range, enter 038000. If you now switch to the 200 Ω range, the lower threshold becomes 38 Ω .

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Judging measured values by setting a reference value and tolerance (Comparator Measurement Function)

Example: In the 20 Ω range, set a reference value of 15 Ω with 5% tolerance, so that when a measured value is judged to be within the specified tolerance, the beeper sounds.



(Sub Display)

%

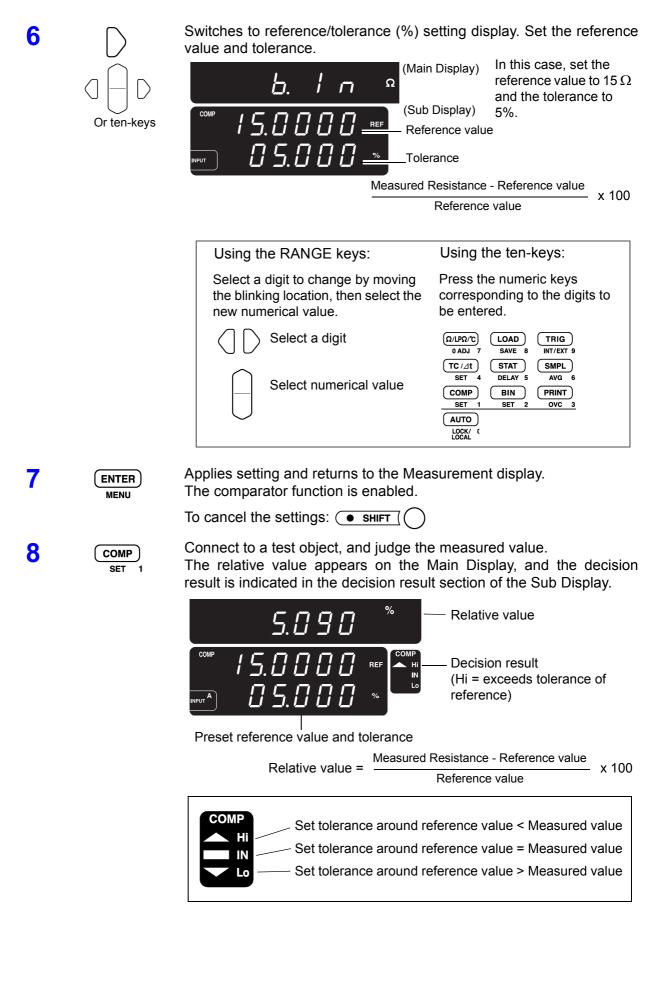
In this case, select REF/%.

reference value/

tolerance

upper/low

thresholds



Executing Comparator Measurements





The comparator measurement function is enabled. Pressing the COMP key executes comparator decision according to the settings

Disabling the Comparator Measurement Function

COMP SET 1

COMP off

The comparator measurement function is disabled.



- Comparator and BIN measurements cannot be executed simultaneously.
- Auto-ranging is not available for comparator measurements. If auto-ranging is on when the comparator function is enabled, autoranging is disabled.
- To avoid operating errors, only the following keys are enabled when the comparator is being used: SAVE (SHIFT+LOAD), LOAD, STAT, TRIG (for external trigger), and PRINT (when a printer is connected) The comparator function must be disabled in order to change the threshold values.
 5.15 Valid Functions for Each State (Page 75)
 +OE is judged to be Hi, and -OE is judged to be Lo. No decision
- +OF is judged to be Hi, and -OF is judged to be Lo. No decision occurs in the event of a measurement fault.
- If temperature correction is enabled and the temperature probe is improperly connected, or if the measured temperature is OF or -OF, no decision occurs.
- When comparing by reference value/tolerance, upper and lower thresholds are calculated internally for comparison with measured resistance.

Upper threshold = Reference value x $\frac{100 + \text{Tolerance [\%]}}{100}$ Lower threshold = Reference value x $\frac{100 - \text{Tolerance [\%]}}{100}$

Therefore, even if the relative display value is the same as a decision threshold, it may be judged Hi or Lo.

Example: If the reference value is set to 90.000 Ω and the tolerance is set to 0.012%, the upper threshold is 90.010 Ω . At this time, a measurement of 90.011 Ω will be displayed as 0.012%, but because it exceeds the upper threshold, it is judged as Hi.

• If power is turned off while the setting display is active, settings are ignored, and revert to their former values. If you want to apply the displayed settings, press the ENTER key.

Function Description

BIN Measurement compares a measured value with up to ten sets of upper and lower thresholds (BIN0 to BIN9) in one operation, and display the results.

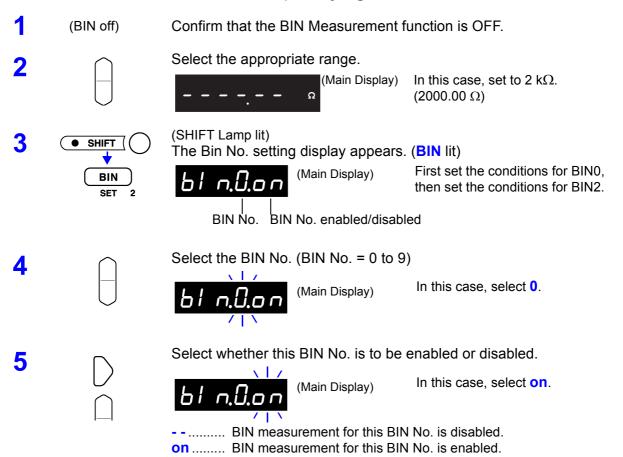
Decision results are output at the EXT I/O connector.

For details about BIN signal outputs at the EXT I/O connector, refer to 6.2 Signal Descriptions (Page 78).

To perform BIN measurement, first select the range, then set the upper and lower thresholds or the reference value/tolerance for each BIN No..

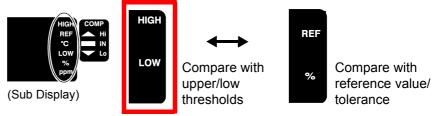
Setting upper and lower thresholds to judge measured values (BIN Measurement Function)

Example: In the 2 k Ω range, set up two decision states using different upper/lower thresholds (BIN0: Upper threshold 1 k Ω /Lower threshold 800 Ω and BIN2: Upper threshold 900 Ω / Lower threshold 700 Ω), and judge measurements.



Switches to comparison method selection for measurements.

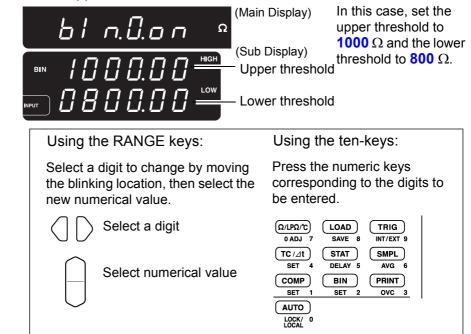
Select the comparison method. Each key-press changes the displayed selection.



In this case, select HIGH/LOW.

Switches the display to upper/lower threshold setting

Set the upper and lower thresholds.



Returns to the Main Display of this BIN No.

Repeat Steps 3 to 7 for each BIN No.



In this case, select BIN2 as shown at the left.

BIN2 Upper threshold: 900 Ω Lower threshold: 700 Ω



Or ten-keys

Applies setting and returns to the Measurement display. The BIN function is enabled.

To cancel the settings: • SHIFT (

6

7

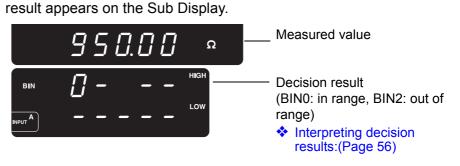
8

9

52



Connect to a test object, and judge the measured value. The measured value appears on the Main Display, and the decision



NOTE

BIN

SET 2

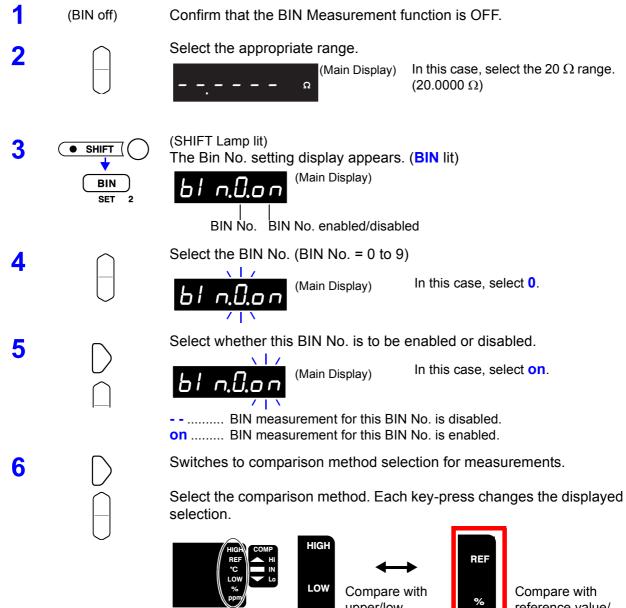
Upper and lower thresholds are stored as the actual entered digits, independent of measurement function and range.

When the measurement function or range is changed, the absolute value represented by the entered digits changes accordingly.

Example: To set the lower threshold to 3.8 Ω in the 20 Ω range, enter 038000. If you now switch to the 200 Ω range, the lower threshold becomes 38 Ω .

Judging measured values by setting a reference value and tolerance (BIN Measurement Function)

Example: In the 20 Ω range, set up two comparisons using a reference value and tolerance for each (BIN0:Reference value 15 Ω/tolerance: 5%, BIN2:Reference value **15** Ω /tolerance: **2%**).

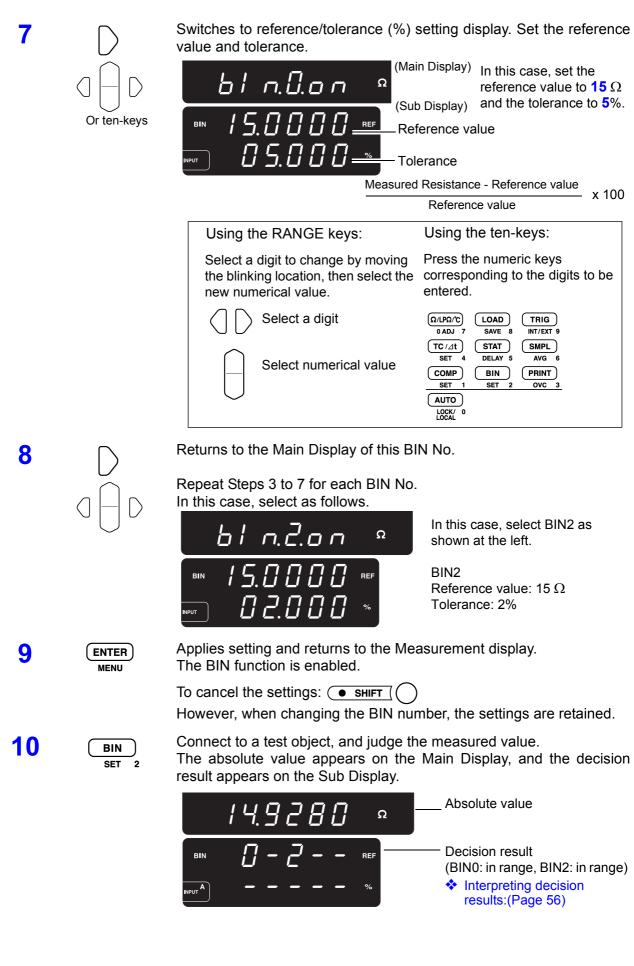


(Sub Display)

upper/low thresholds

reference value/ tolerance

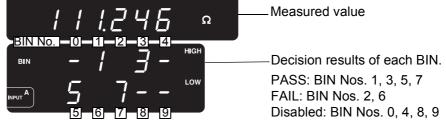
In this case, select **REF**/%.



Executing BIN Measurements

(BIN lit)

The BIN measurement function is enabled. Pressing the BIN key executes decision according to the setting conditions.



- Numerals (0 to 9): Numbers of the BINs that PASS (Measured value is within the range of the conditions set for the displayed BIN No.)
- No Display: FAIL (Measured value is outside of the range of the conditions set for the nondisplayed BIN No.)
- -: Disabled (no decision) (Displayed when the BIN No. setting is OFF on the Main Display)

Disabling the BIN Measurement function



(BIN off) Disables the BIN Measurement function.

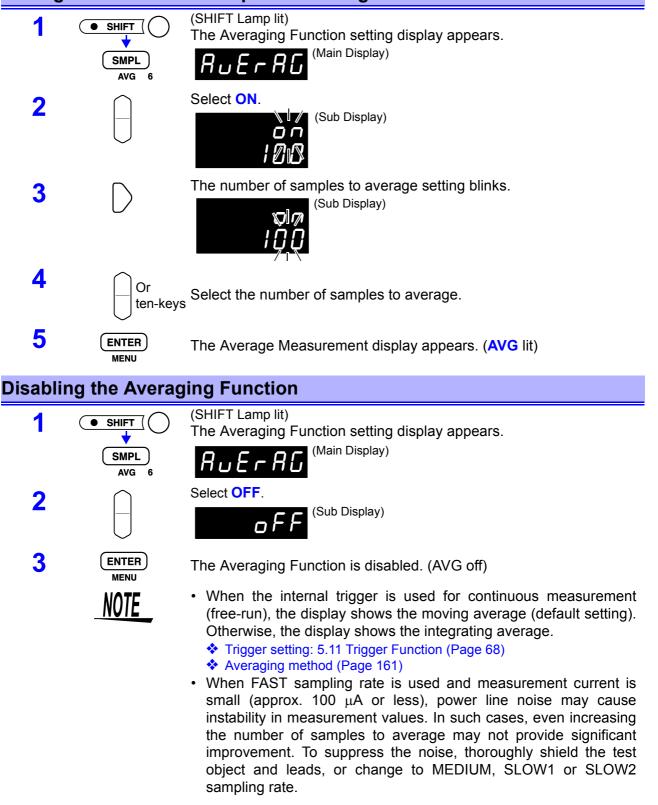


- BIN and Comparator measurements cannot be performed simultaneously.
- When BCD output is enabled, BIN measurement results cannot be output as External I/O signals.
 - BIN No. Output/BCD Signal Selection (Page 82)
- To avoid operating errors, only the following keys are enabled when the BIN function is in use: SAVE (SHIFT+LOAD), LOAD, STAT, TRIG (for external trigger), and PRINT (when a printer is connected)
 \$ 5.15 Valid Functions for Each State (Page 75)
- If power is turned off while the setting display is active, settings are ignored, and revert to their former values. If you want to apply the displayed settings, press the ENTER key.
- If auto-ranging is on when BIN measurement is enabled, auto-ranging is disabled.
- · No decision occurs in the event of a measurement fault.

5.3 Averaging Function

FunctionThe Averaging Function averages measurement values for output.DescriptionThis function can minimize instability of displayed values.
The number of samples to average can be set from 2 to 100.

Setting the Number of Samples to Average



5.4 Temperature Correction Function (TC)

Function Description

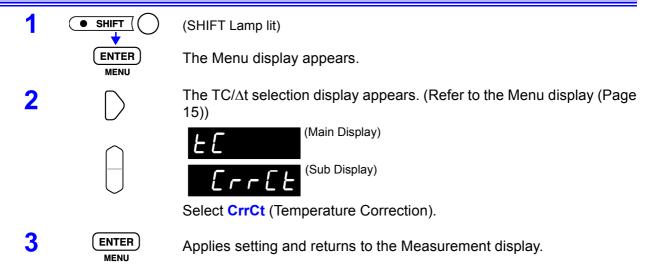
The principle of temperature correction (Appendix 2 Temperature Correction Function (TC) (Page 170)) is used to convert the resistance measured at ambient temperature to its equivalent resistance at a reference temperature for display.

Be sure to read the following before connecting a temperature sensor to the TC SENSOR terminal on the rear panel.

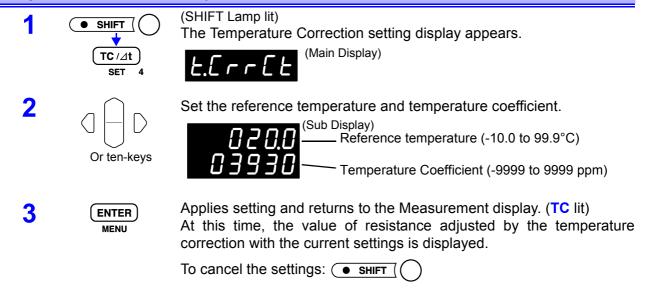
2.4 Connecting the Temperature Probe (Page 21)

2.5 Connecting an Analog Output Thermometer (Page 22)

Selecting the Temperature Correction Function



Making Temperature Correction Settings (Reference Temperature and Temperature Coefficient)



Enabling/Disabling Temperature Correction

| (TC /⊿t) | TC litTemperature Correction enabled |
|----------|--|
| SET 4 | TC off Temperature Correction disabled |



| An error appears when you press the TC/∆t key | The 9451 TEMPERATURE PROBE may not be connected, or may be connected incorrectly. If Temperature Correction cannot be enabled, check the connections of the temperature probe. |
|---|---|
| NOTE | Temperature Correction does not work if the temperature probe is allowed to touch the test object. Only the ambient temperature of the immediate locale should be used. |
| | • Install the temperature probe and allow at least 60 minutes warm- up before measurement. Unless the test object and temperature probe used for temperature correction measurement have been allowed to completely stabilize at ambient temperature, large measurement errors may occur. |

• If the temperature probe is not inserted all the way into the TC SENSOR jack on the rear of the instrument, large measurement errors may occur.

5.5 Temperature Conversion Function (At)

Function Description

The temperature conversion principle (Appendix 3 Temperature Conversion Function (Δt) (Page 172)) is used to derive temperature increase over time.



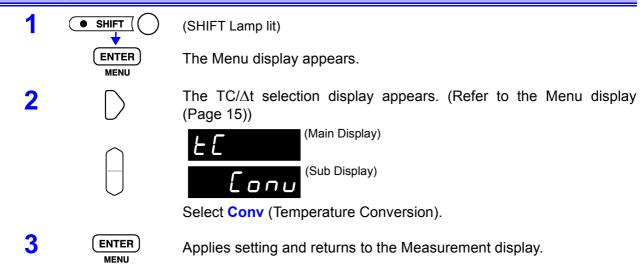
When using the Temperature Conversion function, the following functions are not available:

Comparator, BIN and Statistical Calculation functions

The Temperature Conversion function is disabled at the factory before shipping.

Use the following procedure to enable the Temperature Conversion function. In this case, the Temperature Correction function is disabled.

Selecting the Temperature Conversion Function



| Setting | Setting the Conversion Constant | | | | |
|---------|---------------------------------|--|--|--|--|
| 1 | | (SHIFT Lamp lit) | | | |
| | | The constant setting display appears. | | | |
| 2 | Or ten-keys | Set the reciprocal (k) of the temperature coefficient at 0°C, initial resistance (R1) and initial temperature (t1). (Main Display) Initial resistance (R1) [0 m Ω to 110 M Ω] | | | |
| | | (Sub Display) Initial temperature (t1) [-10.0 to 99.9°C] Reciprocal (k) of the temperature coefficient at 0°C (-999.9 to 999.9) | | | |
| | | k Reference Value Recommended by IEC60034 as follows: Copper: k = 235 Aluminum: k = 225 ★ Reference (Page 171) | | | |
| 3 | ENTER MENU | Applies setting and returns to the Measurement display. To cancel the settings: • SHIFT | | | |

Enabling/Disabling Temperature Conversion

| TC /⊿t | Δt lit |
|--------|--|
| SET 4 | ∆t offTemperature Conversion disabled. |

5.6 Statistical Calculation Functions

Function Description

The mean, maximum, minimum, overall standard deviation, standard deviation of sample and process capability indices are calculated and displayed for up to 30,000 measurement values.

The calculation formulas are as follows: Mean \sum_{r}

Overall standard deviation

Standard deviation of sample

$$\overline{x} = \frac{\sum x}{n}$$

$$\sigma = \sqrt{\frac{\sum x^2 - n\overline{x}^2}{n}} \quad (= \sigma_n)$$

$$s = \sqrt{\frac{\sum x^2 - n\overline{x}^2}{n-1}} \quad (= \sigma_{n-1})$$

$$Cp = \frac{|Hi - Lo|}{\epsilon}$$

Process capability index (dispersion)

Process capability index (bias)

$$CpK = \frac{|Hi - Lo| - |Hi + Lo - 2\overline{x}|}{6\sigma_{n-1}}$$

• In these formulas, n represents the number of valid data samples.

 $6\sigma_{n-1}$

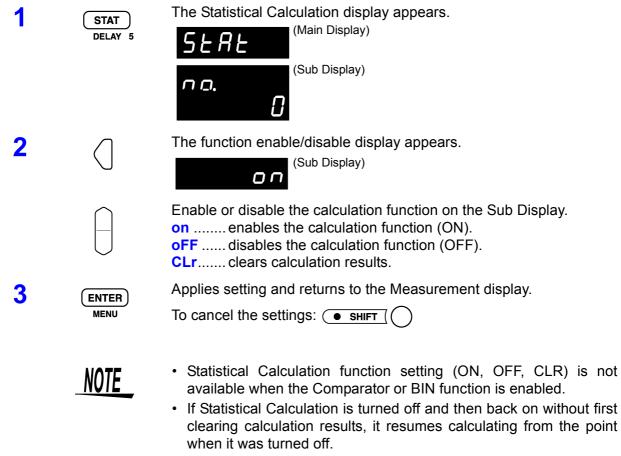
- Hi and Lo are the upper and lower thresholds of the comparator.
- The process capability indices represent the quality achievement capability created by a process, which is the breadth of the dispersion and bias of the process' quality. Generally, depending on the values of Cp and CpK, process capability is evaluated as follows:

| Cp, CpK>1.33 | Process capability is ideal |
|-------------------------|----------------------------------|
| $1.33 \ge Cp, CpK>1.00$ | Process capability is adequate |
| $1.00 \geq Cp, CpK$ | Process capability is inadequate |



- When only one valid data sample exists, standard deviation of sample and process capability indices are not displayed.
- When σ_{n-1} is 0, Cp and Cpk are 99.99.
- The upper limit of Cp and CpK is 99.99. Values of Cp and CpK>99.99 are displayed as 99.99.
- When the BIN function is enabled, Cp and CpK are calculated using the upper and lower thresholds of the comparator.
- Negative values of CpK are handled as CpK=0.
- Values measured by the Temperature Conversion function (Δt) cannot be used in statistical calculations.
- Changing settings for the Comparator, BIN or Temperature Correction functions while performing statistical calculations invalidates calculation results.

Enabling/Disabling the Statistical Calculation Function, and Clearing Calculation Results



• The Statistical Calculation function slows measurements when it is ON.

| Importing Data | | |
|-------------------|---|--|
| TRIG INT/EXT 9 | Pressing the TRIG key while Statistical Calculation is ON executes one of the following operations: External Trigger: Takes one measurement and performs statistical calculation on the result | |
| | Internal Trigger: Performs statistical calculation on the value displayed immediately after pressing | |
| NOTE | *TRG command executes the same operation. Grounding the TRIG terminal of the EXT I/O connector executes the same operation. | |

Confirming Statistical Calculation Results



The Statistical Calculation display appears.

Maximum

No.

Data Sample

The indication on the display changes as follows with each key-press.

(Sub Display)

Total data count \rightarrow Mean (indicated as "Average") \rightarrow Maximum \rightarrow Minimum \rightarrow Overall standard deviation \rightarrow Standard deviation of sample \rightarrow Process capability indices

Mean

Total data count



Maximum

20.0

ALIECRG 2.7019 Valid data Mean

Minimum



Overall standard deviation



Process capability indices



Standard deviation of sample



ON/OFF/CLR setting



NOTE

- No calculation results can be displayed when there are no valid data samples.
- When only one valid data sample exists, standard deviation of sample and process capability indices cannot be displayed.

Sending Statistical Calculation Results to the Printer

PRINT ovc 3 With the statistical calculation results displayed, press the PRINT key. The statistical calculation results are output to the optional printer. Chapter 7 Printer (Optional) (Page 87)

5.7 Offset Voltage Compensation (OVC)

Function Description

This function automatically compensates for the effects of thermoelectromotive force (Appendix 4 Effect of Thermoelectromotive Force (Page 173)) and internal offset voltage of the instrument.

- With the 2 Ω or higher range

Displays the true measurement value as follows by measuring ${\sf R}_{\sf ON}$ with measurement current on, then ${\sf R}_{\sf OFF}$ with measurement current off.

 R_{ON} - R_{OFF}

- With the 20 m Ω and 200 m Ω ranges

Displays the true measurement value as follows depending on measurement R_P with current flow in the positive direction and measurement R_N with current flow in the negative direction.

$$\frac{\left|R_{P}\right|+\left|R_{N}\right|}{2}$$

Enabling/Disabling Offset Voltage Compensation



(SHIFT Lamp lit)

OVC lit Offset Voltage Compensation enabled OVC off Offset Voltage Compensation disabled



- When the thermal capacity of the test object is small, the Offset Voltage Compensation function may be ineffective.
- When the test object is inductive, some delay is necessary after switching current on or off before starting measurement. To ensure that inductance does not affect the measurement, the delay setting should aim for about 10 times the value calculated according to the following formula (see also 5.11.2 Trigger Delay (Page 69)). However, auto delay sets about 100 ms delay presuming that R and L have similar values.

$$t = -\frac{L}{R} \ln \left(1 - \frac{IR}{V_o} \right)$$

L..... Inductance of test object

R Resistance of test object + test leads + contacts

I..... Measurement current (refer to 9.2 Accuracy (Page 164))

V_O...... Open-terminal voltage (refer to 9.2 Accuracy (Page 164))

- The setting is ignored in the 100 k Ω range and higher.
- Even when a test object is purely resistive, a delay of about 1 to 10 ms is required. To adjust the delay, begin with a longer delay than necessary, then gradually shorten it while watching the measured value.
- If using the Zero-Adjust function, execute it after making any changes to Offset Voltage Compensation.
- When Offset Voltage Compensation is enabled (OVC lit) measurement time is increased.
- 6.3 Timing Chart; Measurement Time (Page 84)

5.8 Self-Calibration

Function Description

To enhance measurement precision, this instrument performs selfcalibration to compensate for internal circuit offset voltage and gain drift.

With SLOW1 and SLOW2 sampling, self-calibration is performed once for each measurement. The settings here do not apply when SLOW1 or SLOW2 is selected.

With FAST and MEDIUM sampling, to increase measurement speed, self-calibration is performed only with the timing specified as follows.

- Self-calibration: Auto Self-calibration is performed for about 55 ms once every 30 minutes.
- Self-calibration: Manual

Self-calibration is performed when the CAL terminal of the EXT I/O connector is connected to GND.

Self-calibration should always be performed after warm-up.

Setting Auto or Manual Self-Calibration (FAST or MEDIUM)

| 1 | |
|---|--|
| | |
| | |

(SHIFT Lamp lit)

The Menu display appears.

The self-calibration setting display appears.

(Refer to the Menu display (Page 15))



Select Auto or Manual on the Sub Display.

In Manual self-calibration

3

2

NOTE

Applies setting and returns to the Measurement display.

Self-calibration is performed in the following cases regardless of the above settings:

- When the range is changed
- When the sampling rate is changed
- When a Load operation (refer to 5.13 Panel Load Function (Page 72)) is executed
- When a reset is performed
- When the measurement function is changed.

To obtain the specified accuracy, perform self-calibration in the following cases:

- After warm-up
- When the ambient temperature changes by 2°C or more

Triggers occurring during self-calibration are delayed so that the corresponding measurement occurs only after self-calibration has finished. When using an external trigger, measurement may occur at unintended times, in which case we suggest selecting Manual self-calibration.

5.9 Key Beeper Setting

FunctionSelect whether a beep sounds when an operating key on the front of
the instrument is pressed.

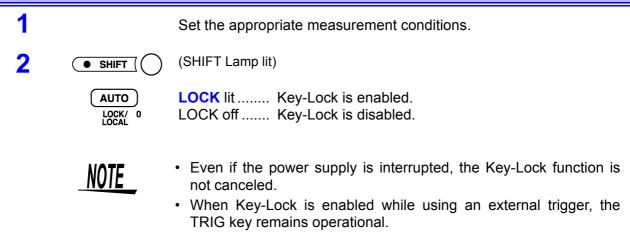
Setting the Key Beeper ON/OFF

| • | • | |
|---|-----------|---|
| 1 | | (SHIFT Lamp lit) |
| | | The Menu display appears. |
| 2 | \square | The key beeper setting display appears. (Refer to the Menu display (Page 15)) |
| | | (Main Display) |
| | ~ | (Sub Display) |
| | | The current setting of the key beeper blinks. |
| | \bigcup | Select the key beeper state on the Sub Display. on Key beeper enabled oFF Key beeper disabled |
| 3 | | Applies setting and returns to the Measurement display. |

5.10 Key-Lock Function

FunctionExecuting Key-Lock disables the operating keys on the front of the
instrument. This function can be useful for protecting settings.

Enabling/Disabling Key-Lock



5.11 Trigger Function

5.11.1 Trigger Source

Function Description Two trigger sources are available: internal and external.

Internal Trigger
 Trigger signals are automatically generated internally.
 When using the internal trigger source, measurement current flows continuously.

• External Trigger Trigger signals are provided externally or manually.

Selecting an Internal or External Trigger Source

Press when **EXT.TRIG** is lit. (SHIFT Lamp lit)

measurement.



EXT.TRIG off Internal triggering is selected.

EXT.TRIG lit External triggering is selected.

| Measurement with External Triggering | External triggering can be provided in three ways: By key operation Pressing the TRIG key triggers one measurement. By External I/O input Grounding the TRIG terminal of the rear panel EXT I/O connector triggers one measurement. |
|---|--|
| | Construction of the interface interfa |

| NOTE | When the Internal Trigger source is enabled, the EXT I/O signal and the "*TRG" command are ignored. |
|------|--|
| | When using external triggering, current flows while measuring with the Low-Power Resistance function in all ranges, and with the Resistance Measurement function, in the 20 mΩ to 20 Ω ranges. 6.3 Timing Chart (Page 83) |
| | The response time depends on the test object, so some Delay should always be set. Initially set a long Delay, then while watching the measured value, shorten it gradually. \$ 5.11.2 Trigger Delay (Page 69) |
| | • Normally, the "continuous measurement" condition occurs when operating from the front panel. When internal triggering is selected, the "Free-Run" condition causes continuous triggering. When external triggering is selected, each trigger causes one measurement. |
| | Continuous measurement can be disabled by setting via RS-232C |

or GP-IB. When continuous measurement is disabled by setting via RS-232C received only according to the timing specified by the host (PC or sequencer).

About trigger commands: (7) Triggering (Page 140)

✤ 8.7 Basic Data Importing Methods (Page 147)

5.11.2 Trigger Delay

Function Description

Set the delay between trigger signal input and the start of measurement.

By using this function, even when a trigger is input immediately upon connecting to a test object, measurement can be delayed to allow conditions to stabilize.

Two types of trigger delay are available:

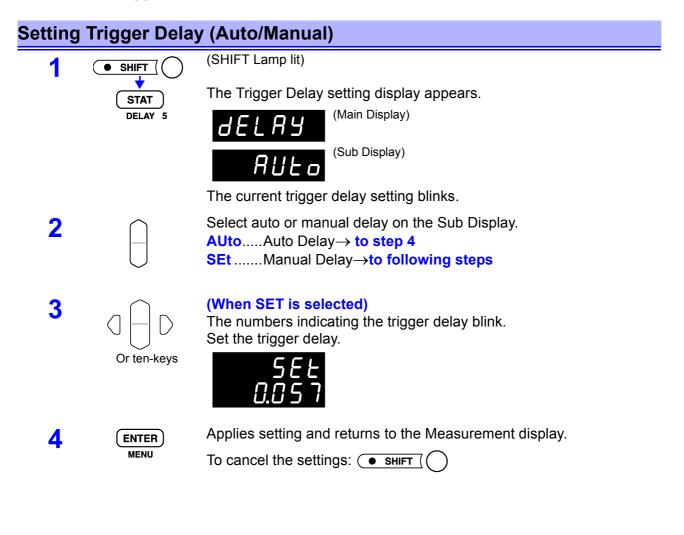
 Auto Delay The delay is set automatically for each range. (see Table below)
 Manual Delay Set the delay time independently.

Set the delay time independently. The trigger delay can be set with 1 ms resolution from 0.000 to 9.999 s.

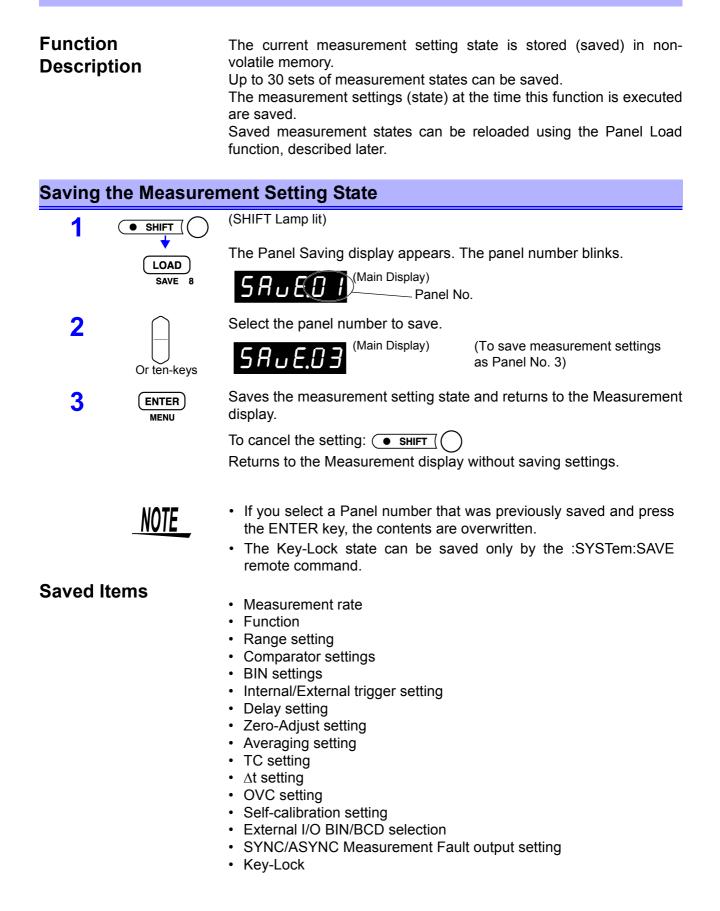
Auto Delay Times

| | | Range [Ω] | 20 m | 200 m | 2 | 20 | 200 | 2 k | 20 k | 100 k | 1 M | 10 M | 100 M |
|---------------------------|------------|--------------------|------|-------|-----|-----|-----|-----|------|-------|-----|------|-------|
| Resistance | Delay [ms] | OVC OFF | 30 | 30 | 3 | 3 | 3 | 3 | 3 | 10 | 100 | 500 | 1000 |
| Measurement | | OVC ON | 100 | 100 | 100 | 100 | 100 | 100 | 100 | — | _ | _ | _ |
| Low-Power | Delay [ms] | OVC OFF | _ | _ | 3 | 3 | 3 | 15 | _ | _ | _ | _ | _ |
| Resistance Measurement | | OVC ON | _ | — | 100 | 100 | 100 | 100 | _ | - | — | _ | - |

OVC: Offset Voltage Compensation



5.12 Panel Save Function



5.13 Panel Load Function

FunctionLoads the measurement settings saved by the Panel Save functionDescriptionfrom internal non-volatile memory.

Loading Saved Measurement Settings



1

2

3

Or ten-keys

Select the panel number to load.



LoRd

(To load measurement settings from Panel No.3)

ENTER MENU Loads the measurement setting state and returns to the Measurement display.

The Panel Loading display appears. The panel number blinks.

Panel No.

(Main Display)

To cancel loading: • SHIFT

Returns to the Measurement display without loading the measurement setting state.



- If an unsaved Panel No. is selected, a warning beep sounds when you press ENTER.
- When selecting a Panel No. with the up/down RANGE keys, only the numbers of previously saved panels appear.
- Loading can also be executed using the TRIG signal and the LOAD0 to LOAD4 pins of the EXT I/O interface.
 - Chapter 6 External Control; Input Signals (Page 79)

5.14 Reset Function

Function Description

Two Reset methods are available:

Reset

Re-initializes all measurement settings except for Panel Save data to their factory defaults.

• System Reset Re-initializes all measurement settings, including Panel Save data, to their factory defaults.

| Execut | Executing Reset or System Reset | | | | | | | | | |
|--------|---------------------------------|--|--|--|--|--|--|--|--|--|
| 1 | | (SHIFT Lamp lit) | | | | | | | | |
| | | The Menu display appears. | | | | | | | | |
| 2 | \square | The Reset display appears. (Refer to the Menu display (Page 15)) CESEL (Main Display) (Sub Display) (Sub Display) | | | | | | | | |
| 3 | | Select the Reset method on the Sub Display. SEt Reset (initializes measurement settings other than those stored with Panel Save) SYS System Reset (initialize all measurement settings) | | | | | | | | |
| 4 | \square | ENTER blinks. SEE EnEEr | | | | | | | | |
| 5 | ENTER MENU | Executes the Reset. | | | | | | | | |
| | | To cancel: • SHIFT O Returns to the Measurement display without resetting. | | | | | | | | |
| | NOTE | System Reset also initializes Panel Save data. | | | | | | | | |

Initial Factory Default Settings

| Description | Default | Description | Default |
|---|---------------------------|---|--------------------------------------|
| Measurement Function | Resistance | Trigger Source | Internal trigger |
| Resistance Measurement Range | AUTO | Line Frequency | 60 Hz |
| LP Resistance Measurement Range | AUTO | Key Beeper | ON |
| Zero-Adjust | OFF | Key-Lock | OFF |
| Zero-Adjust Value | 0 | Comparator | OFF |
| Temperature Correction/ Conversion | Temperature Correction | Comparator Mode | Hi/Lo |
| TC/∆ t | OFF | Comparator Upper Threshold | 0 |
| Temperature Correction Ref Temp. | 20°C | Comparator Lower Threshold | 0 |
| Temperature Correction Coefficient | 3930 ppm | Comparator Beeper | HL |
| Temperature Conversion Initial Resistance | $0 \text{ m}\Omega$ | BIN | OFF |
| Temperature Conversion Initial Temperature | 23°C | BIN Enable/Disable | All Disabled |
| Temperature Conversion Constant | 235°C | BIN Mode | All Hi/Lo |
| Statistical Calculation Functions | OFF | BIN Upper Threshold | All 0 |
| Delay | AUTO | BIN Lower Threshold | All 0 |
| Delay Time | 0.000 s | Interface | RS-232C |
| Sampling Rate | SLOW2 | Print interval | 0 |
| Averaging Function | OFF | BIN/BCD Output | BIN Output |
| Average Times | 2 | Error Output | Async |
| Offset Voltage Compensation | OFF | Input Terminals | А |
| Self-Calibration | AUTO | Temperature Sensor Pt/ Analog /RS-232C | Pt |
| Continuous Measurement | ON | Analog Temperature Measurement Constants | T1: 0°C T2: 500°C V1: 0 V V2: 1 V |

5.15 Valid Functions for Each State

Valid, - = Invalid, * = Fixed Setting

| | State | | | | | | | | | | | |
|--------------------------|---------------------------|----------------------------|---------------|--------|-----------|-----------|--------------|-----------|------------------|-----------|-----------|----------------------------|
| Function | Resistance Measurement | Temperature Measurement | Comparator ON | BIN ON | TC ON | Δt ON | Auto-Ranging | 0-Adjust | External Trigger | Delay | Averaging | Statistical Calculation |
| Function selection | | | * | * | | | | | | | | |
| Load/Save | • | • | • | • | • | ٠ | • | • | ٠ | • | • | • |
| Trigger selection | | — | * | * | • | • | • | • | • | • | • | • |
| TC/∆t ON/OFF | ٠ | - | * | * | ٠ | ٠ | • | • | ٠ | ٠ | ٠ | • |
| TC/∆t Setting | \bullet | — | * | * | | | | | | • | | • |
| Statistical Calculation | | - | * *1 | * *1 | • | - | • | • | ٠ | ٠ | ٠ | • |
| Sampling | | - | * | * | • | \bullet | • | • | • | • | \bullet | \bullet |
| Averaging setting | ۲ | — | * | * | \bullet | \bullet | • | • | ۲ | • | \bullet | • |
| Comparator ON/OFF | • | — | • | - | • | — | ●*3 | • | • | • | • | • |
| Comparator setting | • | — | * | — | \bullet | — | \bullet | \bullet | ۲ | ۲ | \bullet | \bullet |
| BIN ON/OFF | • | - | — | * | • | — | ●*3 | • | • | • | • | • |
| BIN setting | • | — | - | * | • | - | \bullet | • | ٠ | • | ٠ | • |
| Print | • | • | • | • | • | | • | • | • | • | • | • |
| Auto-Ranging | \bullet | — | — | — | • | \bullet | \bullet | \bullet | ۲ | ۲ | \bullet | lacksquare |
| Range selection | • | — | * | * | • | • | • | • | • | • | • | • |
| 0-Adjust execution | \bullet | _ | * | * | \bullet | \bullet | \bullet | \bullet | \bullet | \bullet | \bullet | ightarrow |
| Delay setting | \bullet | — | * | * | | | \bullet | | | | | \bullet |
| OVC ON/OFF | ۲ | — | * | * | \bullet | \bullet | • | • | ۲ | • | \bullet | • |
| Key-Lock | • | • | • | • | • | | • | • | • | • | • | • |
| Zero-Adjust Clear | ullet | ● | * *2 | * *2 | \bullet | \bullet | lacksquare | \bullet | \bullet | ● | \bullet | \bullet |
| TC/∆t selection | • | \bullet | * *2 | * *2 | \bullet | \bullet | • | • | | • | | • |
| Interface setting | • | • | * *2 | * *2 | • | • | • | • | • | • | • | • |
| AUTO/MANU Calibration | • | • | * *2 | * *2 | • | • | • | • | • | • | • | • |
| External I/O BIN/BCD |) 🔴 | \bullet | * *2 | * *2 | • | \bullet | \bullet | \bullet | ۲ | ۲ | \bullet | lacksquare |
| Err Output Sync/Async | • | • | * *2 | * *2 | • | • | • | • | • | • | • | • |
| Key Click Sound | • | • | * *2 | * *2 | • | • | • | • | ٠ | ٠ | • | • |
| Line Frequency | • | \bullet | * *2 | * *2 | • | • | \bullet | \bullet | • | \bullet | • | • |
| Adjustment | | • | * *2 | * *2 | • | | \bullet | • | | • | • | \bullet |

*1: Display-only

*2: Does not appear on menu display

*3: Auto-Ranging is OFF

5.15 Valid Functions for Each State

External Control Chapter 6

6.1 External Control and the External Input/ Output (EXT I/O) Connector

| <u> WARNING</u> | To avoid electrical hazards, observe the following cautions: Turn off power to all devices before making connections. Make sure connections are secure so that no wires can become loose during operation and contact conductive parts such as the chassis or test leads. Note that INT.GND is grounded. Therefore, if the controller has electric potential relative to ground, a short-circuit hazard exists which may cause an accident. |
|--|--|
| <u> CAUTION</u> | To avoid damage to the instrument, observe the following cautions: Do not apply voltage or current to the EXT I/O terminals that exceeds their ratings. When driving relays, be sure to install diodes to absorb counter-electromotive force. Be careful not to short-circuit INT.VCC to INT.GND. Always provide protective grounding for devices to be connected to external input and output terminals. |
| External Control Input Functions | External trigger input (TRIG) Select Panel No. to load (LOAD0 to LOAD4) Zero-adjust signal input (OADJ) Print Signal input (PRINT) Self-calibration signal input (CAL) |
| External Output Terminal Functions | End-of-Conversion signal output (EOC) Reference signal output (INDEX) Measurement Fault signal output (ERR) Comparator decision signal output (Hi, IN, Lo) BIN signal outputs (BIN0 to BIN9)^{*1} BCD output (BCD1-0 to BCD6-3)^{*1} General-purpose outputs (OUT0 to OUT7)^{*2} *1: BIN outputs and BCD outputs cannot both be used simultaneously. *2: General-purpose outputs (OUT0 to OUT7) are not available when the BCD outputs are selected. |

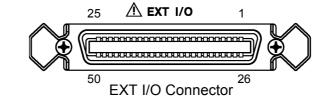
6.2 Signal Descriptions

Connector Type 57RE-40500-730B (D29) (manufactured by DDK)

Mating Connector 57-30500 (manufactured by DDK) or equivalent

6.2 Signal Descriptions

Pinout



| Pin | I/O | Signal name | Pin | I/O | Signal name |
|-----|-----|---------------|-----|-----|---------------|
| 1 | IN | LOAD0 | 26 | IN | LOAD1 |
| 2 | IN | LOAD2 | 27 | IN | LOAD3 |
| 3 | IN | LOAD4 | 28 | IN | 0ADJ |
| 4 | IN | TRIG (IN0) | 29 | IN | CAL |
| 5 | IN | PRINT (IN1) | 30 | - | Unused |
| 6 | | INT.GND | 31 | | INT.GND |
| 7 | | INT.GND | 32 | | INT.GND |
| 8 | | INT.GND | 33 | | INT.GND |
| 9 | | INT.VCC | 34 | | INT.VCC |
| 10 | | INT.VCC | 35 | | INT.VCC |
| 11 | OUT | ERR | 36 | OUT | INDEX |
| 12 | OUT | EOC | 37 | OUT | Hi |
| 13 | OUT | IN | 38 | OUT | Lo |
| 14 | OUT | BIN0 (BCD1-0) | 39 | OUT | BIN1 (BCD1-1) |
| 15 | OUT | BIN2 (BCD1-2) | 40 | OUT | BIN3 (BCD1-3) |
| 16 | OUT | BIN4 (BCD2-0) | 41 | OUT | BIN5 (BCD2-1) |
| 17 | OUT | BIN6 (BCD2-2) | 42 | OUT | BIN7 (BCD2-3) |
| 18 | OUT | BIN8 (BCD3-0) | 43 | OUT | BIN9 (BCD3-1) |
| 19 | OUT | OB (BCD3-2) | 44 | OUT | (BCD3-3) |
| 20 | OUT | (BCD4-0) | 45 | OUT | (BCD4-1) |
| 21 | OUT | (BCD4-2) | 46 | OUT | (BCD4-3) |
| 22 | OUT | OUT0 (BCD5-0) | 47 | OUT | OUT1 (BCD5-1) |
| 23 | OUT | OUT2 (BCD5-2) | 48 | OUT | OUT3 (BCD5-3) |
| 24 | OUT | OUT4 (BCD6-0) | 49 | OUT | OUT5 (BCD6-1) |
| 25 | OUT | OUT6 (BCD6-2) | 50 | OUT | OUT7 (BCD6-3) |

Input Signals _

LOAD0 to LOAD4 Select a Panel No. to load and apply a TRIG signal to load the selected Panel No. and measure. LOAD0 is the LSB, and LOAD4 is the MSB.

| LOAD4 | LOAD3 | LOAD2 | LOAD1 | LOAD0 | Panel No. | - |
|--------|--------|--------|-------|-------|-----------|-------------------|
| 0 | 0 | 0 | 0 | 0 | * | 0: LOAD terminal |
| 0 | 0 | 0 | 0 | 1 | 30 | shorted to GND |
| 0 0 | 0 0 | 0 0 | 1 | 0 | 29 | |
| 0 | 0 | 0 | 1 | 1 | 28 | 1: LOAD terminal |
| 0 | 0 | 1 | 0 | 0 | 27 | open or connected |
| 0 | 0 | 1 | 0 | 1 | 26 | to 5 V |
| 0 | 0 | 1 | 1 | 0 | 25 | |
| 0 | 0 | 1 | 1 | 1 | 24 | • |
| 0 | 1 | 0 | 0 | 0 | 23 | |
| 0 | 1 | 0 | 0 | 1 | 22 | |
| 0 | 1 | 0 | 1 | 0 | 21 | |
| 0 | 1 | 0 | 1 | 1 | 20 | |
| 0 | 1 | 1 | 0 | 0 | 19 | |
| 0 | 1 | 1 | 0 | 1 | 18 | |
| 0 | 1 | 1 | 1 | 0 | 17 | |
| 0 | 1 | 1 | 1 | 1 | 16 | |
| 1 | 0 | 0 | 0 | 0 | 15 | |
| 1 | 0 | 0 | 0 | 1 | 14 | |
| 1 | 0 | 0 | 1 | 0 | 13 | |
| 1 | 0 | 0 | 1 | 1 | 12 | |
| 1 | 0 | 1 | 0 | 0 | 11 | |
| 1 | 0 | 1 | 0 | 1 | 10 | |
| 1 | 0 | 1 | 1 | 0 | 9 | |
| 1 | 0 | 1 | 1 | 1 | 8 | _ |
| 1 | 1 | 0 | 0 | 0 | 7 | |
| 1 | 1 | 0 | 0 | 1 | 6 | |
| 1 | 1 | 0 | 1 | 0 | 5 | |
| 1 | 1 | 0 | 1 | 1 | 4 | |
| 1 | 1 | 1 | 0 | 0 | 3 | |
| 1 | 1 | 1 | 0 | 1 | 2 | |
| 1 | 1 | 1 | 1 | 0 | 1 | |
| 1 | 1 | 1 | 1 | 1 | * | - |

*: When a trigger signal is applied with LOAD0 to LOAD4 set to all 1's or all 0's, no Panel Load occurs.

At least 70 ms is required for the settings to change after executing a Panel Load (the actual time depends on the particular function, range and sampling rate).

Before using an external trigger signal applied to the $\overline{\text{TRIG}}$ terminal to control measurement, and after executing a Panel Load operation, set $\overline{\text{LOAD0}}$ to $\overline{\text{LOAD4}}$ to either all High or all Low.

When the external trigger, one measurement is taken each time the TRIG signal transitions from High to Low.

In the following cases, the $\overline{\text{TRIG}}$ signal is ignored:

- When using the internal trigger source
- When the Measurement display is not the active display
- When executing Panel Load in Remote state

Zero adjustment executes once when the \overline{OADJ} signal transitions from High to Low.

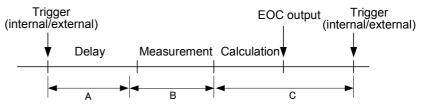
TRIG

0ADJ

| 80 | 6.2 Signal Descr | iptions | | | | | | |
|-----|---|---|--|--|--|--|--|--|
| | PRINT The current measurement value prints when the PRINT sign transitions from High to Low. | | | | | | | |
| | <u>INO, IN1</u> | When not using the TRIG and PRINT functions, they can be monitore as general-purpose input terminals with the :IO:IN? command. | | | | | | |
| | CAL | When manual self-calibration is selected with FAST or MEDIUM sampling rate, self-calibration begins when the CAL signal transitions from High to Low. Self-calibration requires about 55 ms to complete. When the SLOW1 or SLOW2 sampling rate is selected, the CAL signal is ignored. ◆ 5.8 Self-Calibration (Page 66) | | | | | | |
| Out | put Signals | | | | | | | |
| | ERR | Indicates a measurement fault. The Synchronous ERR output setting causes ERR output to be synchronous with EOC output, while with the Asynchronous ERR output setting causes ERR output to follow actual (asynchronous) contact of the probes with the test object. ◆ 4.5 Measurement Fault Detection Function (Page 43) ◆ Measurement Fault Output Signal (ERR) Setting (Page 82) | | | | | | |
| | INDEX | The INDEX signal is output during the Trigger Wait, Delay, Self-Calibration and Calculation states. This signal is not output while measuring the resistance of test objects. This signal transitions from Off to On to indicate that the test object can be removed. | | | | | | |
| | EOC | This signal indicates the end of a measurement (End-Of-Conversion). | | | | | | |
| | Hi, IN, Lo | These are the results of comparator decision. | | | | | | |
| | BIN0 to BIN9, OB (Out of BINs) | This output indicates the BIN No. that was judged to be IN by the BIN measurement function. If the decision does not apply to any BIN, the OB signal is output. When BCD outputs are selected, the BIN signals are not available. BIN No. Output/BCD Signal Selection (Page 82) | | | | | | |
| | OUT0 to OUT7 | The output signals are controlled by the :IO:OUT command. | | | | | | |
| | BCD1-0 to BCD6-3 | These are BCD outputs. BCD1 is the lower digit, and BCD6 the upper digit. BCDx-0 is the LSB, and BCDx-3 is the MSB. When BIN outputs are selected, the BCD signals are not available. Minus signs are not output. Also, temperature measurements are not output as BCD. IN No. Output/BCD Signal Selection (Page 82) | | | | | | |
| | INT.GND, INT.VCC | These are outputs of the instrument's internal 5 VDC and GND. | | | | | | |

NOTE

- I/O signals should not be used while measurement settings have been changed.
- When ERR output is set to Synchronous, errors are detected during the measurement period. Timing for the Asynchronous ERR setting is as follows:



Delay (A): any measurement fault is ignored

Measurement (B): the ERR is output immediately upon detection of a fault After measurement until the next trigger (C): ERR is output for measurement faults lasting at least 5 ms

Or, the fault is canceled by a valid measurement of at least 5 ms

However, when measuring large inductances, the ERR signal may be output for a period of (C).

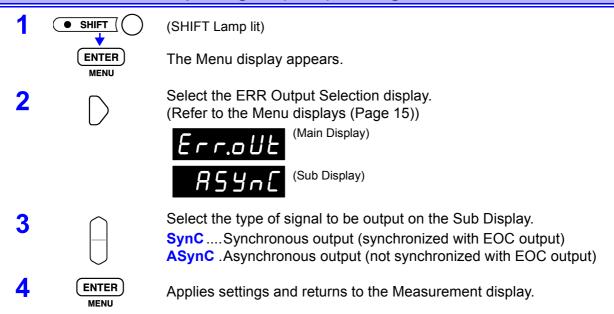
- After the probes contact the test object, at least about 500 μs is required for measurement stabilization.

This instrument's measurement fault detection function begins detecting measurement faults about 500 μ s before INDEX goes Low (OFF).

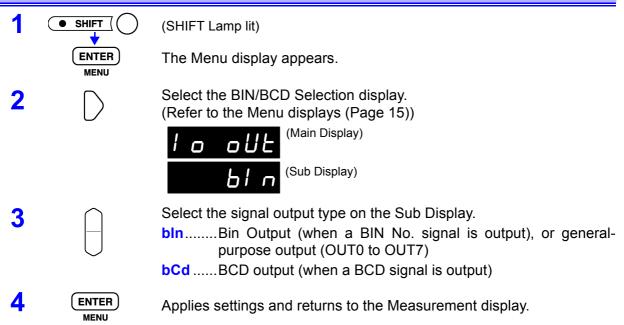
Therefore, if the Delay is set to 0.000 s, measurement faults that may occur before INDEX goes Low cannot be detected. To ensure reliable measurement, we suggest setting the Delay to at least 1 ms.

Instrument Settings

Measurement Fault Output Signal (ERR) Setting

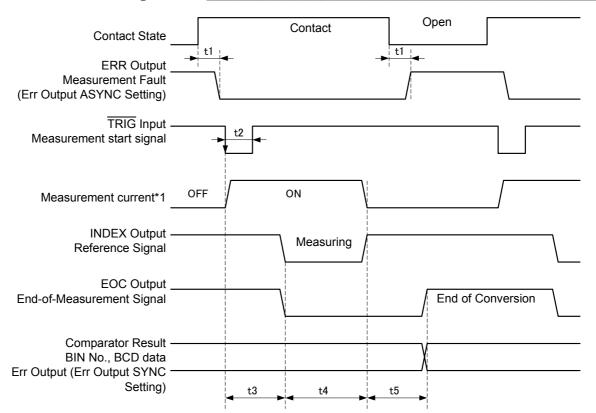


BIN No. Output/BCD Signal Selection



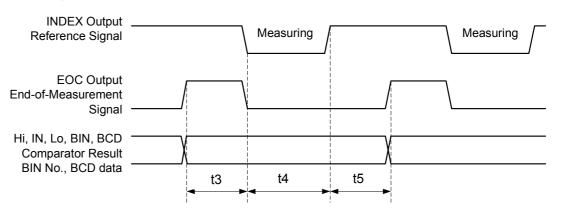
6.3 Timing Chart

Non-Free-Run Timing Chart



*1: However, in the 200 Ω or higher resistance ranges, current flows continuously.

Free-Run Timing Chart



| De | scription | | Time Offset Voltage Compensation (OVC) OFF | Offset Voltage Compensation (OVC) ON |
|----|------------------------|----------------------------------|---|---|
| t1 | ERR Output rea | sponse time | 100 μs | 100 μs |
| t2 | Measurement t width | rigger pulse | 100 μs min | 100 μs min |
| t3 | Delay Time | | per setting5.11.2 Trigger Delay (Page 69) | per setting |
| t4 | Measurement time*1 | FAST MEDIUM SLOW1 SLOW2 | 300 μs 20 ms (50 Hz) 16.7 ms (60 Hz) 100 ms 400 ms | 600 μs + t3 40 ms + t3 (50 Hz) 33.3 ms + t3 (60 Hz) 200 ms + t3 800 ms + 7 x t3 |
| t5 | Calculation time*2 | FAST, MEDIUM SLOW1, 2 | 0.3 ms 55 ms (50 Hz line frequency setting)/ 49 ms (60 Hz line frequency setting) | 0.3 ms 55 ms (50 Hz line frequency setting)/ 49 ms (60 Hz line frequency setting) |

*1: About t4 measurement time

• Even when Averaging is enabled, in the free-run state the moving average is calculated, so measurement time t4 is unchanged.

• Non-free-run calculation (:INITiate:CONTinuous ON;:TRIGger:SOURce IMMediate) times t4 are as follows: (n = samples to average)

| | | Offset Voltage Compensation (OVC) OFF | Offset Voltage Compensation (OVC) ON |
|-----------------------|-------------------------------------|---|--|
| t4 Measuremer Time | nt FAST MEDIUM SLOW1 SLOW2 | 0.33 ms x n+80 μs 20 ms x n (50 Hz) 16.7 ms x n (60 Hz) 100 ms x n 400 ms x n | 0.67 ms x n + t3 + 80 μs 40 ms x n + t3 (50 Hz) 33.3 ms x n + t3 (60 Hz) 200 ms x n + (2n-1)t3 800 ms x n + (8n-1)t3 |

*2: About t5 calculation time In the following cases, add the indicated times to calculation time t5:

| When the BIN Measurement function is enabled | 0.08 ms |
|---|---------|
| When the Temperature Correction function is enabled | 0.22 ms |
| When the Statistical Calculation function is enabled | 0.3 ms |
| When BCD external I/O is selected | 0.08 ms |
| When the reference value/tolerance method of comparator decision is selected | 0.15 ms |
| When the measured value is printed | 0.5 ms |

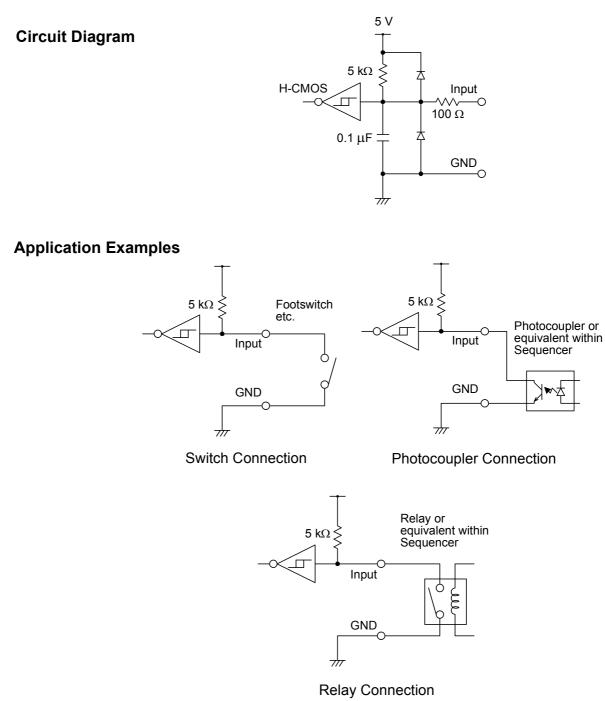
5.3 Averaging Function (Page 57)
5.11 Trigger Function (Page 68)

6.4 Internal Circuitry

External Control and External Output Terminal Ratings

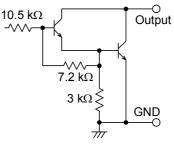
| | I/O type | Logic | Electrical specification |
|---------|-----------------------|---------------|--------------------------------|
| Output | Open collector | | 35 VDC, 50 mA DC max. |
| Input | C-MOS | Inverse logic | H: 3.8 to 5.0 V, L: 0 to 1.2 V |
| INT.DCV | Internal power output | | 5 VDC ±10%, 200 mA max. |

External Control Terminals



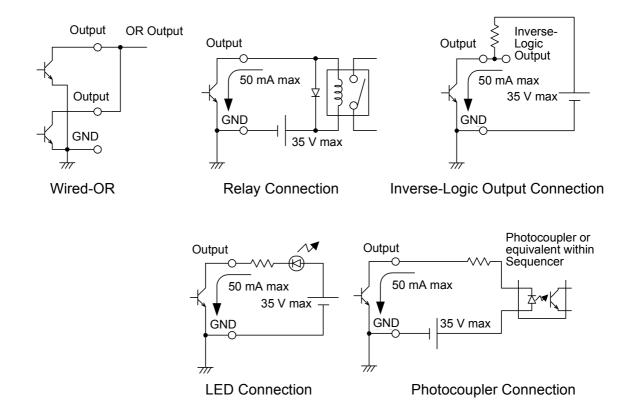
External Output Terminals

Circuit Diagram



Open-Collector Output

Application Examples



Printer(Optional) Chapter 7

7.1 About Printing

The following items can be printed using the optional Model 9670 PRINTER, 9638 RS-232C CABLE, 9671 AC ADAPTER and 9237 RECORDING PAPER:

- · Measurement values and decision results
- · Statistical calculation results

The following items are required to use the 9670 PRINTER.

- Model 9670 PRINTER (Sanei Electric Model BL-80RSII, supplied with a roll of thermal paper)
- Model 9671 AC ADAPTER (Sanei Electric Model BL-100W)
- Model 9237 RECORDING PAPER (thermal paper 80 x 25 m, 4 rolls)
- Model 9638 RS-232C CABLE

To use the printer with a battery:

- Model 9672 BATTERY PACK (Sanei Electric UR-100 or UR-121)
- Model 9673 BATTERY CHARGER (Sanei Electric NC-LSC01)

NOTE

- The 9670 PRINTER does not include a charging function for the 9672 BATTERY PACK. Use the 9673 BATTERY CHARGER to charge it.
- Read the manuals supplied with the printer and battery charger for the operating procedures.
- As much as possible, avoid printing in hot and humid environments. Otherwise, printer life may be severely shortened.
- Please use only the specified recording paper. Using non-specified paper may not only result in faulty printing, but printing may become impossible.
- If the recording paper is skewed on the roller, paper jams may result.
- Printing is not possible if the front and back of the recording paper are reversed.

7.2 Printer Connection

?\WARNING

Because electric shock and instrument damage hazards are present, always follow the steps below when connecting the printer.

- Always turn off the instrument and the printer before connecting.
- A serious hazard can occur if a wire becomes dislocated and contacts another conductor during operation. Make certain connections are secure.

<u>A</u>CAUTION

- To avoid damaging the instrument and printer, do not connect and disconnect the connectors when the power is on.
- If using a cable other than the 9638 RS-232C CABLE, the connector at the instrument end should be a molded type. The metal type (with hooks preventing the surface from being flat) will not fit due to the instrument's design.

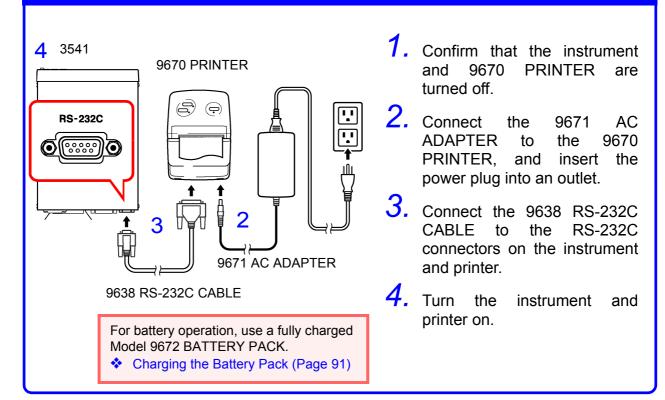
NOTE

The requirements for a printer to be connected to the instrument are as follows.

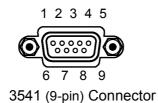
Confirm compatibility and make the appropriate settings on the printer before connecting it to the instrument.

- Interface RS-232C
- Characters per line At least 40
- Communication speed..... 19200 bps
- Data bits 8
- Parity none
- Stop bits..... 1
- Flow control none

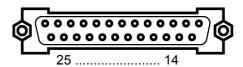




Connector Pinouts



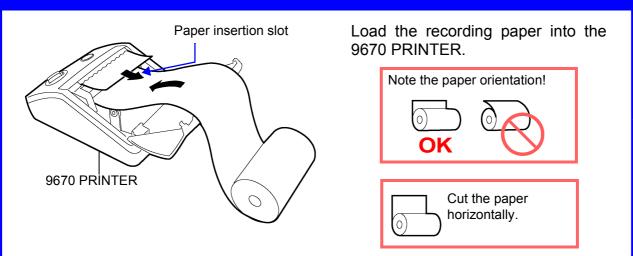
| Function | Signal Name | Pin | |
|-------------------------|----------------|-----|----------|
| Receive Data | RxD | 2 | 0 |
| Transmit Data | TxD | 3 | 0 |
| Signal or Common Ground | GND | 5 | o |
| | | | <u>о</u> |
| | | | <u> </u> |



9670 (25-pin) Connector

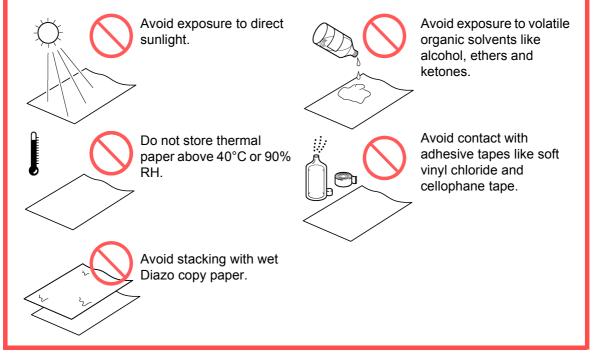
| | Pin | Signal Name | Function |
|----|-----|----------------|-------------------------|
| -0 | 2 | TxD | Transmit Data |
| -0 | 3 | RxD | Receive Data |
| -0 | 7 | GND | Signal or Common Ground |
| _0 | 4 | RTS | Request to Send |
| Lo | 5 | CTS | Clear to Send |

Loading Recording Paper



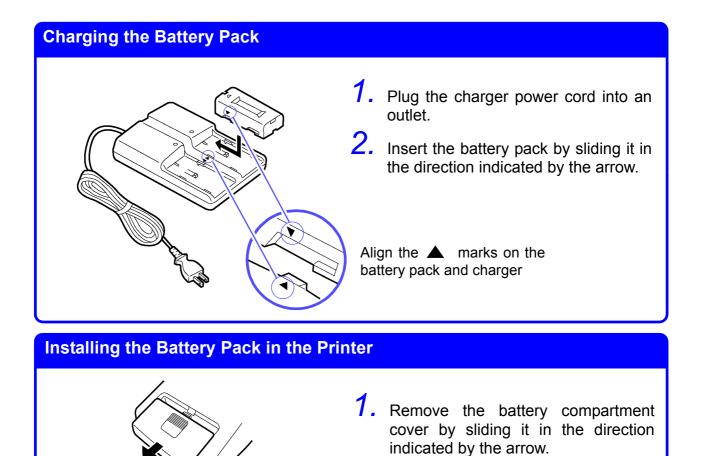
Handling and Storing Recording Paper

The recording paper is thermally and chemically sensitized. Observe the following precautions to avoid paper discoloration and fading.



NOTE

- Store thermal paper where its temperature will not exceed 40°C.
- The paper will deteriorate if exposed to light for a long time, so do not remove rolls from their wrappers until ready to use.
- Make photocopies of recording printouts that are to be handled or stored for legal purposes.

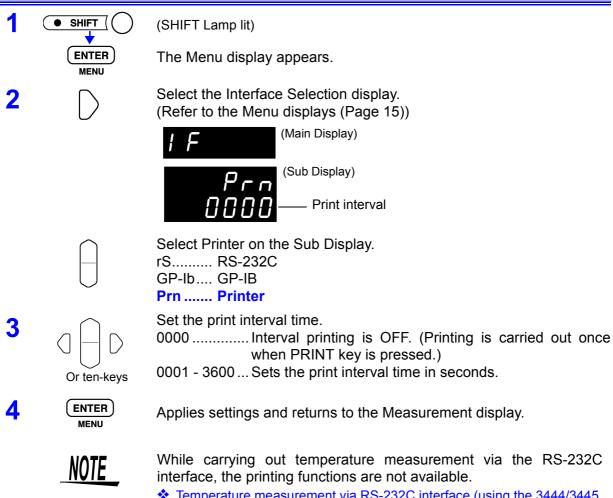


Battery Pack

2. Install the battery pack with its arrow pointing as shown at the left.

7.3 Interface Selection

Set the Instrument Interface selection to Printer



Temperature measurement via RS-232C interface (using the 3444/3445 TEMPERATURE HITESTER+ 3909 INTERFACE PACK) (Page 34)

7.4 Setting of the 9670 PRINTER

Turn the 9670 PRINTER on while holding the **FEED** button. Then press **SELECT** to set as needed according to print results.

The settings are as follows:

- International char = Japan
- Print mode = Graphic
- Character set = 24Dot ANK Gothic type
- Select switch = Enabled (ON) Baud rate =19200 bps
- Bit length = 8 bits
- Parity = None
- Data control = SBUSY
- Paper selection = Normal paper
 - Upright/inverted = Upright printing
- Auto power off = Enabled (ON) [as needed]
- Battery mode = Disabled (OFF) [as needed]

7.5 Printing

Printing Measured Values and Decision Results

From the Measurement display, press the PRINT key or ground the PRINT pin in the EXT I/O connector to print the measured value and decision result.



- When using the external trigger, if you want to print after a triggered measurement finishes, connect the EOC signal of the External I/O to the PRINT signal.
- To print all measurements continuously, connect the EOC signal to the PRINT signal and enable the internal trigger.

Interval printing

This function allows you to automatically print out measurement results at preset intervals. The print interval time must be set from the Interface Selection display.

7.3 Interface Selection (Page 92)

The setting range is 1 to 3600 seconds. When the print interval time is set to "0", interval printing is disabled, and only normal printing is carried out.

Operation when interval printing is selected

- Start printing by pressing the PRINT key or sending the PRINT signal via EXT I/O.
- Elapsed time (hours/minutes/seconds) and measurement values are printed automatically at intervals corresponding to the preset interval time.
- Stop printing by pressing the PRINT key or sending the PRINT signal via EXT I/O again.



When the actual time has exceeded 99 hours, the elapsed time information will be fixed to 99 hours.

Printing Statistical Calculation Results_

From the Statistical Calculation display, press the PRINT key to print statistical calculation results. If no valid data exists, only the data count is printed. When only one valid data sample exists, standard deviation of sample and process capability indices cannot be printed.

Example Printouts _____

| Resistance measurements | With BIN ON | Temperature measurements | | |
|--|---|--|--|--|
| 38.418mOhm 38.55mOhm 0.0403 Ohm 0.06 Ohm - 0.498kOhm 19.9950kOhm 10.0117MOhm | 1200.06 Ohm 0 1200.16 Ohm 45 1200.19 Ohm 6 1200.12 Ohm 23 1200.26 Ohm 9 | 0.7 C 7.2 C 73.7 C - 0.8 C - 7.3 C - 75.5 C | | |
| | With ∆T ON | | | |
| With the Comparator ON | 119.1 C | Interval print | | |
| 109.558MOhm Hi 109.542MOhm IN 109.546MOhm Lo 0.F. Hi - 0.F. Lo | - 63.8 C With erroneous measurement values | 00:00:00431.95mOhm00:00:01431.95mOhm00:00:02431.95mOhm00:00:03431.95mOhm00:00:04431.94mOhm00:00:05431.95mOhm | | |
| With the REF/% comparator function 11.222 % Hi - 0.100 % IN | O.F. - O.F. Invalid CurrErr Sens Hi | | | |

Sens Lo

Statistical Calculations (Comparator ON)

- 90.805 % Lo

| Number | 11 | |
|---------|-----------------|--|
| Valid | 10 | |
| Average | 1200.16 Ohm | |
| Max | 1200.20 Ohm(9) | |
| Min | 1200.13 Ohm(1) | |
| Sn | 24.104mOhm | |
| Sn-1 | 25.408mOhm | |
| Ср | 0.19 | |
| СрК | 0.03 | |
| | | |
| Comp Hi | 4 | |
| Comp IN | 6 | |
| Comp Lo | 0 | |

Statistical Calculations (BIN ON)

| | | | • | , |
|---------|------|------|----------|-----|
| Number | | 12 | | |
| Valid | | 11 | | |
| Average | 1209 | 9.25 | Ohm | |
| Max | 1300 |).15 | o Ohm (| 12) |
| Min | 1200 | 0.10 |) Ohm(| 9) |
| Sn | 28. | .744 | Ohm | |
| Sn-1 | 30. | .147 | Ohm (| |
| Ср | (| 0.00 |) | |
| СрК | (| 0.00 |) | |
| | | | | |
| 1200.06 | Ohm | to | 1200.08 | Ohm |
| 1200.08 | Ohm | to | 1200.10 | Ohm |
| 1200.10 | Ohm | to | 1200.12 | Ohm |
| 1200.12 | Ohm | to | 1200.14 | Ohm |
| 1200.14 | Ohm | to | 1200.16 | Ohm |
| 1200.16 | Ohm | to | 1200.18 | Ohm |
| 1200.18 | Ohm | to | 1200.20 | Ohm |
| 1200.20 | Ohm | to | 1200.22 | Ohm |
| 1200.22 | Ohm | to | 1200.24 | Ohm |
| 1200.24 | Ohm | to | 1200.26 | Ohm |
| | Out | of | BIN | |
| | T | | a | |

Invalid

Chapter 8

RS-232C/GP-IB Interfaces

This chapter describes the GP-IB and RS-232C interfaces, using the following symbols to indicate which information pertains to each interface. Sections with neither of these symbols pertain to both interfaces.



Before Use

- Always make use of the connector screws to affix the GP-IB or RS-232C connectors.
- When issuing commands that contain data, make certain that the data is provided in the specified format.

8.1 Overview and Features

All instrument functions other than power on/off switching can be controlled via GP-IB/RS-232C interfaces.

Resetting is supported.

GP-IB

- IEEE 488.2-1987 Common (essential) Commands are supported.
 Complies with the following standard:
 - Applicable standard IEEE 488.1-1987^{*1}
- This instrument is designed with reference to the following standard: Reference standard IEEE 488.2-1987^{*2}
- If the output queue becomes full, a query error is generated and the output queue is cleared. Therefore, clearing the output queue and query error output from the deadlocked condition^{*3} as defined in IEEE 488.2 is not supported.



While carrying out temperature measurement via the RS-232C interface, the RS-232C/GP-IB communication functions are not available.

- Temperature measurement via RS-232C interface (using the 3444/3445 TEMPERATURE HITESTER+ 3909 INTERFACE PACK) (Page 34)
- *1. ANSI/IEEE Standard 488.1-1987, IEEE Standard Digital Interface for Programmable Instrumentation.
- *2. ANSI/IEEE Standard 488.2-1987, IEEE Standard Codes, Formats, Protocols, and Common Commands.
- *3. The situation in which the input buffer and the output queue become full, so that processing cannot continue.

8.2 Specifications

8.2.1 RS-232C Specifications

RS-232C

| Transfer method | Communications: Full duplex Synchronization: Start-stop synchronization |
|-----------------------------------|---|
| Baud rate | 9600 bps |
| Data length | 8 bit |
| Parity | none |
| Stop bit | 1 bit |
| Message terminator (delimiter) | Receiving: CR+LF, CR Transmitting: CR+LF |
| Flow control | none |
| Electrical specification | Input voltage levels 5 to 15 V : ON -15 to -5 V: OFF Output voltage levels 5 to 9 V : ON -9 to -5 V: OFF |
| Connector | RS-232C Interface Connector Pinout (Male 9-pin D-sub, with #4-40 attachment screws) The I/O connector is a DTE (Data Terminal Equipment) configuration Recommended cables: Model 9637 RS-232C CABLE (for PC/AT-compatibles) Model 9638 RS-232C CABLE (for PC98-series) & 8.3.1 Attaching the Connector (Page 97) |

8.2.2 GP-IB Specifications



Interface Functions

| SH1 | All Source Handshake functions are supported. |
|---------|--|
| AH1 | All Acceptor Handshake functions are supported. |
| Т6 | Basic talker functions are supported. Serial poll function are supported. No talk-only mode. The talker cancel function with MLA (My Listen Address) is supported. |
| L4 | Basic listener functions are supported. No listen-only mode. The listener cancel function with MTA (My Talk Address) is supported. |
| SR1 | All Service Request functions are supported. |
| RL1 | All Remote/Local functions are supported. |
| PP0 | No Parallel Poll function. |
| DC1 | All Device Clear functions are supported. |
| DT1 | All Device Trigger functions are supported. |
| C0 | No Controller functions are supported. |
| Onerati | na Code: ASCII codes |

Operating Code: ASCII codes

8.3 Connections and Protocol Selection

8.3.1 Attaching the Connector



- Always turn both devices OFF when connecting and disconnecting an interface connector. Otherwise, an electric shock accident may occur.
- To avoid damage to the product, do not short-circuit the terminal and do not input voltage to the terminal.



After connecting, always tighten the connector screws. If the connector is not secured, operation may fail to meet specifications, and damage could result.

RS-232C

RS-232C Connector



Connect the RS-232C cable.

Male 9-pin D-sub #4-40 attaching screws To connect the instrument to a controller (DTE), use a <u>crossover cable</u> compatible with the connectors on both the instrument and the controller.

The I/O connector is a DTE (Data Terminal Equipment) configuration. This instrument uses only pins 2, 3 and 5. The other pins are unconnected.

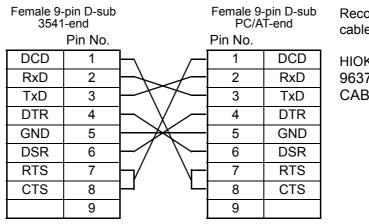
| Pin | Mutual connection circuit name | | CCITT | EIA | JIS | Signal |
|-----|--------------------------------|------------------------|-------------|---------------|---------------|--------|
| No. | | | Circuit No. | Code Addr. | Code Addr. | Name |
| 1 | unused | | | | | |
| 2 | Receive Data | Receive Data | 104 | BB | RD | RxD |
| 3 | Transmit Data | Send Data | 103 | BA | SD | TxD |
| 4 | Data Terminal Ready | Data Terminal Ready | 108/2 | CD | ER | DTR |
| 5 | Signal Ground | Signal Ground | 102 | AB | SG | GND |
| 6 | unused | | | | | |
| 7 | Request to Send | Request to Send | 105 | CA | RS | RTS |
| 8 | Clear to Send | Clear to Send | 106 | СВ | CS | CTS |
| 9 | unused | | | | | |



Connecting to a PC/AT-Compatible (DOS/V) Machine

Use a crossover cable with female 9-pin D-sub connectors.

Crossover Wiring



Recommended cable:

HIOKI 9637 RS-232C CABLE (1.8 m)

Connecting to an NEC PC9801 or PC9821 **Series Desktop PC** (excluding NX)

Use a crossover cable with a female 9-pin D-sub and a male 25-pin D-sub connector.

As the figure shows, RTS and CTS pins are shorted together and crossed to DCD in the other connector.

Crossover Wiring

| Female 9- 3541 | pin D-sub -end Pin No. | | Male 25-p PC-end Pin No. | in D-sub | Recommen cable: |
|-------------------|------------------------------|--------------------------------|--------------------------------|----------|--------------------|
| DCD | 1 | F~ | | | HIOKI |
| RxD | 2 | | 2 | TxD | 9638 RS-23 |
| TxD | 3 | \vdash | 3 | RxD | CABLE (1.8 |
| DTR | 4 | | 4 | RTS | |
| GND | 5 | \vdash \searrow \vdash | 5 | CTS | |
| DSR | 6 | \vdash \diagdown \succeq | 6 | DSR | |
| RTS | 7 | $\vdash \land \sim$ | 7 | GND | |
| CTS | 8 | \vdash \checkmark | 8 | DCD | |
| | 9 |] `_ | 20 | DTR | |
| | | - | | | |

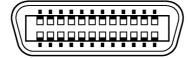
nded

32C 8 m)

Note that the combination of a dual male 25-pin D-sub cable and a 9to 25-pin adapter cannot be used.



GP-IB Connector



Connecting a GP-IB cable.

Recommended cable: 9151-02 GP-IB CONNECTOR CABLE (2 m) 9151-04 GP-IB CONNECTOR CABLE (4 m)

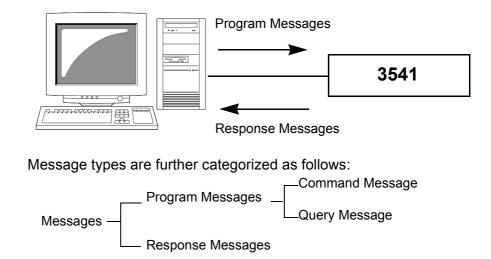
8.3.2 Communications Protocol Selection

Selecting the Interface 1 • SHIFT (SHIFT Lamp lit) ENTER The Menu display appears. MENU Select the Interface Selection display. 2 (Refer to the Menu displays (Page 15)) (Main Display) (Sub Display) Select RS-232C or GP-IB on the Sub Display. rS RS-232C GP-Ib ... GP-IB Prn Printer When selecting GP-IB, also set the Address and Message Terminator. (Sub Display) \Box i – Message Terminator setting (LF/CRLF) Address setting (0 to 30) Setting Selects the item to set 3 ENTER Applies settings and returns to the Measurement display. MENU While carrying out temperature measurement via the RS-232C NOTE interface, the RS-232C/GP-IB communication functions are not available. Temperature measurement via RS-232C interface (using the 3444/3445) TEMPERATURE HITESTER+ 3909 INTERFACE PACK) (Page 34)

8.4 Communication Methods

Various messages are supported for controlling the instrument through the interfaces.

Messages can be either program messages, sent from the PC to the instrument, or response messages, sent from the instrument to the PC.



8.4.1 Message Format

Program Messages

Program messages can be either Command Messages or Query Messages.

Command Messages

Instructions to control the instrument, such as to change settings or reset

Example: (instruction to set the measurement range)

| : RESISTANCE : RANGE | 100E3 |
|----------------------|-------|
|----------------------|-------|

| ↑ | ↑ ↑ | |
|----------------|--------------------|---|
| Header portion | Space Data portion | I |

Query Messages

Requests for responses relating to results of operation or measurement, or the state of instrument settings.

Example: (request for the current measurement range)

| :RESISTANCE:RANGE? | |
|--------------------|---------------|
| ≜ | |
| Header portion | Question Mark |

For details:Headers (Page 101), Separators (Page 102), Data Formats (Page 103)

8.4 Communication Methods

ResponseWhen a query message is received, its syntax is checked and a
response message is generated.

The ":SYSTem:HEADer" command determines whether headers are prefixed to response messages.

Header ON :RESISTANCE:RANGE 110.000E+03 Header OFF 110.000E+03 (the current resistance measurement range is 100 k Ω) At power-on, Header OFF is selected. If an error occurs when a query message is received, no response message is generated for that query. No header is applied to commands used only for queries, such as :FETCH? and :CALCulate:LIMit:RESult?.

Command Syntax Command names are chosen to mnemonically represent their function, and can be abbreviated. The full command name is called the "long form", and the abbreviated name is called the "short form". The command references in this manual indicate the short form in upper-case letters, extended to the long form in lower case letters, although the commands are not case-sensitive in actual usage.

| FUNCTION | OK (long form) |
|------------|-----------------|
| FUNC | OK (short form) |
| FUNCT | Error |
| FUN | Error |
| Response m | essages generat |

Response messages generated by the instrument are in long form and in upper case letters.

Headers Headers must always be prefixed to program messages.

(1) Command Program Headers

There are three types of commands: Simple, Compound and Standard.

- Headers for Simple Commands
 This header type is a sequence of letters and digits
 ESE 0
- Headers for Compound Commands

These headers consist of multiple simple command type headers separated by colons ":"

:SAMPle:RATE

Headers for Standard Commands
 This header type begins with an asterisk "*",
 indicating that it is a standard command defined by IEEE 488.2.
 *RST

(2) Query Program Header

These commands are used to interrogate the instrument about the results of operations, measured values and the current states of instrument settings.

As shown by the following examples, a query is formed by appending a question mark "?" after a program header.

:FETCh?

:MEASure:RESistance?

8.4 Communication Methods

Message Terminators

This instrument recognizes the following message terminators:

GP-IB

• LF

- **RS-232C** • CR
 - CR+LF

- CR+LFEOI
- LF with EOI

From the instrument's interface settings, the following can be selected as the terminator for response messages.

GP-IB

RS-232C

CR + LF (initial setting)

- LF with EOI (initial setting)
- LF with CR and EOI
- Interface setting: 8.3.2 Communications Protocol Selection (Page 99)

Separators

(1) Message Unit Separator

Multiple message can be written in one line by separating them with semicolons ";".

:SYSTEM:LFREQUENCY 60; *IDN?

- When messages are combined in this way and if one command contains an error, all subsequent messages up to the next terminator will be ignored.
- A query error occurs if a query command is combined with an immediately following semicolon and subsequent command.

(2) Header Separator

In a message consisting of both a header and data, the header is separated from the data by a space " ".

:SYSTEM:OVC V

(3) Data Separator

In a message containing multiple data items, commas are required to separate the data items from one another.

:CALCULATE:BIN:UPPER 3,100000

- **Data Formats** The instrument uses character data and decimal numeric data, depending on the command.
- (1) Character Data

Character data always begins with an alphabetic character, and subsequent characters may be either alphabetic or numeric. Character data is not case-sensitive, although response messages from the instrument are only upper case.

:SYSTEM:OVC ON

(2) Decimal Numeric Data

Three formats are used for numeric data, identified as NR1, NR2 and NR3. Numeric values may be signed or unsigned. Unsigned numeric values are handled as positive values.

Values exceeding the precision handled by the instrument are rounded to the nearest valid digit.

- NR1 Integer data (e.g.: +12, -23, 34)
- NR2 Fixed-point data(e.g.: +1.23, -23.45, 3.456)
- NR3 Floating-point exponential representation data (e.g.: +1.0E-2, -2.3E+4)

The term "NRf format" includes all three of the above numeric decimal formats.

The instrument accepts NRf format data.

The format of response data is specified for each command, and the data is sent in that format.

:ESR0 106 :FETCH? +106.571



The instrument does not fully support IEEE 488.2. As much as possible, please use the data formats shown in the Reference section. Also, be careful to avoid constructing single commands that could overflow the input buffer or output queue.

Compound Command Header Omission

When several commands having a common header are combined to form a compound command (e.g., :CALCulate: LIMit:UPPer and :CALCulate:LIMit:LOWer), if they are written together in sequence, the common portion (here, :CALCulate:LIMit) can be omitted after its initial occurrence.

This common portion is called the "current path" (analogous to the path concept in computer file storage), and until it is cleared, the interpretation of subsequent commands presumes that they share the same common portion.

This usage of the current path is shown in the following example:

Full expression

:CALCulate:LIMit:UPPer 110000;:CALCulate:LIMit:LOWer 90000

Compacted expression

:CALCulate:LIMit:UPPer 110000;LOWer 90000

This portion becomes the current path, and can be omitted from the messages immediately following.

The current path is cleared when the power is turned on, when reset by key input, by a colon ":" at the start of a command, and when a message terminator is detected.

Standard command messages can be executed regardless of the current path.

They have no effect upon the current path.

A colon ":" is not required at the start of the header of a Simple or Compound command. However, to avoid confusion with abbreviated forms and operating mistakes, we recommend always placing a colon at the start of a header.

In this instrument, the current path is as follows (for both GP-IB and RS-232C):

:CALCulate:LIMit:

8.4.2 Output Queue and Input Buffer

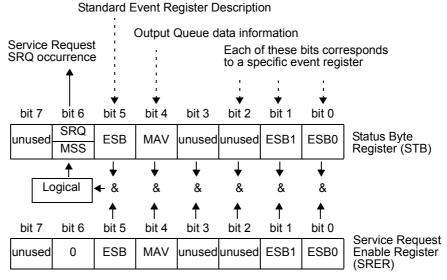
| Output Queue | Response messages are stored in the output queue until read by the controller. The output queue is also cleared in the following circumstances: Power on Device clear Power on Query Error |
|--------------|--|
| | The output queue capacity of the instrument is 64 bytes. If response messages overflow the buffer, a query error is generated and the output queue is cleared. Also, with GP-IB, if a new message is received while data remains in the output queue, the output queue is cleared and a query error is generated. |
| Input Buffer | The input buffer capacity of the instrument is 256 bytes. If 256 bytes are allowed to accumulate in this buffer so that it becomes full, the GP-IB interface bus enters the waiting state until space is cleared in the buffer. The RS-232C interface will not accept data beyond 256 bytes. |
| | Ensure that the ne command over exceeds 256 bytes |



Ensure that the no command ever exceeds 256 bytes.

8.4.3 Status Byte Register

This instrument implements the status model defined by IEEE 488.2 with regard to the serial poll function using the service request line. The term "event" refers to any occurrence that generates a service request.



Overview of Service Request Occurrence

The Status Byte Register contains information about the event registers and the output queue. Required items are selected from this information by masking with the Service Request Enable Register. When any bit selected by the mask is set, bit 6 (MSS; the Master Summary Status) of the Status Byte Register is also set, which generates an SRQ (Service Request) message and dispatches a service request.

Status Byte Register (STB)

During serial polling, the contents of the 8-bit Status Byte Register are sent from the instrument to the controller.

When any Status Byte Register bit enabled by the Service Request Enable Register has switched from 0 to 1, the MSS bit becomes 1. Consequently, the SRQ bit is set to 1, and a service request is dispatched.

The SRQ bit is always synchronous with service requests, and is read and simultaneously cleared during serial polling. Although the MSS bit is only read by an ***STB**? query, it is not cleared until a clear event is initiated by the ***CLS** command.

| Bit 7 | unused |
|-------|--|
| Bit 6 | |
| SRQ | Set to 1 when a service request is dispatched. |
| MSS | This is the logical sum of the other bits of the Status Byte Register. |
| Bit 5 | Standard Event Status (logical sum) bit |
| ESB | This is logical sum of the Standard Event Status Register. |
| Bit 4 | Message available |
| MAV | Indicates that a message is present in the output queue. |
| Bit 3 | unused |
| Bit 2 | unused |
| Bit 1 | Event Status (logical sum) bit 1 |
| ESB1 | This is the logical sum of Event Status Register 1. |
| Bit 0 | Event Status (logical sum) bit 0 |
| ESB0 | This is the logical sum of Event Status Register 0. |

Service Request Enable Register (SRER)

This register masks the Status Byte Register. Setting a bit of this register to 1 enables the corresponding bit of the Status Byte Register to be used.

8.4.4 Event Registers

Standard Event Status Register (SESR)

The Standard Event Status Register is an 8-bit register. If any bit in the Standard Event Status Register is set to 1 (after masking by the Standard Event Status Enable Register), bit 5 (ESB) of the Status Byte Register is set to 1.

Standard Event Status Register (SESR) and Standard Event Status Enable Register (SESER) (Page 109)

The Standard Event Status Register is cleared in the following situations:

- When a ***CLS** command is executed
- When an event register query (*ESR?) is executed
- When the instrument is powered on

| Bit 7 | PON | Power-On Flag |
|-------|-----|---|
| | | Set to 1 when the power is turned on, or upon recovery from an outage. |
| Bit 6 | | User Request |
| | | unused |
| Bit 5 | CME | Command error. (The command to the message terminator is ignored.) |
| | | This bit is set to 1 when a received command contains a syntactic or semantic error: • Program header error |
| | | Incorrect number of data parameters |
| | | Invalid parameter format |
| | | Received a command not supported by the instrument |
| Bit 4 | EXE | Execution Error |
| | | This bit is set to 1 when a received command cannot be executed for some reason. |
| | | The specified data value is outside of the set range The specified setting data separat he set |
| | | The specified setting data cannot be set Execution is prevented by some other operation being performed |
| Bit 3 | DDE | |
| BILS | DDE | Device-Dependent Error |
| | | This bit is set to 1 when a command cannot be executed due to some reason other than a command error, a query error or an execution error. |
| | | Execution is impossible due to an internal instrument fault |
| Bit 2 | QYE | Query Error (the output queue is cleared) |
| | | This bit is set to 1 when a query error is detected by the output queue control. When an attempt has been made to read an empty output queue (GP-IB only) When the data overflows the output queue When data in the output queue has been lost |
| Bit 1 | | unused |
| Bit 0 | OPC | Operation Complete (GP-IB only) |
| | | This bit is set to 1 in response to an *OPC command.It indicates the completion of operations of all messages up to the *OPC command |

8.4 Communication Methods

Standard Event Status Enable Register (SESER)

Setting any bit of the Standard Event Status Enable Register to 1 enables access to the corresponding bit of the Standard Event Status Register.

Standard Event Status Register (SESR) and Standard Event Status Enable Register (SESER)

| bit 6 | bit 5 | bit 4 | | | | | | | | |
|------------|---------|-------|-------|---------------------------------------|-------|-------|-------|-------|-------|-------|
| SRQ MSS | | MAV | | Standard Event Status Register (SESR) | | | | | | |
| | Î | | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | | | PON | URQ | CME | EXE | DDE | QYE | RQC | OPC |
| | Logical | | ¥ | ↓ | ↓ | ↓ | ↓ | ↓ | ↓ | ↓ |
| | sum | | & | & | & | & | & | & | & | & |
| - | | | ↑ | ↑ | ↑ | ↑ | ↑ | ↑ | ↑ | 1 |
| | | | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | | | PON | URQ | CME | EXE | DDE | QYE | RQC | OPC |

Standard Event Status Enable Register (SESER)

Device-Specific Event Status Registers (ESR0 and ESR1)

This instrument provides two event status registers for controlling events.

Each event register is an 8-bit register.

When any bit in one of these event status registers enabled by its corresponding event status enable register is set to 1, the following happens:

- For Event Status Register 0, bit 0 (ESB0) of the Status Byte Register is set to 1.
- For Event Status Register 1, bit 1 (ESB1) of the Status Byte Register is set to 1.

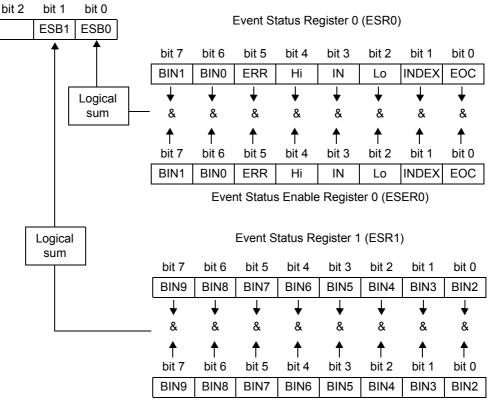
Event Status Registers 0 and 1 are cleared in the following situations:

- When a *CLS command is executed
- When an Event Status Register query (:ESR0? or :ESR1?) is executed
- · When the instrument is powered on

| | Event Status Register 0 (ESR0) | | Event Status Register 1 (ESR1) | |
|-------|--------------------------------|------------------------|-----------------------------------|------|
| Bit 7 | BIN1 | BIN1 | BIN9 | BIN9 |
| Bit 6 | BIN0 | BIN0 | BIN8 | BIN8 |
| Bit 5 | ERR | Measurement Fault | BIN7 | BIN7 |
| Bit 4 | Hi | High Comparator Result | BIN6 | BIN6 |
| Bit 3 | IN | IN Comparator Result | BIN5 | BIN5 |
| Bit 2 | Lo | Low Comparator Result | BIN4 | BIN4 |
| Bit 1 | INDEX | End of Measurement | BIN3 | BIN3 |
| Bit 0 | EOC | End of Conversion | BIN2 | BIN2 |

Event Status Registers 0 (ESR0) and 1 (ESR1), and Event Status Enable Registers 0 (ESER0) and 1 (ESER1)

Status Byte Register (STB)



Event Status Enable Register 1 (ESER1)

Register Reading and Writing

| Register | Read | Write |
|---------------------------------------|--------|-------|
| Status Byte Register | *STB? | _ |
| Service Request Enable Register | *SRE? | *SRE |
| Standard Event Status Register | *ESR? | _ |
| Standard Event Status Enable Register | *ESE? | *ESE |
| Event Status Register 0 | :ESR0? | _ |
| Event Status Enable Register 0 | :ESE0? | :ESE0 |
| Event Status Register 1 | :ESR1? | _ |
| Event Status Enable Register 1 | :ESE1? | :ESE1 |

GP-IB Commands

The following commands can be used for performing interface functions.

| Command | Description | |
|---------|--------------------------|--|
| GTL | Go To Local | Cancels the Remote state and enters the Local state. |
| LLO | Local Lock Out | Disables all keys, including the LOCAL key. |
| DCL | Device CLear | Clears the input buffer and the output queue. |
| SDC | Selected Device Clear | Clears the input buffer and the output queue. |
| GET | Group Execute Trigger | When an external trigger occurs, processes one sample. |

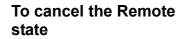
8.4.5 Initialization Items

| | ● = initialized, - = not initialized | | | |
|--|--------------------------------------|---------|--------|---------|
| Initialization Method | At Power- | *RST | Device | *CLS |
| Item | on | Command | Clear | Command |
| Device-specific functions (Range, etc.) | | • | - | _ |
| Output Queue | • | — | • | - |
| Input buffer | • | _ | • | - |
| Status Byte Register | • | _ | - *1 | • *2 |
| Event registers | • *3 | — | _ | • |
| Enable register | • | _ | | - |
| Current path | • | _ | • | _ |
| Headers on/off | • | • | _ | _ |

- *1 Only the MAV bit (bit 4) is cleared.
- *2 All bits except the MAV bit are cleared.
- *3 Except the PON bit (bit 7).

8.4.6 Local Function

During communications, **REMOTE** is lit to indicate the remote control state.







If the Local Lock Out (Page 110) GP-IB command has been issued, the Remote state cannot be canceled.

8.5 Message List

Commands specific to RS-232C or GP-IB are identified by RS-232C or GP-IB , respectively.

- Any spelling mistake in a message results in a command error. • < > = contents of the data portion
 - < > = contents of the data portion. [Numeric data values are indicated by format as (NR1), (NR2) and (NR3), representing integer, fixed-point and floating point decimal data values respectively, or as (NRf), representing any of these formats]
 - []: optional

8.5.1 Standard Commands

| Command | Data Formats (Response data if a Query) | Description | Error | Ref page |
|---------|--|--|-------|-------------|
| *CLS | | Clears the event registers and the Status Byte Register | *1 | 120 |
| *ESE | 0 to 255 (NR1) | Sets the contents of the Standard Event Status Enable Register | *3 | 121 |
| *ESE? | 0 to 255 (NR1) | Queries the Standard Event Status Enable Register | *2 | 121 |
| *ESR? | 0 to 255 (NR1) | Queries the Standard Event Status Register | *2 | 121 |
| *IDN? | <manufacturer's name>,<model name>,0,<software version></software </model </manufacturer's | Queries the Device ID. | *2 | 119 |
| *OPC | <u> </u> | Requests an SRQ after execution completion | *1 | 120 |
| *OPC? | 1 | Queries execution completion | *2 | 120 |
| *RST | | Initializes the device | *1 | 119 |
| *SRE | 0 to 255 (NR1) | Sets the Service Request Enable Register | *3 | 122 |
| *SRE? | 0 to 255 (NR1) | Queries the contents of the Service Request Enable Register | *2 | 122 |
| *STB? | 0 to 255 (NR1) | Queries the Status Byte Register | *2 | 122 |
| *TRG | | Executes one sampling | *1,4 | 122 |
| *TST? | 0 to 3 (NR1) | Initiates a self-test and queries the result | *2 | 119 |
| *WAI | | Wait for operations to finish | *1 | 120 |

Error description (an error occurs when executing messages in the following cases):

*1 Command Error When data is present after the command

- *2 Query Error.....When the response message exceeds 64 bytes
- *3 Execution Error......When invalid character or numeric data is present
- *4 Execution Error...... When the command is executed in internal trigger mode

8.5.2 Device-Specific Commands

| Message ([] = optional) | Data Contents () = response data | Description | Ref page |
|-----------------------------------|---|--|-------------|
| Event Registers | | | |
| :ESE0 | 0 to 255 | Sets Event Status Enable Register 0 | 123 |
| :ESE0? | (0 to 255) | Queries Event Status Enable Register 0 | 123 |
| :ESR0? | (0 to 255) | Queries Event Status Register 0 | 123 |
| :ESE1 | 0 to 255 | Sets Event Status Enable Register 1 | 123 |
| :ESE1? | (0 to 255) | Queries Event Status Enable Register 1 | 123 |
| :ESR1? | (0 to 255) | Queries Event Status Register 1 | 123 |
| Measurement functions | | | |
| [:SENSe:]FUNCtion | RESistance, LPResistance or TEMPerature | Function settings | 124 |
| [:SENSe:]FUNCtion? | (RESISTANCE, LPRESISTANCE or TEMPERATURE) | Function queries | 124 |
| Measurement Range | | | |
| [:SENSe:]LPResistance:RANGe | 0 to 2000 | Sets Low-Power Resistance measurement range | 124 |
| [:SENSe:]LPResistance:RANGe? | (2000.00E-3 to 2000.00E+0) | Queries the Low-Power Resistance measurement range setting | 124 |
| [:SENSe:]LPResistance:RANGe:AUTO | 1, 0, ON or OFF | Sets AUTO-ranging for Low-Power Resistance measurement | 125 |
| [:SENSe:]LPResistance:RANGe:AUTO? | (ON or OFF) | Queries the AUTO-ranging Low-Power Resistance measurement setting | 125 |
| [:SENSe:]RESistance:RANGe | 0 to 110E+6 | Sets the Resistance measurement range | 125 |
| [:SENSe:]RESistance:RANGe? | (20.0000E-3 to 110.000E+6) | Queries the Resistance measurement range | 125 |
| [:SENSe:]RESistance:RANGe:AUTO | 1, 0, ON or OFF | Sets AUTO-ranging Resistance measurement | 125 |
| [:SENSe:]RESistance:RANGe:AUTO? | (ON or OFF) | Queries the AUTO-ranging resistance measurement setting | 125 |
| Zero-Adjust | | | |
| :ADJust? | (0 or 1) | Execute Zero-Adjustment | 126 |
| :ADJust:CLEAr | | Cancels zero-adjustment | 126 |
| Measurement Terminals | | | |
| [:SENSe:]TERMinal | A or B | Selects the Measurement Terminals | 126 |
| [:SENSe:]TERMinal? | (A or B) | Queries the Measurement Terminal selection | 126 |
| Sampling rate | | | |
| :SAMPle:RATE | FAST, MEDium, SLOW1 or SLOW2 | Sets the Sampling Rate | 126 |
| :SAMPle:RATE? | (FAST, MEDIUM, SLOW1 or SLOW2) | Queries the Sampling Rate setting | 126 |

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8.5 Message List

:CALCulate:LIMit:BEEPer

| | Data Contents | D | Ref |
|--|--|---|------|
| Message ([] = optional) | () = response data | Description | page |
| Temperature Correction | | | |
| :CALCulate:TCORrect:STATe | 1, 0, ON or OFF | Set Temperature Correction execution | 127 |
| :CALCulate:TCORrect:STATe? | (ON or OFF) | Queries the Temperature Correction execution setting | 127 |
| :CALCulate:TCORrect:PARameter | <reference temp.="">, <temp. coefficient=""></temp.></reference> | Sets the Temperature Correction constant | 127 |
| :CALCulate:TCORrect:PARameter? | (<reference temp.="">, <temp. coefficient="">)</temp.></reference> | Queries the Temperature Correction constant setting | 127 |
| Temperature Conversion (∆t) | | | |
| :CALCulate:TCONversion:DELTa:STATe | 1, 0, ON or OFF | Set Temperature Conversion execution | 128 |
| :CALCulate:TCONversion:DELTa:STATe? | (ON or OFF) | Queries the Temperature Conversion execution setting | 128 |
| :CALCulate:TCONversion:DELTa:PARa meter | <initial resistance="">,<ini- tial Temp.>,<constant></constant></ini- </initial> | Sets the Temperature Conversion constant | 128 |
| :CALCulate:TCONversion:DELTa:PARa meter? | (<initial resistance="">, <initial temp.="">,<con- stant>)</con- </initial></initial> | Queries the Temperature Conversion constant setting | 128 |
| Averaging Function | | | |
| :CALCulate:AVERage | 2 to 100 | Sets the no. of samples to average | 129 |
| :CALCulate:AVERage? | (2 to 100) | Queries the no. of samples to average setting | 129 |
| :CALCulate:AVERage:STATe | 1, 0, ON or OFF | Sets Averaging function execution | 128 |
| :CALCulate:AVERage:STATe? | (ON or OFF) | Queries the Averaging function execution setting | 128 |
| Statistical Functions | | | |
| :CALCulate:STATistics:STATe | 1, 0, ON or OFF | Sets Statistical Calculation function execution | 129 |
| :CALCulate:STATistics:STATe? | (ON or OFF) | Queries the Statistical Calculation function execution setting | 129 |
| :CALCulate:STATistics:CLEAr | | Clears Statistical Calculation results | 129 |
| :CALCulate:STATistics:NUMBer? | (<total count="" data="">, <valid count="" data="">)</valid></total> | Queries the data count | 129 |
| :CALCulate:STATistics:MEAN? | (<mean>)</mean> | Queries the mean value | 129 |
| :CALCulate:STATistics:MAXimum? | (<maximum value="">, <data no.="">)</data></maximum> | Queries the maximum value | 129 |
| :CALCulate:STATistics:MINimum? | (<minimum value="">, <data no.="">)</data></minimum> | Queries the minimum value | 130 |
| :CALCulate:STATistics:LIMit? | (<hi count="">,<in count="">, <lo count="">, <measure- ment fault count>)</measure- </lo></in></hi> | Queries comparator results | 130 |
| :CALCulate:STATistics:BIN? | (<bin0 count="">,,<bin 9 count>,<out count="">, <measurement fault<br="">count>)</measurement></out></bin </bin0> | Queries BIN results | 130 |
| :CALCulate:STATistics:DEViation? | (<ơn>,<ơn-1>) | Queries standard deviation | 130 |
| :CALCulate:STATistics:CP? | (<cp>,<cpk>)</cpk></cp> | Queries the Process Capability Indices | 130 |
| Comparator | | | |
| :CALCulate:LIMit:STATe | 1, 0, ON or OFF | Sets comparator execution | 131 |
| :CALCulate:LIMit:STATe? | (ON or OFF) | Queries the comparator execution setting | 131 |
| | | | 101 |

OFF, HI or IN

Sets the beep sound

131

| Message ([] = optional) | Data Contents () = response data | Description | Ref page |
|-----------------------------|--|--|-------------|
| :CALCulate:LIMit:BEEPer? | (OFF, HI or IN) | Queries the beep sound setting | 131 |
| :CALCulate:LIMit:MODE | HL or REF | Selects the decision mode | 131 |
| :CALCulate:LIMit:MODE? | (HL or REF) | Queries the decision mode setting | 131 |
| :CALCulate:LIMit:UPPer | <upper threshold=""></upper> | Sets the upper threshold | 131 |
| :CALCulate:LIMit:UPPer? | (<upper threshold="">)</upper> | Queries the upper threshold setting | 131 |
| :CALCulate:LIMit:LOWer | <lower threshold=""></lower> | Sets the lower threshold | 131 |
| :CALCulate:LIMit:LOWer? | (<lower threshold="">)</lower> | Queries the lower threshold setting | 131 |
| :CALCulate:LIMit:REFerence | <reference resistance=""></reference> | Sets the reference resistance | 132 |
| :CALCulate:LIMit:REFerence? | (<reference resistance="">)</reference> | Queries the reference resistance setting | 132 |
| :CALCulate:LIMit:PERCent | <tolerance (%)=""></tolerance> | Sets the decision tolerance | 132 |
| :CALCulate:LIMit:PERCent? | (<tolerance (%)="">)</tolerance> | Queries the decision tolerance setting | 132 |
| :CALCulate:LIMit:RESult? | (HI, IN, LO, OFF or ERR) | Queries the decision result | 132 |

Setting and Querying BIN Measurements

| 1, 0, ON or OFF | Sets BIN measurement execution | 132 |
|--|--|---|
| (ON or OFF) | Queries the BIN execution state setting | 132 |
| < Enable Mask> | Sets the enable mask | 133 |
| (<enable mask="">)</enable> | Queries the Enable Mask setting | 133 |
| <bin no.="">,<hl or="" ref=""></hl></bin> | Sets the decision mode | 133 |
| <bin no.="">,(<hl or="" ref="">)</hl></bin> | Queries the decision mode setting | 133 |
| <bin no.="">,<upper threshold></upper </bin> | Sets the upper threshold | 133 |
| <bin no.="">,(<upper threshold>)</upper </bin> | Queries the upper threshold setting | 133 |
| <bin no.="">,<lower threshold></lower </bin> | Sets the lower threshold | 133 |
| <bin no.="">,(<lower threshold>)</lower </bin> | Queries the lower threshold setting | 133 |
| <bin no.="">,<reference resistance></reference </bin> | Sets the reference resistance | 134 |
| <bin no.=""> (<reference resistance="">)</reference></bin> | Queries the reference resistance setting | 134 |
| <bin no.="">,<tolerance (%)></tolerance </bin> | Sets the decision tolerance | 134 |
| <bin no.="">,(<tolerance (%)>)</tolerance </bin> | Queries the decision tolerance setting | 134 |
| 0 to 1023 | Sets the upper threshold | 134 |
| | (ON or OFF) < Enable Mask> (<enable mask="">) <bin no.="">,<hl or="" ref=""> <bin no.="">,<upper <bin no.="">,<upper <br< td=""><td>(ON or OFF)Queries the BIN execution state setting< Enable Mask>Sets the enable mask(<enable mask="">)Queries the Enable Mask setting<bin no.="">,<hl or="" ref="">Sets the decision mode<bin no.="">,<hl or="" ref="">Queries the decision mode setting<bin no.="">,<upper </upper threshold>Sets the upper threshold setting<bin no.="">,<upper </upper threshold>Queries the lower threshold setting<bin no.="">,<lower </lower threshold>Sets the lower threshold setting<bin no.="">,<lower </lower threshold>Queries the lower threshold setting<bin no.="">,<reference </reference resistance>Queries the lower threshold setting<bin no.="">,<reference </reference (%)>Queries the decision tolerance setting<bin no.="">,<reference </reference (%)>Sets the decision tolerance setting<bin no.="">,<tolerance< td="">Queries the decision tolerance setting<bin no.="">,<tolerance </tolerance (%)>Queries the decision tolerance setting</bin></tolerance<></bin></bin></bin></bin></bin></bin></bin></bin></hl></bin></hl></bin></enable></td></br<></br></br></br></br></upper </bin></upper </bin></hl></bin></enable> | (ON or OFF)Queries the BIN execution state setting< Enable Mask>Sets the enable mask(<enable mask="">)Queries the Enable Mask setting<bin no.="">,<hl or="" ref="">Sets the decision mode<bin no.="">,<hl or="" ref="">Queries the decision mode setting<bin no.="">,<upper </upper threshold>Sets the upper threshold setting<bin no.="">,<upper </upper threshold>Queries the lower threshold setting<bin no.="">,<lower </lower threshold>Sets the lower threshold setting<bin no.="">,<lower </lower threshold>Queries the lower threshold setting<bin no.="">,<reference </reference resistance>Queries the lower threshold setting<bin no.="">,<reference </reference (%)>Queries the decision tolerance setting<bin no.="">,<reference </reference (%)>Sets the decision tolerance setting<bin no.="">,<tolerance< td="">Queries the decision tolerance setting<bin no.="">,<tolerance </tolerance (%)>Queries the decision tolerance setting</bin></tolerance<></bin></bin></bin></bin></bin></bin></bin></bin></hl></bin></hl></bin></enable> |

Offset Voltage Compensation function

| :SYSTem:OVC | 1, 0, ON or OFF | Set Offset Voltage Compensation function execution | 134 |
|----------------------|--------------------|---|-----|
| :SYSTem:OVC? | (ON or OFF) | Query Offset Voltage Compensation function execution | 134 |
| Temperature measurem | ent (analog input) | | |
| | | | 405 |

| :SYSTem:TEMPerature:SENSor | PT or ANALog | Selects the temperature sensor type | 135 |
|-------------------------------|---|---|-----|
| :SYSTem:TEMPerature:SENSor? | (PT or ANALOG) | Queries the temperature sensor type selection | 135 |
| :SYSTem:TEMPerature:PARameter | <v1>,<t1>,<v2>,<t2></t2></v2></t1></v1> | Sets the analog input scaling constants | 135 |

8.5 Message List

| Message ([] = optional) | Data Contents | Description | Ref |
|--------------------------------|---|---|-------------|
| :SYSTem:TEMPerature:PARameter? | () = response data (<v1>,<t1>,<v2>, <t2>)</t2></v2></t1></v1> | Queries the analog input scaling constant | page 135 |
| | (<v12,<112,<v22,<122)< td=""><td>settings</td><td></td></v12,<112,<v22,<122)<> | settings | |
| Self-Calibration | | | |
| :SYSTem:CALibration | | Execute Self-Calibration | 136 |
| :SYSTem:CALibration:AUTO | 1, 0, ON or OFF | Sets automatic self-calibration | 136 |
| :SYSTem:CALibration:AUTO? | (ON or OFF) | Queries the automatic self-calibration setting | 136 |
| Key Beeper | | | |
| :SYSTem:BEEPer:STATe | 1, 0, ON or OFF | Sets the key beeper | 136 |
| :SYSTem:BEEPer:STATe? | (ON or OFF) | Queries the key beeper setting | 136 |
| Line Frequency | | | |
| :SYSTem:LFRequency | 50 or 60 | Selects the AC line frequency | 136 |
| :SYSTem:LFRequency? | (50 or 60) | Queries the AC line frequency selection | 136 |
| Key-Lock | | | |
| :SYSTem:KLOCk | 1, 0, ON or OFF | Sets the key-lock | 137 |
| :SYSTem:KLOCk? | (ON or OFF) | Queries the key-lock setting | 137 |
| Saving and Loading Measurem | ent Setting States | | |
| :SYSTem:SAVE | <table no.=""></table> | Saves the measurement setting state | 137 |
| :SYSTem:LOAD | <table no.=""></table> | Loads a measurement setting state | 137 |
| Header Present | | | |
| :SYSTem:HEADer | 1, 0, ON or OFF | Sets header present | 137 |
| :SYSTem:HEADer? | (ON or OFF) | Queries the header present setting | 137 |
| ERR Output | | | |
| :SYSTem:ERRor | SYNChronous or ASYNchronous | Sets error output timing | 137 |
| :SYSTem:ERRor? | (SYNCHRONOUS or ASYNCHRONOUS) | Queries the error output timing setting | 137 |
| External I/O Output | | | |
| :SYSTem:EXTernalout | BIN or BCD | Selects BIN or BCD | 138 |
| :SYSTem:EXTernalout? | (BIN or BCD) | Queries the external I/O output selection | 138 |
| Delimiter (Terminator) | | | |
| :SYSTem:TERMinator GP-IB | 0 or 1 | Sets the command delimiter | 138 |
| :SYSTem:TERMinator? | (0 or 1) | Queries the command delimiter setting | 138 |
| System Reset | | | |
| :SYSTem:RESet | | Executes a system reset, including saved measurement setting state data | 138 |

8.5 Message List

Reads the Temperature Measurement 145

| Message ([] = optional) | Data Contents () = response data | Description | Ref page |
|-------------------------|--------------------------------------|--|-------------|
| External I/O | | | |
| :IO:OUT | 0 to 255 | External I/O Output | 139 |
| :IO:IN? | (0 to 3) | External I/O Input | 139 |
| Trigger | | | |
| :INITiate:CONTinuous | 1, 0, ON or OFF | Sets continuous measurement | 142 |
| :INITiate:CONTinuous? | (ON or OFF) | Queries the continuous measurement setting | 142 |
| :INITiate[:IMMediate] | | Trigger wait setting | 142 |
| :TRIGger:SOURce | IMMediate or EXTernal | Sets the trigger source | 143 |
| :TRIGger:SOURce? | (IMMEDIATE or EXTERNAL) | Queries the trigger source setting | 143 |
| :TRIGger:DELay | <delay></delay> | Sets the trigger delay | 143 |
| :TRIGger:DELay? | (0 to 9.999) | Queries the trigger delay setting | 143 |
| :TRIGger:DELay:AUTO | 1, 0, ON or OFF | Sets automatic trigger delay | 143 |
| :TRIGger:DELay:AUTO? | (ON or OFF) | Queries the automatic trigger delay setting | 143 |
| Reading Measured Values | | | |
| :FETCh? | | Reads the Most Recent Measurement | 145 |
| :READ? | | Waits for trigger and reads the measured value | 145 |
| :MEASure:LPResistance? | <[Expected measure- ment value] > | Presets a specified low-power resistance range, and measures | 146 |
| :MEASure:RESistance? | <[Expected measure- ment value] > | Presets a specified resistance range, and measures | 146 |

:MEASure:TEMPerature?

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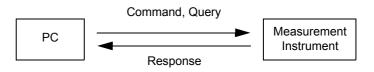
8.6 Message Reference

 Indicates the contents (character or numeric parameters) of the data portion of a message. Character parameters are returned as all capital letters.

Numeric Parameters:

- NRf Number format may be any of NR1, NR2 and NR3
- NR1 Integer data (e.g.: +12, -23, 34)
- NR2 Fixed-point data(e.g.: +1.23, -23.45, 3.456)
- NR3 Floating-point exponential representation data (e.g.: +1.0E-2, -2.3E+4)

| Shows the command description. | Read/Write | the Stand | ard Ev | ent Stat | tus Ena | ble Reg | ister (| ESER) | |
|---|-------------|-------------------|--------------|----------------------------|---------|----------------|---------|-----------------------|---------|
| Shows the message syntax. | Syntax | Command | *ES | E <0 to | 255(N | R1) ⋊ – | | | |
| Explains the command data or response message. | • | Query Response | *ES <0 to | E? 5 255(N | IR1)> | | | | |
| Describes the message. | Description | Command | 0 to | SESEF 255. initial v | | | | | I value |
| | | Query | | mand, a | | | | et by the R1 value | |
| | | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
| | | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| Shows an example of an actual | | PON | URQ | CME | EXE | DDE | QYE | RQC | OPC |
| command application. (Normally described with HEADER ON, (except the HEADER command itself).) | Example | Command | , — | E 36 s bits 5 | and 2 | of SESI | ER) | | |



8.6.1 Standard Commands

Messages specific to the RS-232C or GP-IB interface are identified by their corresponding symbols.

(1) System Data Command

| Queries device | e ID. | |
|----------------|-------------------|---|
| Syntax | Query Response | *IDN? <manufacturer's name="">,<model name="">,0,<software version=""></software></model></manufacturer's> |
| Example | Response | HIOKI, 3541, 0, V1.00 The Device ID is HIOKI 3541, 0, software version 1.00. |
| Note | The respor | se message has no header. |

(2) Internal Operation Command

| Initialize Devic | 9 |
|------------------|---|
| Syntax | Command *RST |
| Description | Command Resets instrument settings (other than saved data) to factory defaults. Operation returns to the initial display after initialization. |
| Note | The communications state is not initialized.To initialize saved data as well, send the :SYSTem:RESet command. |

Execute Self-Test and Query the Result

| Syntax | Query Response | *TST? <0 to 3 (NR1)> 0: No Errors 1: RAM Error 2: EEPROM Error 3: RAM and EEPROM Errors |
|-------------|-------------------|--|
| Description | Perform ir 3. | nstrument self-test and return the result as numerical value 0 to |
| Example | Query Response | *TST? 1 A RAM Error occurred. |

8.6 Message Reference

(3) Synchronization Commands

Set the OPC bit of SESR When Finished All Pending Operations

Syntax Command ***OPC**

Description Sets OPC bit 0 of the Standard Event Status Register (SESR) when all prior commands have finished processing.

Example A;B;*OPC;C The OPC bit of the SESR is set after commands A and B have finished processing.

Respond with ASCII "1" When Finished All Pending Operations

| Syntax | Query | *OPC? |
|--------|----------|-------|
| | Response | 1 |

Description Responds with ASCII "1" when all prior commands have finished processing.

Wait for Pending Commands to Finish

| Syntax Command *W |
|-------------------|
|-------------------|

- **Description** The instrument waits until all prior commands finish before executing any subsequent commands.
 - **Note** The ***WAI** command is supported because it is defined in IEEE 488.2-1987, but because all Model 3541 device-specific commands are sequential types, this command has no actual affect.

(4) Status and Event Control Commands

Note

Clear the Status Byte and Related Queues (Except the Output Queue)

| Syntax Command *CI |
|--------------------|
|--------------------|

Description Clears the event registers corresponding to each bit of the Status Byte Register. Also clears the Status Byte Register.

RS-232C The output queue is unaffected.



The output queue, the various enable registers and MAV bit 4 of the Status Byte Register are unaffected.

Read/Write the Standard Event Status Enable Register (SESER)

| Syntax | Command | *ESE 0 | <0 to 255 | (NR1)> | | | | | |
|-------------|-------------------|---------------------------|---|--------|-------|-------|-------|-------|--|
| | Query Response | * ESE? <0 to 25 | 5 (NR1)> | | | | | | |
| Description | Command | | The SESER mask is set to the numerical value 0 to 255. The initial value (at power-on) is 0. | | | | | | |
| | Query | | The contents of the SESER, as set by the *ESE command, returned as an NR1 value (0 to 255). | | | | | | |
| | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 | |
| | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 | |
| | PON | URQ | CME | EXE | DDE | QYE | RQC | OPC | |
| Example | Command | *ESE | 36 | | | | | | |

(Sets bits 5 and 2 of SESER)

Read and Clear the Standard Event Status Register (SESR)

| Syntax | Query | *ESR? |
|--------|----------|------------------|
| | Response | <0 to 255 (NR1)> |

Description Returns the contents of the SESR as an NR1 value from 0 to 255, then clears register contents.

The response message has no header.

RS-232C

| 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
|-------|--------|-------|-------|-------|-------|--------|--------|
| bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| PON | unused | CME | EXE | DDE | QYE | unused | unused |
| | | | | | | | |

| C | GP-IB | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
| | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | PON | URQ | CME | EXE | DDE | QYE | RQC | OPC |

Example 32

Bit 5 of the SESR was set to 1.

Write and Read the Service Request Enable Register (SRER)

| Syntax | Command | *SRE < | * SRE <0 to 255 (NR1)> | | | | | | |
|-------------|-------------------|--|-------------------------------|-----------|-------------|--------|-------|-------|--|
| | Query Response | *SRE? <0 to 25 | 5 (NR1)> | | | | | | |
| Description | Command | d The SRER mask is set to the numerical value 0 to 255. Although NRf numerical values are accepted, values to the right of the decimal are rounded to the nearest integer. Bit 6 and unused bits 2, 3 and 7 are ignored. The data is initialized to zero at power-on. The contents of the SRER, as set by the *SRE command, are returned as an NR1 value (0 to 255). Bit 6 and unused bits 2, 3 and 7 always return as zero. | | | | | | | |
| | Query | | | | | | | | |
| | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 | |
| | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 | |
| | unused | 0 | ESB | MAV | unused | unused | ESE1 | ESE0 | |
| Example | Command | *SRE 33 Set SRER bits 0 and 5 to 1. | | | | | | | |
| | Query | *SRE? | | | | | | | |
| | Response | 33 | | | | | | | |
| | | SRER b | its 0 and 5 | 5 have be | en set to 1 | Ι. | | | |

Read the Status Byte and MSS Bit

| Syntax | Query Response | *STB? <0 to 25 | 5 (NR1)> | | | | | |
|-------------|--|-------------------|------------|------------|--------|--------|-------|-------|
| Description | The contents of the STB are returned as an NR1 value (0 to 255). | | | | | | | |
| • | The respor | ise messa | age has no | o header. | | , | | |
| | | | - | | | | | |
| | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
| | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | unused | MSS | ESB | MAV | unused | unused | ESE1 | ESE0 |
| | | | | | | | | |
| Example | Query | *STB? | | | | | | |
| | Response | 16 | | | | | | |
| | | STB bit 4 | 4 has bee | n set to 1 | | | | |

Request a Sample

| Syntax | Command *TRG |
|-------------|--|
| Description | Performs one measurement when external triggering is enabled. When Statistical Calculation is ON, imports calculation data. |
| Example | :TRIGger:SOURce EXTernal;*TRG |

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8.6.2 Device-Specific Commands

(1) Event Status Register

Set and Query Device-Specific Event Status Enable Registers ESER0 and ESER1

ESER0

| Syntax | Con | nmand | :ESE0 <0 | to 255 (N | R1)> | | | | |
|---------------|------------|--------------|----------------------------|-----------|-------|-------------|----------|-------------|-----------|
| | Que Res | ery ponse | :ESE0? <0 to 255 (| NR1)> | | | | | |
| Description | Command | | Sets the m the Event \$ | • | | nt Status E | nable Re | gister 0 (E | SER0) for |
| | | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
| | | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | 1 | BIN1 | BIN0 | ERR | Hi | IN | Lo | INDEX | EOC |
| Note ESER1 | | | zes to zero | · | | | | | |
| Syntax | Con | nmand | :ESE0 <0 | to 255 (N | R1)> | | | | |
| | Que Res | ery ponse | :ESE1? <0 to 255 (| NR1)> | | | | | |
| Description | Con | nmand | Sets the m the Event \$ | • | | nt Status E | nable Re | gister 1 (E | SER1) for |
| | | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 |
| | | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
| | | BIN9 | BIN8 | BIN7 | BIN6 | BIN5 | BIN4 | BIN3 | BIN2 |

Note Data initializes to zero at power-on.

Read Device-Specific Event Status Registers ESR0 and ESR1

| Syntax | Query | :ESR0? :ESR1? |
|--------|----------|--|
| | Response | <0 to 255 (NR1)> |
| Note | • | ESR0? clears the contents of ESR0. ESR1? clears the contents of ESR1. |

8.6 Message Reference

(2) Measurement-Related

Select and Query the Function Setting

| Syntax | Command | [:SENSe:]FUNCtion <resistance, lpresistance="" or="" temperature=""></resistance,> |
|---------|---|---|
| | Query Response | [:SENSe:]FUNCtion? RESISTANCEResistance measurement function LPRESISTANCELow-Power Resistance measurement function TEMPERATURETemperature measurement function |
| Example | Command | FUNC LPR Selects the Low-Power Resistance measurement function. |
| | Query Response | FUNC? RESISTANCE The Resistance measurement function has been selected. |
| Note | The follow response | :] may be omitted. owing HIOKI 3227 command can be used, but the format of the e message is different. on RESIstance |

Set and Query the Range Setting

Low-Power Resistance Measurement Range

| Syntax | Command | [:SENSe:]LPResistance:RANGe <expected measurement="" value=""> <expected measurement="" value=""> = 0 to 2000</expected></expected> |
|-------------|-------------------|--|
| | Query Response | [:SENSe:]LPResistance:RANGe? <measurement (nr3)="" range=""></measurement> |
| | | < <u>Measurement Range (NR3)</u> > = 2000.00E-3, 20.0000E+0, 200.000E+0 or 2000.00E+0 |
| Description | Command | Enter the expected measurement value. The instrument is set to the most suitable range for measuring the given numerical value data. |
| | Query | Queries the measurement range setting. |
| Example | Query Response | LPR : RANG? 20.0000E+0 Low-Power Resistance measurement has been set to the 20Ω range. |

Resistance Measurement Range

| | Command | [:SENSe:]RESistance:RANGe <expected measurement="" value=""> <expected measurement="" value=""> = 0 to 110E+6</expected></expected> | |
|-------------|---|--|--|
| | Query Response | [:SENSe:]RESistance:RANGe? <measurement (nr3)="" range=""> <measurement (nr3)="" range=""> = 20.0000E-3, 200.000E-3, 2000.00E- 3, 20.0000E+0, 200.000E+0, 2000.00E+0, 20.0000E+3, 110.000E+3, 1100.00E+3, 11.0000E+6 or 110.0000E+6</measurement></measurement> | |
| Description | Command | Enter the expected measurement value. The instrument is set to the most suitable range for measuring the given numerical value data. | |
| | Query | Queries the measurement range setting. | |
| Example | Command | RES : RANG 123 Sets the Resistance function to the 200 Ω range. | |
| Note | The following HIOKI 3227 command can be used, but the format of the response message is different. :RESIstance:RANGe | | |

Set and Query the Auto-Ranging Setting

Low-Power Resistance Measurement Range

| Syntax | Command | [:SENSe:]LPResistance:RANGe:AUTO <1, 0, ON or OFF> |
|--------|---------|---|
| | | [:SENSe:]LPResistance:RANGe:AUTO? <on off="" or=""></on> |

Example Command LPR:RANG:AUTO ON

Resistance Measurement Range

| Syntax | Command | [:SENSe:]RESistance:RANGe:AUTO <1, 0, ON or OFF> |
|--------|---------|---|
| | | [:SENSe:]RESistance:RANGe:AUTO? <on off="" or=""></on> |

- Example
 Query
 RES:RANG:AUTO?

 Response
 OFF
 - Note The following HIOKI 3227 command can be used, but the format of the response message is different. :RESIstance:AUTO

Clear Zero-Adjustment

Syntax Command :ADJust:CLEAr

Execute Zero-Adjustment

| Syntax | Query | :ADJust? |
|--------|----------|----------|
| | Response | <0 or 1> |

0..... Indicates zero-adjustment succeeded.

1 Indicates the offset resistance exceeded 1,000 dgt during zeroadjustment.

Select and Query the Measurement Terminal Setting

| Syntax | Command | [:SENSe:]TERMinal |
|---------|-------------------|--|
| | Query Response | [:SENSe:]TERMinal? |
| | | A INPUT A is enabled. B INPUT B is enabled. |
| Example | Command | TERM B |
| | Query Response | TERM? B |

(3) Sampling

Select and Query the Sampling Rate setting

| Syntax | Query | :SAMPIe:RATE <fast, medium,="" or="" slow1="" slow2=""> :SAMPIe:RATE? <fast, medium,="" or="" slow1="" slow2=""></fast,></fast,> |
|---------|--|--|
| Example | Command | :SAMP:RATE MED |
| | Query Response | :SAMP:RATE? MEDIUM |
| Note | The following HIOKI 3227 commands can be used, but the response for both SLOW1 and SLOW2 settings is SLOW. Measurement and response times are both different from the Model 3227. :SAMPle | |
| | Sending the | SAMPle SLOW command sets this instrument to SLOW1 sampling |

Sending the :SAMPle SLOW command sets this instrument to SLOW1 sampling rate.

(4) Calculation

Set and Query the Temperature Correction Settings

Temperature Correction (TC) State

| Syntax | Command | :CALCulate:TCORrect:STATe <1, 0, ON or OFF> | |
|--------------------------------------|-------------------|---|--|
| | Query Response | :CALCulate:TCORrect:STATe? <on off="" or=""></on> | |
| Example | Command | :CALC:TCOR:STAT ON | |
| | Query Response | : CALC : TCOR : STAT? OFF | |
| Temperature Correction (TC) Settings | | | |
| Syntax | Command | :CALCulate:TCORrect:PARameter <reference temp.="">,<temp. Coefficient></temp. </reference> | |

| Query | :CALCulate:TCORrect:PARameter? |
|----------|---|
| Response | <reference temp.="">,<temp. coefficient=""></temp.></reference> |
| | <reference temperature=""> = -10.0 to 99.9 (NR3) [°C] <temp. coefficient=""> = -9999 to 9999 (NR1) [ppm/°C]</temp.></reference> |

Example Command :CALC:TCOR:PAR 20,3930

Query :CALC:TCOR:PAR? Response 70.0E+0,4500

 Note
 When the Temperature Correction function is enabled, the Temperature Conversion function is disabled.

 The units of the Reference Temperature are °C, and the units of the Temperature Coefficient are ppm/°C.

 The following HIOKI 3227 command can be used, but the format of the response message is different.

 :TC

 :TCSET

 :TCSET?

Set and Query Temperature Conversion (At) Settings

Temperature Conversion (∆t) State

| Syntax | Command Query Response | :CALCulate:TCONversion:DELTa:STATe? |
|-----------------|------------------------------|---|
| Example | Command | :CALC:TCON:DELT:STAT ON |
| | Query Response | : CALC: TCON: DELT: STAT? ON |
| Temperature Con | version (∆t |) Settings |
| Syntax | Command | :CALCulate:TCONversion:DELTa:PARameter <initial resistance>,<initial temperature="">,<constant></constant></initial></initial |
| | Query Response | :CALCulate:TCONversion:DELTa:PARameter? <initial resistance="">,<initial temp.="">,<constant> <initial resistance=""> = 0 to 110.000E+6 (NR3) <reference temperature=""> = -10.0 to 99.9 (NR3) <constant> = -999.9 to999.9 (NR2)</constant></reference></initial></constant></initial></initial> |
| Example | Command | :CALC:TCON:DELT:PAR 100,20,235 |

Query :CALC:TCON:DELT:PAR? Response 100.000E+0,20.0E+0,235.0

Note When the Temperature Conversion function is enabled, the Temperature Correction function is disabled. The unit of initial resistance is Ω . The unit of initial temperature and constant is °C.

Set and Query the Averaging Function Setting

Averaging Function State

| Syntax | Command | :CALCulate:AVERage:STATe <1, 0, ON or OFF> |
|---------|-------------------|---|
| | Query Response | :CALCulate:AVERage:STATe? <on off="" or=""></on> |
| Example | Command | :CALC:AVER:STAT ON |
| | Query Response | : CALC : AVER : STAT? OFF |

No. of samples to average

| Syntax | Command | :CALCulate:AVERage <averaging samples=""></averaging> |
|---------|-------------------|---|
| | Query Response | :CALCulate:AVERage? <averaging samples=""> <averaging samples=""> = 2 to 100 (NR1)</averaging></averaging> |
| Example | Command | :CALC:AVER 10 |
| | Query Response | :CALC:AVER? 50 |

Clear and Query the Statistical Calculation State

Statistical Calculation State

| Syntax | Command | :CALCulate:STATistics:STATe <1, 0, ON or OFF> |
|---------|-------------------|--|
| | Query Response | :CALCulate:STATistics:STATe? <on off="" or=""></on> |
| Example | Command | :CALC:STAT:STAT ON |
| | Query Response | : CALC : STAT : STAT? ON |

Clear Statistical Calculation Results

Syntax Command :CALCulate:STATistics:CLEAr

Queries the data count

| Syntax | Query Response | :CALCulate:STATistics:NUMBer? <total (nr1)="" count="" data="">,<valid (nr1)="" count="" data="">) 0 to 30000</valid></total> |
|---------|-------------------|--|
| Example | Query Response | :CALC:STAT:NUMB? 23456,23449 |

Query the Mean value

| Syntax | Query | :CALCulate:STATistics:MEAN? |
|--------|----------|-----------------------------|
| | Response | <mean (nr3)=""></mean> |

Query the Maximum value

| Syntax | Query Response | :CALCulate:STATistics:MAXimum? <maximum (nr3)="" value="">,<data (nr1)="" maximum="" no.="" of="" value=""></data></maximum> |
|---------|-------------------|---|
| Example | Query Response | :CALC:STAT:MAX? 12.4859E+3,1124 |

Query the Minimum value

| Syntax | Query | :CALCulate:STATistics:MINimum? |
|--------|----------|---|
| | Response | <minimum (nr3)="" value="">,<data (nr1)="" minimum="" no.="" of="" value=""></data></minimum> |

Query Comparator results

| Syntax | Query Response | :CALCulate:STATistics:LIMit? <hi (nr1)="" count="">,<in (nr1)="" count="">,<lo (nr1)="" count="">,<measure- ment fault count (NR1)></measure- </lo></in></hi> |
|---------|-------------------|---|
| Example | Query Response | :CALC:STAT:LIM? 1516,9310,737,16 |

Query BIN Measurement results

| Syntax | Query Response | :CALCulate:STATistics:BIN? <bin0 (nr1)="" count="">,,<bin9 (nr1)="" count="">,<out count<br="">(NR1)>,<no. (nr1)="" faults="" meas.="" of=""></no.></out></bin9></bin0> |
|---------|-------------------|---|
| Example | Query Response | :CALC:STAT:BIN? 53,16,70,53,57,28,30,77,1,76,81,3 |

Query Standard Deviation

| Syntax | Query Response | :CALCulate:STATistics:DEViation? <on (nr3)="">,<on-1></on-1></on> |
|---------|-------------------|--|
| Example | Query Response | :CALC:STAT:DEV? 0.0159E-3,0.0161E-3 |

Query the Process Capability Indices

| Syntax | Query Response | :CALCulate:STATistics:CP? <cp (nr2)="">,<cpk (nr2)=""></cpk></cp> |
|---------|-------------------|--|
| Example | Query Response | :CALC:STAT:CP? 0.86,0.14 |

- **Note** A data sample can be taken by the following methods:
 - 1. Press the TRIG key
 - 2. Apply a signal to the TRIG terminal of the External I/O
 - 3. Send a *TRG command
 - The :CALCulate:STATistics:STATe command does not clear calculation results.
 - When the valid data count is 0, σ n-1 returns 0.
 - · When cleared, the Statistical Calculation function is not turned OFF.
 - The upper limit of Cp and CpK is 99.99. When Cp or Cpk >99.99, its value is returned as 99.99.

Set and Query Comparator Settings

Comparator State

| Syntax | Command | :CALCulate:LIMit:STATe <1, 0, ON or OFF> |
|--------------|-------------------|---|
| | Query Response | :CALCulate:LIMit:STATe? <on off="" or=""></on> |
| Example | Command | :CALC:LIM:STAT ON |
| Beeper State | | |
| Syntax | Command | :CALCulate:LIMit:BEEPer <off, hl="" in="" or=""></off,> |
| | Query Response | :CALCulate:LIMit:BEEPer? <off, hl="" in="" or=""></off,> |
| | <u> </u> | |

Example Command :CALC:LIM:BEEP HL

Note The following HIOKI 3227 command can be used, but the format of the response message is different. :CSET:BEEPer

Decision Mode Setting

| Syntax | Command | :CALCulate:LIMit:MODE <hl or="" ref=""></hl> |
|---------|-------------------|---|
| | Query Response | :CALCulate:LIMit:MODE? <hl or="" ref=""></hl> |
| | | HL = Decision by preset upper and lower thresholds. REF = Decision by a reference value and tolerance. |
| Example | Command | :CALC:LIM:MODE REF |

Note The following HIOKI 3227 command can be used, but the format of the response message is different. :CSET:CMODe

Upper Threshold Setting

| Syntax | Command | :CALCulate:LIMit:UPPer <upper threshold=""></upper> |
|---------|-------------------|--|
| | Query Response | :CALCulate:LIMit:UPPer? <upper threshold=""> <upper threshold=""> = 0 to 999999 (NR1)</upper></upper> |
| Example | Command | :CALC:LIM:UPP 005971 |

•

Lower Threshold Setting

| Syntax | Command | :CALCulate:LIMit:LOWer <lower threshold=""></lower> | |
|--------------------------|--|---|--|
| | Query | :CALCulate:LIMit:LOWer? | |
| Response | <lower threshold=""></lower> | | |
| | <lower threshold=""> = 0 to 999999 (NR1)</lower> | | |
| Note oth Upper | | Upper and Lower thresholds are specified as integer values. To specify 0.567 Ω in the 2Ω range, send the following command: | |

 (For both Upper and Lower thresholds)
 in the 2Ω range, send the following command: :CALCulate:LIMit:UPPer 56700 (or 056700)
 The following HIOKI 3227 command can be used, but the format of the response message is different. :CSET:PARAmeter 8.6 Message Reference

Reference Resistance Setting

| Syntax | Command | :CALCulate:LIMit:REFerence <reference resistance=""></reference> |
|-------------------|---|--|
| | Query Response | :CALCulate:LIMit:REFerence? <reference resistance=""></reference> |
| | | <reference resistance=""> = 0 to 999999 (NR1)</reference> |
| Example | Command | :CALC:LIM:REF 141000 |
| Note | Reference Resistance is specified as an integer value.2. To specify 0.567 Ω in the 2 Ω range, send the following command: :CALCulate:LIMit:REFerence 56700 | |
| Decision Toleranc | e Setting | |
| Syntax | Command | :CALCulate:LIMit:PERCent <tolerance (%)=""></tolerance> |
| | Deenser | :CALCulate:LIMit:PERCent? <tolerance (%)=""></tolerance> |
| | | <tolerance (%)=""> = 0 to 99.999 (NR2)</tolerance> |
| Example | Command | :CALC:LIM:PERC 10.000 |
| Note | The following HIOKI 3227 command can be used, but the format of the response message is different. :CSET:PARAmeter | |
| Comparator Resu | lt | |

| Syntax | Query Response | :CALCulate:LIMit:RESult? <hi, err="" in,="" lo,="" off="" or=""></hi,> |
|---------|-------------------|---|
| Example | Query Response | :CALC:LIM:RES? HI |

Setting and Querying BIN Measurements

BIN Measurement State

| Syntax | Command | :CALCulate:BIN:STATe <1, 0, ON or OFF> |
|---------|---------|---|
| | | :CALCulate:BIN:STATe? <on off="" or=""></on> |
| Example | Command | :CALC:BIN:STAT ON |

Enable Mask Setting

Syntax Command :CALCulate:BIN:ENABle <Enable Mask>

:CALCulate:BIN:ENABle?

Response <Enable Mask>

Query

<Enable Mask> = 0 to 1023 (base-10)

Set the bit corresponding to each BIN to be enabled for BIN measurement.

| bit 9 | bit 8 | bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIN9 | BIN8 | BIN7 | BIN6 | BIN5 | BIN4 | BIN3 | BIN2 | BIN1 | BIN0 |

Example Command :CALC:BIN:ENAB 15

Enables BIN0 to BIN3.

Decision Mode Setting

| Command | :CALCulate:BIN:MODE <bin no.="">,<hl or="" ref=""></hl></bin> |
|----------|---|
| Query | :CALCulate:BIN:MODE? <bin no.=""></bin> |
| Response | <hl or="" ref=""></hl> |
| | <bin no.=""> = 0 to 9</bin> |
| | <hl or="" ref=""> =</hl> |
| | HL Compare with upper/lower thresholds. |
| | REF Compare with reference value and tolerance. |
| | Query |

Example Command :CALC:BIN:MODE 3,HL

Upper Threshold Setting

| Syntax | Command | :CALCulate:BIN:UPPer? <bin no.="">,<upper threshold=""></upper></bin> |
|--------|-------------------|--|
| | Query Response | :CALCulate:BIN:UPPer? <bin no.=""> <upper threshold=""> <bin no.=""> = 0 to 9 <upper threshold=""> = 0 to 999999 (NR1)</upper></bin></upper></bin> |

Lower Threshold Setting

| Syntax | Command | :CALCulate:BIN:LOWer <bin no.="">,<lower threshold=""></lower></bin> |
|---------|-------------------|--|
| | Query Response | :CALCulate:BIN:LOWer? <bin no.=""> <lower threshold=""> <bin no.=""> = 0 to 9 <lower threshold=""> = 0 to 999999 (NR1)</lower></bin></lower></bin> |
| Example | Command | :CALC:BIN:LOW 0,117832 |
| Note | To specify (| Lower thresholds are specified as integer values. 0.567 Ω in the 2 Ω range, send the command as follows: 1:BIN:UPPer 3,56700 (or 056700) |

8.6 Message Reference

Reference Resistance Setting

| Syntax | Command | :CALCulate:BIN:REFerence <bin no.="">,<reference resistance=""></reference></bin> |
|-------------------|-------------------|--|
| | Query Response | :CALCulate:BIN:REFerence? <bin no.=""> <reference resistance=""> <bin no.=""> = 0 to 9 <reference resistance=""> = 0 to 999999 (NR1)</reference></bin></reference></bin> |
| Note | To specify (| Resistance is specified as an integer value. 0.567 Ω in the 2 Ω range, send the command as follows: a:BIN:REFerence 5,56700 |
| Decision Tolerand | ce Setting | |
| Syntax | Command | :CALCulate:BIN:PERCent <bin no.="">,<tolerance (%)=""></tolerance></bin> |
| | Query Response | :CALCulate:BIN:PERCent? <bin no.=""> <tolerance (%)=""> <bin no.=""> = 0 to 9 <tolerance (%)=""> = 0 to 99.999 (NR2)</tolerance></bin></tolerance></bin> |
| Query the Decisio | on Result | |
| Syntax | Query Response | :CALCulate:BIN:RESult? <nr1> <nr1> = 0 to 1023 The bit corresponding to each BIN with a PASS decision is set to 1. bit 9 bit 8 bit 7 bit 6 bit 5 bit 4 bit 3 bit 2 bit 1 bit 0 BIN9 BIN8 BIN7 BIN6 BIN5 BIN4 BIN3 BIN2 BIN1 BIN0</nr1></nr1> |
| Example | Query | :CALC:BIN:RES? |

Response 128

BIN7 was judged PASS.

(5) System

Offset Voltage Compensation State

| Syntax | Command | :SYSTem:OVC <1, 0, ON or OFF> |
|---------|-------------------|--|
| | Query Response | :SYSTem:OVC? <on off="" or=""></on> |
| Example | Command | :SYST:OVC ON |
| | Query Response | :SYST:OVC? OFF |
| Note | Settings in | the 110 K Ω range and higher are ignored. |

Temperature Measurement Settings (Analog Input)

Temperature Sensor Selection

| Syntax | Command | :SYSTem:TEMPerature:SENSor <pt analog="" or=""></pt> |
|---------|-------------------|--|
| | Query Response | :SYSTem:TEMPerature:SENSor? <pt analog="" or=""></pt> |
| | | PTThe 9451 TEMPERATURE PROBE is used as the temperature sensor |
| | | ANALOGAn analog output thermometer is used as the temperature sensor |
| Example | Command | :SYST:TEMP:SENS ANAL |
| | Query Response | : SYST : TEMP : SENS? PT |

Note For some commands, RS-232C cannot be selected as input for temperature measurement. In such a case, use the menu screens on the 3541 unit to make the setting.

Temperature measurement via RS-232C interface (using the 3444/3445 TEMPERATURE HITESTER+ 3909 INTERFACE PACK) (Page 34)

Analog Input Parameter Settings

| Syntax | Command | :SYSTem:TEMPerature:PARameter 1 , <t1>,<v2>,<t2></t2></v2></t1> |
|---------|-------------------|---|
| | Query Response | :SYSTem:TEMPerature:PARameter? <v1>,<t1>,<v2>,<t2></t2></v2></t1></v1> |
| | | <v1> = 0 to 2.00 (NR2) Reference Voltage 1 [V]</v1> |
| | | <t1> = -99.9 to 999.9 (NR2) Reference Temperature 1 [°C]</t1> |
| | | <v2> = 0 to 2.00 (NR2) Reference Voltage 2 [V]</v2> |
| | | <t1> = -99.9 to 999.9 (NR2) Reference Temperature 2 [°C]</t1> |
| Example | Command | :SYST:TEMP:PAR 0,-10,2,100 |
| | Query | :SYST:TEMP:PAR? |
| | Response | 0.00,0.00,1.00,100.0 |
| | | 0 V displays as 0°C, and 1 V displays as 100°C. |

Self-Calibration State and Setting

Execute Self-Calibration

Syntax Command :SYSTem:CALibration

Set Self-Calibration Execution State

| | Command | :SYSTem:CALibration:AUTO <1, 0, ON or OFF> |
|---------|-------------------|---|
| | Query Response | :SYSTem:CALibration:AUTO? <on off="" or=""></on> |
| | | ON AUTO Self-Calibration selected OFF MANUAL Self-Calibration selected |
| Example | Command | :SYST:CAL:AUTO OFF |
| | Query Response | : SYST : CAL : AUTO? ON |
| Note | Even when | AUTO is selected, Self-Calibration can be manually per |

rformed at any iy pe time by sending the SYSTem:CALibration command.

Set and Query the Key Beeper Setting

| Syntax | Command | :SYSTem:BEEPer:STATe <1, 0, ON or OFF> |
|---------|-------------------|---|
| | Query Response | :SYSTem:BEEPer:STATe? <on off="" or=""></on> |
| Example | _ | :SYST:BEEP:STAT ON |
| | Query Response | : SYST: BEEP: STAT? ON |

Select and Query the Line Frequency Setting

| Syntax | Command | :SYSTem:LFRequency <50 or 60> |
|---------|--|-----------------------------------|
| | Query Response | :SYSTem:LFRequency? <50 or 60> |
| Example | Command | :SYST:LFR 50 |
| | Query Response | :SYST:LFR? 60 |
| Note | The following HIOKI 3227 command can be used, but the format of the response message is different. :FREQuency | |

Set and Query the Key-Lock State

| Syntax | Command | :SYSTem:KLOCk <1, 0, ON or OFF> |
|---------|-------------------|--|
| | | :SYSTem:KLOCk? <on off="" or=""></on> |
| Example | Command | :SYST:KLOC ON |
| | Query Response | :SYST:KLOC? OFF |

Save and Load Measurement Setting States

Syntax Command :SYSTem:SAVE <Table No. 1 to 30> :SYSTem:LOAD <Table No. 1 to 30>

Set and Query the Header Present Setting

| Syntax | Command | :SYSTem:HEADer <1, 0, ON or OFF> |
|---------|-------------------|--|
| | Query Response | :SYSTem:HEADer? <on off="" or=""></on> |
| Example | Command | :SYST:HEAD ON |
| | Query Response | :SYST:HEAD? OFF :SYSTEM:HEADER ON |
| Note | The followir | ng HIOKI 3227 command can be used, but the f |

Note The following HIOKI 3227 command can be used, but the format of the response message is different. HEADer

Select the ERR Output Setting

| Syntax | Command | :SYSTem:ERRor <synchronous asynchronous="" or=""></synchronous> |
|---------|-------------------|--|
| | Query Response | :SYSTem:ERRor? <synchronous asynchronous="" or=""></synchronous> |
| | | SYNCHRONOUSSynchronize with EOC output ASYNCHRONOUSAsynchronous with EOC output |
| Example | Command | :SYST:ERR SYNC |
| | Query Response | : SYST : ERR? ASYNCHRONOUS |

BCD Output Setting

| Syntax | Command | :SYSTem:EXTernalout <bin bcd="" or=""></bin> |
|---------|---|--|
| | Query Response | :SYSTem:EXTernalout? <bin bcd="" or=""></bin> |
| Example | Command | :SYST:EXT BCD |
| | Query Response | :SYST:EXT? BIN |
| Note | BIN output is disabled when BCD output is selected.BCD output is disabled when BIN output is selected. | |

Delimiter Setting

| GP-IB |
|-------|
|-------|

| Syntax | Command | :SYSTem:TERMinator <0 or 1> |
|---------|-------------------|---|
| | Query Response | :SYSTem:TERMinator? <0 or 1> |
| | | 0 LF+EOI 1 CR,LF+EOI |
| Example | Command | :SYST:TERM 1 |
| | Query Response | :SYST:TERM? 0 |
| Note | • | er-on, this is set to 0 (LF+EOI). -232C delimiter is fixed as CR + LF. |

System Reset

| Syntax | Command | :SYSTem:RESet |
|-------------|--|--|
| Description | Command | Returns all settings, including any saved data, to factory default settings. |
| Example | Command | :SYST:RES |
| Note | If you want to preserve saved data, use the *RST command instead. | |

(6) External I/O

External I/O Output

| Syntax | Command | :10:01 | T <outp< th=""><th>ut Data</th><th>0 to 2</th><th>55></th><th></th><th></th><th></th><th></th></outp<> | ut Data | 0 to 2 | 55> | | | | |
|-------------|-------------|----------|---|----------|---------|---------|-------|--------|---------|---------------------------|
| Description | | | | | | • | | | | nector when ernal I/O. |
| | | bit | 7 bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 | |
| | | OU | 7 OUT6 | OUT5 | OUT4 | OUT3 | OUT2 | OUT1 | OUT0 | |
| | | 50 | 25 | 49 | 24 | 48 | 23 | 47 | 22 | Pin No. |
| | | ♦ 6.2 \$ | Signal De | scriptio | ons (Pa | ige 78) | | | | |
| Note | An executio | n error | occurs if | BCD i | s selec | ted as | the B | IN/BCI |) outpu | it setting for |

Note An execution error occurs if BCD is selected as the BIN/BCD output setting for External I/O.

External I/O Input

| Syntax | Query Response | :IO:IN? 0 to 3 (NR1) |
|-------------|-------------------|---|
| Description | Query | Reads at the leading edge (ON) of the EXT I/O $\overline{\text{TRIG}}$ and $\overline{\text{PRINT}}$ terminals, and then clears. |
| | | A bit is set when the leading edge (short between each signal terminal and the GND terminal) is detected, and is cleared when read by this query command. |
| | | TRIG key input is detected in the same way as the $\overline{\text{TRIG}}$ terminal signal. |
| | | bit 0: EXT I/O TRIG (leading edge), TRIG key input |
| | | bit 1: EXT I/O PRINT (leading edge) |

(7) Triggering

Triggering System Description

Triggering operates as follows depending on the continuous measurement setting (:INITIATE:CONTINUOUS) and the trigger source setting (:TRIGGER:SOURCE).

8.7 Basic Data Importing Methods (Page 147)

| | | Continuous Measurement (: INITIATE : CONTINUOUS) | | | |
|-----------------------|--|--|---|--|--|
| | | ON | OFF ^{*1} | | |
| Trigger Source | IMMEDIATE (EXT.TRIG off) | Free-Run state. Measurement continues automatically. (Page 141)-1 | Trigger by : INITIATE (or :READ?) command. (Page 141)-2 | | |
| (:TRIGGER: SOURCE) | EXTERNAL ^{*2} (EXT.TRIG lit) | Trigger by TRIG terminal, TRIG key or *TRG command. After measurement, enters the trigger wait state. (Page 141)-3 | Issue : INITIATE (or : READ?) command to wait for trigger. Trigger by TRIG terminal, TRIG key or ∗TRG command. ♦ (Page 141)-4 | | |

*1 : INITIATE : CONTINUOUS OFF

Can only be set by Remote command. If this has been set to OFF when operation is returned to the Local state or power is turned off, the following state occurs when power is turned back on.

: INITIATE : CONTINUOUS ON

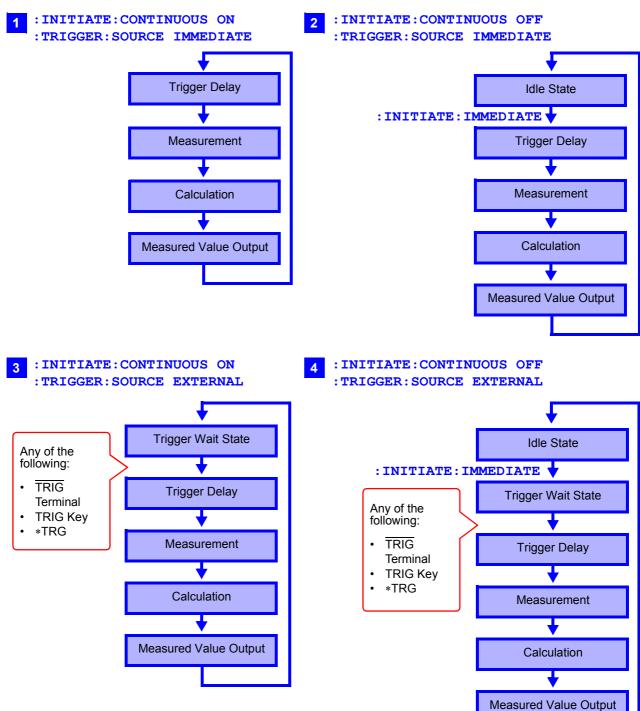
✤ 8.4.6 Local Function (Page 111)

*2 : TRIGGER: SOURCE EXTERNAL

Current flows only while measuring in all ranges of the Low-Power Resistance function, and in the 20 m Ω to 20 Ω ranges of the Resistance Measurement function.

6.3 Timing Chart (Page 83)





Continuous Measurement Setting

| Syntax | Query | :INITiate:CONTinuous <1, 0, ON or OFF> :INITiate:CONTinuous? <on off="" or=""> ON Continuous Measurement Enabled OFF Continuous Measurement Disabled</on> |
|---------|--|--|
| Example | Command | :INIT:CONT OFF |
| | Query Response | : INIT: CONT? ON |
| Note | After me setting is • Continuc After me • Triggerin the Trigg • The follo :INITiate | bus Measurement Enabled: basurement, enters the Trigger Wait State. When the trigger source i IMMediate, the next trigger occurs immediately (the Free-Run State). bus Measurement Disabled: asurement, enters the Idle State instead of the Trigger Wait State. g is ignored in the Idle State. Executing :INITiate[:IMMediate] enables er Wait State. wing commands do not apply to temperature measurement. cONTinuous bus measurement is enabled upon exit from the Remote State. |

Trigger Wait Setting

| Syntax | Command | :INITiate[:IMMediate] | | |
|-------------|---|---|--|--|
| Description | Switches triggering from the Idle State to the Trigger Wait State. | | | |
| Example | Disable continuous measurement, and read one value for each trigger event | | | |
| | Sending | : TRIG: SOUR IMM Trigger immediately when entering Trigger Wait State | | |
| | | : INIT: CONT OFF Disables continuous measurement | | |
| | | : INIT Enable Trigger Wait Trigger immediately upon :TRIG:SOUR IMM | | |
| | | : FETC?Fetch measured value | | |
| | Reading | 2.16414E+3 Measured value is $2.16414k\Omega$ | | |
| Error | | cution error occurs when continuous measurement is enabled E:CONTINUOUS ON). | | |
| Note | | e trigger source is IMMediate, triggering occurs immediately before the Idle State. | | |
| | for an ex | When the trigger source is EXTernal, the Trigger Wait State is enabled to wait for an external trigger, and when a trigger occurs, one measurement is taken before entering the Idle State. | | |
| | | wing commands do not apply to temperature measurement. [:IMMediate] | | |

Trigger Source Setting

| Syntax | Command | :TRIGger:SOURce <immediate external="" or=""></immediate> |
|-------------------|-------------------|--|
| Query Response | | :TRIGger:SOURce? <immediate external="" or=""></immediate> |
| response | reepenee | IMMEDIATEInternal triggering |
| | | EXTERNAL External trigger source. Triggering by TRIG key, TRIG terminal or *TRG command. |
| Example | Command | :TRIG:SOUR IMM |
| | Query Response | :TRIG:SOUR? IMMEDIATE |
| Note | The follo | wing commands do not apply to temperature measurement. |

- The following commands do not apply to temperature measurement. :TRIGger:SOURce
 - The HOLD command for the HIOKI 3227 is the same as the :TRIGger:SOURce EXTernal command.

Trigger Delay Setting

Setting the Trigger Delay Time

| Syntax | Command | :TRIGger:DELay <delay></delay> |
|---------|----------|--------------------------------|
| | Query | :TRIGger:DELay? |
| | Response | <delay></delay> |
| | | Delay [s]0 to 9.999 (NR2) |
| Example | Query | :TRIG:DEL? |
| | Response | 0.010 |

Setting Automatic Trigger Delay

| Syntax | Command | :TRIGger:DELay:AUTO <1, 0, ON or OFF> |
|--------|---------|--|
| | | :TRIGger:DELay:AUTO? <on off="" or=""></on> |

Example Cancel automatic triggering and set a trigger delay of 0.01 s.

Sending :TRIG:DEL:AUTO OFF :TRIG:DEL 10E-3

Query :TRIG:DEL:AUT? Response ON

- Note The following commands do not apply to temperature measurement. :TRIGger:DELay :TRIGger:DELay:AUTO
 - When Auto Delay is enabled (:TRIGger:DELay:AUTO ON), the Delay setting is ignored.

(8) Reading Measured Values

Measurement Value Formats

| Resistance Measurement | Measurement Range | Measured Value | ±OF | Measurement Fault |
|-------------------------------|----------------------|----------------|-------------|-------------------|
| Absolute Value | 20m Ω | ±00.000E-3 | ±10.0000E+8 | +10.0000E+9 |
| Indication | $200 \text{m}\Omega$ | ±E-3 | ±100.000E+7 | +100.000E+8 |
| | 2Ω | ±000.00E-3 | ±1000.00E+6 | +1000.00E+7 |
| | 20Ω | ±00.000E+0 | ±10.0000E+8 | +10.0000E+9 |
| | 200Ω | ±000.000E+0 | ±100.000E+7 | +100.000E+8 |
| | 2kΩ | ±E+0 | ±1000.00E+6 | +1000.00E+7 |
| | 20k Ω | ±00.000E+3 | ±10.0000E+8 | +10.0000E+9 |
| | 100kΩ | ±E+3 | ±100.000E+7 | +100.000E+8 |
| | 1MΩ | ±000.00E+3 | ±1000.00E+6 | +1000.00E+7 |
| | 10MΩ | ±E+6 | ±10.0000E+8 | +10.0000E+9 |
| | 100MΩ | ±000.000E+6 | ±100.000E+7 | +100.000E+8 |
| | | | | |
| Resistance | | Measured Value | ±OF | Measurement Fault |
| Measurement Relative Value | | ±000.000E+0 | ±100.000E+7 | +100.000E+8 |
| Indication | | | | |
| Temperature | | Measured Value | ±OF | Measurement Fault |
| Conversion Indication | | ±0000.0E+0 | ±10000.0E+5 | +10000.0E+6 |
| | | | | |
| Temperature | | Measured Value | ±OF | |
| Indication | | ±000.0E+0 | ±100.0E+7 | |
| | | | | |

Note

For positive measurements, the sign position is blank.

Reading the Most Recent Measurement

| Syntax | Query | :FETCh? | | |
|-------------|--|--|--|--|
| Description | Reads the | Reads the most recent measurement. No trigger occurs. | | |
| Example | Query Response | :FETC? 17.0216E-3 | | |
| Note | message is | The following HIOKI 3227 command can be used, but the format of the response message is different. :MEASure:RESIstance? | | |
| | However, the long-form :MEASURE:RESISTANCE? command operates the same as the :MEASure:RESistance? command of this model. Measure in a Specifying Range and Function (Ω, LPΩ) (Page 146) | | | |
| Note | message is :MEASure: However, t as the :ME | s different. RESIstance? he long-form :MEASURE:RESISTANCE? command operates the same ASure:RESistance? command of this model. | | |

Reading the Temperature Measurement

| Syntax | Query | :MEASure:TEMPerature? |
|-------------|-------------------|--|
| Description | | most recently measured temperature value. rature measurement can be read regardless of the current resistance |
| Example | Query Response | :MEAS:TEMP? 25.1.0000E+0 |

Measuring (Awaiting Triggers and Reading Measurements)

| Syntax | Query | :READ? |
|--------|-------|--------|
|--------|-------|--------|

Description Switches from the Idle State to the Trigger Wait State, then reads the next measured value. With auto-ranging enabled, the most suitable range is selected before measurement.

| Trigger Source | Operation |
|----------------|---|
| IMMediate | Triggers and reads measured value. |
| EXTernal | After triggering by the TRIG terminal (External I/O), *TRG command or TRIG key, reads the measured value. |

- Error This command causes an execution error if issued during the Continuous Measurement state (after :INITIATE:CONTINUOUS ON).
 - This command causes an execution error if issued during the Trigger Wait State.
- **Note** The next command does not execute until measurement is finished.
 - With external triggering using the *TRG command, after sending the *TRG command and waiting for a time equivalent to the sampling rate, specify the Talker. (only with the GP-IB interface setting)

Measure in a Specifying Range and Function (Ω , LP Ω)

| Syntax | Query | :MEASure:LPResistance? <expected measurement="" value=""> <expected measurement="" value=""> = 0 to 2E+3</expected></expected> |
|-------------|--|---|
| | | :MEASure:RESistance? <expected measurement="" value=""> <expected measurement="" value=""> = 0 to 110E+6</expected></expected> |
| Description | • | cted measurement value is provided, the instrument selects the most nge for measuring. If the data value is omitted, auto-ranging is selected. |
| | Triggeri Internal The spectrum The spectrum One trig | SURE command operates as follows: ing is set to disable continuous measurement. triggering is enabled. ecified function is selected. ecified range is selected. gger executes. easured value is read. |
| | ∶ FUNC < <functior (If al <fu : INIT :</fu </functior | SURE command causes the following commands to execute internally. <function> >:RANG <expected measurement="" value=""> n <expected measurement="" value=""> is not present, nction>:RANG:AUTO ON) CONT OFF SOUR IMM</expected></expected></function> |
| Example | Query Response | :MEAS:RES? 5.1124E+3 |
| | Query Response | :MEAS:LPR? 104.140E+0 |
| Note | | asuring inductive objects such as transformers or coils, measurement be returned before the value has stabilized with auto-ranging. In such |

data may be returned before the value has stabilized with auto-ranging. In such cases, specify the measurement range or use the trigger delay function.

8.7 Basic Data Importing Methods

Flexible data importing is available depending on the application.

| Free-Run Data Importing | | | | | | | | |
|------------------------------|------------------|--|--|--|--|--|--|--|
| | Initial Setup | :INITiate:CONTinuous ON (enable continuous measurement) :TRIGger:SOURce IMM (internal triggering) | | | | | | |
| | Importing | :FETCh? Imports the most recent measurement | | | | | | |
| Importing by Host Triggering | | | | | | | | |
| | Initial Setup | :INITiate:CONTinuous OFF (disable continuous measurement) :TRIGger:SOURce IMM (internal triggering) | | | | | | |
| | Importing | :READ? A trigger occurs, and a measurement is taken and the result is transferred. | | | | | | |
| Importing Data | by TRIG | Key or TRIG Terminal | | | | | | |
| | Initial Setup | :INITiate:CONTinuous OFF (disable continuous measurement) :TRIGger:SOURce EXT (external triggering) | | | | | | |

Importing :READ?

When triggered by the TRIG key or TRIG terminal, a measurement is taken and the result is transferred.

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8.8 Sample Programs

These sample programs are written in Microsoft Visual Basic 5.0 and 6.0.

- The following are used for communication:
 - For RS-232C communication: MSComm from Visual Basic Professional

For GP-IB communication: National Instruments GP-IB Board, Driver and Module for Visual Basic

• During communications, the terminator setting is supposed to be as follows:

```
RS-232C: CR+LF
GP-IB: LF
```

Visual Basic is a registered trademark of Microsoft Corporation.

RS-232C Communications

(Using Microsoft Visual Basic Professional MSComm)

(1) Simple Resistance Measurement

Imports measured values 10 times, and saves measurements in a text file.

```
Private Sub MeasureSubRS()
Dim recvstr As String
                                                             'Receiving char string
Dim i As Integer
MSComm1.Settings = "9600,n,8,1"
                                                             'Comm port setting
MSComm1.PortOpen = True
                                                             'Open a port
Open App.Path & "\data.csv" For Output As #1
                                                             'Open a text file for saving
MSComm1.Output = ":TRIG:SOUR IMM" & vbCrLf
                                                             'Select internal triggering
MSComm1.Output = ":INIT:CONT ON" & vbCrLf
                                                             'Continuous measurement ON
For i = 1 To 10
  MSComm1.Output = ":FETCH?" & vbCrLf
                                                             'Send ":FETCH?" to import the most recent
                                                             measurement
  recvstr = ""
                                                             'From here on, continue receiving until an LF code
                                                             occurs
  While Right(recvstr, 1) <> Chr(10)
    recvstr = recvstr + MSComm1.Input
    DoEvents
  Wend
  recvstr = Left(recvstr, Len(recvstr) - 2)
                                                             'Delete the terminator (CR+LF)
  Print #1, Str(i) & "," & recvstr
                                                             'Write to the file
Next
Close #1
MSComm1.PortOpen = False
End Sub
```

(2) Measure Resistance by PC Key

Measures and imports by key input on the PC, and saves measurements in a text file.

```
Private Sub MeasureReadSubRS()
Dim recvstr As String
                                                             'Receiving char string
Dim i As Integer
MSComm1.Settings = "9600,n,8,1"
                                                             'Comm port setting
MSComm1.PortOpen = True
                                                             'Open a port
Open App.Path & "\data.csv" For Output As #1
                                                             'Open a text file for saving
MSComm1.Output = ":TRIG:SOUR IMM" & vbCrLf
                                                             'Select internal triggering
MSComm1.Output = ":INIT:CONT OFF" & vbCrLf
                                                             'Continuous measurement OFF
For i = 1 To 10
  'Wait for PC key input
  'Create a key input check routine to set InputKey() = True when a key is pressed
  Do While 1
    If InputKey() = True Then Exit Do
    DoEvents
  Loop
  'After confirming key input, measure once, and read the measured value
  MSComm1.Output = ":READ?" & vbCrLf
                                                             'Send ":READ?" to measure and import the
                                                             measurement
  recvstr = ""
                                                             'From here on, continue receiving until an LF code
                                                             occurs
  While Right(recvstr, 1) <> Chr(10)
    recvstr = recvstr + MSComm1.Input
    DoEvents
  Wend
  recvstr = Left(recvstr, Len(recvstr) - 2)
                                                             'Delete the terminator (CR+LF)
  Print #1, Str(i) & "," & recvstr
                                                             'Write to the file
Next
Close #1
MSComm1.PortOpen = False
End Sub
```

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8.8 Sample Programs

(3) External Trigger Measurement 1

Measure and import according to external triggering of the 3541 (TRIG key or EXT I/O TRIG terminal input), or by PC key input, and save measurements in a text file.

```
Private Sub MeasureTrigSubRS()
Dim recvstr As String
                                                             'Receiving char string
Dim i As Integer
MSComm1.Settings = "9600,n,8,1"
                                                             'Comm port setting
MSComm1.PortOpen = True
                                                             'Open a port
Open App.Path & "\data.csv" For Output As #1
                                                             'Open a text file for saving
MSComm1.Output = ":TRIG:SOUR EXT" & vbCrLf
                                                             'Select external triggering
MSComm1.Output = ":INIT:CONT OFF" & vbCrLf
                                                             'Continuous measurement OFF
For i = 1 To 10
  MSComm1.Output = ":READ?" & vbCrLf
                                                             'Send ":READ?" to measure and import the
                                                             measurement
  recvstr = ""
                                                             'From here on, continue receiving until an LF code
                                                             occurs
  While Right(recvstr, 1) <> Chr(10)
    recvstr = recvstr + MSComm1.Input
    DoEvents
    'To execute trigger measurement when a PC key is pressed,
    'Create a key input check routine to set InputKey() = True when a key is pressed
    If InputKey() = True Then
       MSComm1.Output = "*TRG" & vbCrLf
                                                             'When key input occurs, send "*TRG" to trigger
                                                             measurement
    End If
  Wend
  recvstr = Left(recvstr, Len(recvstr) - 2)
                                                             'Delete the terminator (CR+LF)
  Print #1, Str(i) & "," & recvstr
                                                             'Write to the file
Next
Close #1
MSComm1.PortOpen = False
End Sub
```

(4) External Trigger Measurement 2

Measure and import according to external triggering of the 3541 (TRIG key or EXT I/O TRIG terminal input), and save measurements in a text file.

(The 3541 imports the most recent measurement by trigger input timing with the continuous measurement state)

Private Sub MeasureTrig2SubRS() Dim recvstr As String 'Receiving char string Dim i As Integer MSComm1.Settings = "9600,n,8,1" 'Comm port setting MSComm1.PortOpen = True 'Open a port Open App.Path & "\data.csv" For Output As #1 'Open a text file for saving MSComm1.Output = ":TRIG:SOUR IMM" & vbCrLf 'Select internal triggering MSComm1.Output = ":INIT:CONT ON" & vbCrLf 'Continuous measurement ON 'Clear confirmation of External I/O TRIG input MSComm1.Output = ":IO:IN?" & vbCrLf recvstr = "" While Right(recvstr, 1) <> Chr(10) recvstr = recvstr + MSComm1.Input DoEvents Wend For i = 1 To 10 'Wait for External I/O TRIG input Do While 1 MSComm1.Output = ":IO:IN?" & vbCrLf recvstr = "" While Right(recvstr, 1) <> Chr(10) recvstr = recvstr + MSComm1.Input DoEvents Wend If Left(recvstr, 1) = "1" Then Exit Do DoEvents Loop MSComm1.Output = ":FETCH?" & vbCrLf 'Send ":FETCH?" to import the most recent measurement recvstr = "" 'From here on, continue receiving until an LF code occurs While Right(recvstr, 1) <> Chr(10) recvstr = recvstr + MSComm1.Input DoEvents Wend recvstr = Left(recvstr, Len(recvstr) - 2) 'Delete the terminator (CR+LF) Print #1, Str(i) & "," & recvstr 'Write to the file Next Close #1 MSComm1.PortOpen = False End Sub

8.8 Sample Programs

(5) Set Measurement State

Sets up the measurement setting state.

'Function: Resistance Measurement 'Range: 200 mΩ 'Sampling: SLOW2 'Triggering: Internal 'Comparator: ON, HI/LO Mode, Beeper HL, Upper Threshold 200000, Lower Threshold 100000 Private Sub SettingsSubRS() MSComm1.Settings = "9600,n,8,1" 'Comm port setting MSComm1.PortOpen = True 'Open a port MSComm1.Output = ":FUNC RES" & vbCrLf 'Select Resistance function MSComm1.Output = ":RES:RANG 200E-3" & vbCrLf 'Select 200 mΩ range MSComm1.Output = ":SAMP:RATE SLOW2" & vbCrLf 'Select SLOW2 sampling MSComm1.Output = ":TRIG:SOUR IMM" & vbCrLf 'Select internal triggering MSComm1.Output = ":INIT:CONT ON" & vbCrLf 'Continuous measurement ON MSComm1.Output = ":CALC:LIM:MODE HL" & vbCrLf 'From here on, comparator settings MSComm1.Output = ":CALC:LIM:BEEP HL" & vbCrLf MSComm1.Output = ":CALC:LIM:UPP 200000" & vbCrLf MSComm1.Output = ":CALC:LIM:LOW 100000" & vbCrLf MSComm1.Output = ":CALC:LIM:STAT ON" & vbCrLf 'Comparator ON MSComm1.PortOpen = False End Sub

GP-IB Communications

(Using National Instruments GP-IB Board)

(1) Simple Resistance Measurement

Imports measured values 10 times, and saves measurements in a text file.

Private Sub MeasureSub() Dim buffer As String * 13 'Receiving butter Dim recvstr As String 'Receiving char string Dim pad As Integer 'Controller access Dim gpibad As Integer 'Device Address Dim timeout As Integer 'Timeout period 'State (unused) Dim ud As Integer Dim i As Integer 'Board Address 0 pad = 0gpibad = 1 '3541 Address 1 timeout = T10s 'Timeout about 10s 'Initialize GP-IB Call ibfind("gpib0", 0) Call ibdev(pad, gpibad, 0, timeout, 1, 0, ud) Call SendIFC(pad) Open App.Path & "\data.csv" For Output As #1 'Open a text file for saving Call Send(pad, gpibad, ":TRIG:SOUR IMM", NLend) 'Select internal triggering Call Send(pad, gpibad, ":INIT:CONT ON", NLend) 'Continuous measurement ON For i = 1 To 10 Call Send(pad, gpibad, ":FETCH?", NLend) 'Send ":FETCH?" to import the most recent measurement Call Receive(pad, gpibad, buffer, STOPend) 'Receive recvstr = Left(buffer, InStr(1, buffer, Chr(10)) - 1) Print #1, Str(i) & "," & recvstr 'Write to the file Next Close #1 Call ibonl(pad, 0) End Sub

8.8 Sample Programs

(2) Measure Resistance by PC Key

Measures and imports by key input on the PC, and saves measurements in a text file.

Private Sub MeasureReadSub() Dim buffer As String * 13 'Receiving butter Dim recvstr As String 'Receiving char string Dim pad As Integer 'Controller access Dim gpibad As Integer 'Device Address Dim timeout As Integer 'Timeout period Dim ud As Integer 'State (unused) Dim i As Integer pad = 0'Board Address 0 gpibad = 1 '3541 Address 1 timeout = T10s 'Timeout about 10s 'Initialize GP-IB Call ibfind("gpib0", 0) Call ibdev(pad, gpibad, 0, timeout, 1, 0, ud) Call SendIFC(pad) Open App.Path & "\data.csv" For Output As #1 'Open a text file for saving Call Send(pad, gpibad, ":TRIG:SOUR IMM", NLend) 'Select internal triggering Call Send(pad, gpibad, ":INIT:CONT OFF", NLend) 'Continuous measurement OFF For i = 1 To 10 'Wait for PC key input 'Create a key input check routine to set InputKey() = True when a key is pressed Do While 1 If InputKey() = True Then Exit Do DoEvents Loop 'After confirming key input, measure once, and read the measured value Call Send(pad, gpibad, ":READ?", NLend) 'Send ":READ?" to measure and import the measurement Call Receive(pad, gpibad, buffer, STOPend) 'Receive recvstr = Left(buffer, InStr(1, buffer, Chr(10)) - 1) Print #1, Str(i) & "," & recvstr 'Write to the file Next Close #1 Call ibonl(pad, 0) End Sub

(3) External Trigger Measurement 1

Measure and import according to external triggering of the 3541 (TRIG key or EXT I/O TRIG terminal input), and save measurements in a text file.

| Private Sub MeasureTrigSub() | |
|---|---|
| Dim buffer As String * 13 | 'Receiving butter |
| Dim recvstr As String | 'Receiving char string |
| Dim pad As Integer | 'Controller access |
| Dim gpibad As Integer | 'Device Address |
| Dim timeout As Integer | 'Timeout period |
| Dim ud As Integer | 'State (unused) |
| Dim i As Integer | |
| oad = 0 | 'Board Address 0 |
| gpibad = 1 | '3541 Address 1 |
| imeout = T100s | 'Timeout 100s (because of external trigger wait state) |
| Call ibfind("gpib0", 0) Call ibdev(pad, gpibad, 0, timeout, 1, 0, ud) Call SendIFC(pad) | 'Initialize GP-IB |
| Dpen App.Path & "\data.csv" For Output As #1 | 'Open a text file for saving |
| Call Send(pad, gpibad, ":TRIG:SOUR EXT", NLend) | 'Select external triggering |
| Call Send(pad, gpibad, ":INIT:CONT OFF", NLend) | 'Continuous measurement OFF |
| Call Send(pad, gpibad, ":READ?", NLend) | 'Send ":READ?" to measure and import the measurement |
| Call Receive(pad, gpibad, buffer, STOPend) recvstr = Left(buffer, InStr(1, buffer, Chr(10)) - 1) | 'Receive |
| Print #1, Str(i) & "," & recvstr Next | 'Write to the file |
| Close #1 | |
| Call ibonl(pad, 0) | |
| End Sub | |

(4) External Trigger Measurement 2

Measure and import according to external triggering of the 3541 (TRIG key or EXT I/O TRIG terminal input), and save measurements in a text file.

(The 3541 imports the most recent measurement by trigger input timing with the continuous measurement state)

```
Private Sub MeasureTrig2Sub()
Dim buffer As String * 13
                                                                'Receiving butter
Dim recvstr As String
                                                                'Receiving char string
Dim pad As Integer
                                                                'Controller access
Dim gpibad As Integer
                                                                'Device Address
Dim timeout As Integer
                                                                'Timeout period
Dim ud As Integer
                                                                'State (unused)
Dim i As Integer
pad = 0
                                                                'Board Address 0
gpibad = 1
                                                                '3541 Address 1
timeout = T100s
                                                                'Timeout 100s (because of external trigger wait state)
Call ibfind("gpib0", 0)
                                                                'Initialize GP-IB
Call ibdev(pad, gpibad, 0, timeout, 1, 0, ud)
Call SendIFC(pad)
Open App.Path & "\data.csv" For Output As #1
                                                                'Open a text file for saving
                                                                'Select internal triggering
Call Send(pad, gpibad, ":TRIG:SOUR IMM", NLend)
Call Send(pad, gpibad, ":INIT:CONT ON", NLend)
                                                                'Continuous measurement ON
'Clear confirmation of External I/O TRIG input
Call Send(pad, gpibad, ":IO:IN?", NLend)
Call Receive(pad, gpibad, buffer, STOPend)
recvstr = Left(buffer, InStr(1, buffer, Chr(10)) - 1)
For i = 1 To 10
  'Wait for External I/O TRIG input
  Do While 1
    Call Send(pad, gpibad, ":IO:IN?", NLend)
    Call Receive(pad, gpibad, buffer, STOPend)
    If Left(buffer, 1) = "1" Then Exit Do
    DoEvents
  Loop
  Call Send(pad, gpibad, ":FETCH?", NLend)
                                                                'Send ":FETCH?" to import the most recent
                                                                measurement
  Call Receive(pad, gpibad, buffer, STOPend)
                                                                'Receive
  recvstr = Left(buffer, InStr(1, buffer, Chr(10)) - 1)
  Print #1, Str(i) & "," & recvstr
                                                                'Write to the file
Next
Close #1
Call ibonl(pad, 0)
End Sub
```

(5) Set Measurement State

Sets up the measurement setting state.

| 'Function: Resistance Measurement | |
|--|--|
| 'Range: 200 m Ω | |
| 'Sampling: SLOW2 | |
| 'Triggering: Internal | |
| 'Comparator: ON, HI/LO Mode, Beeper HL, Upper Threshold | 200000, Lower Threshold 100000 |
| Private Sub SettingsSub() | |
| Dim pad As Integer | 'Controller access |
| Dim gpibad As Integer | 'Device Address |
| Dim timeout As Integer | 'Timeout period |
| Dim ud As Integer | 'State (unused) |
| | |
| pad = 0 | 'Board Address 0 |
| gpibad = 1 | '3541 Address 1 |
| timeout = T10s | 'Timeout about 10s |
| Call ibfind("gpib0", 0) | 'Initialize GP-IB |
| Call ibdev(pad, gpibad, 0, timeout, 1, 0, ud) | |
| Call SendIFC(pad) | |
| | Indust Desistance for the |
| Call Send(pad, gpibad, ":FUNC RES", NLend) | 'Select Resistance function |
| Call Send(pad, gpibad, ":RES:RANG 200E-3", NLend) | Select 200 m Ω range |
| Call Send(pad, gpibad, ":SAMP:RATE SLOW2", NLend) | 'Select SLOW2 sampling |
| Call Send(pad, gpibad, ":TRIG:SOUR IMM", NLend) | 'Select internal triggering 'Continuous measurement OFF |
| Call Send(pad, gpibad, ":INIT:CONT OFF", NLend) Call Send(pad, gpibad, ":CALC:LIM:MODE HL", NLend) | |
| Call Send(pad, gpibad, "CALC:LIM:MODE HL, NLend) Call Send(pad, gpibad, ":CALC:LIM:BEEP HL", NLend) | 'From here on, comparator settings |
| Call Send(pad, gpibad, "CALC:LIM:UPP 200000", NLend) | |
| Call Send(pad, gpibad, "CALC:LIM:OFF 200000", NLend) | |
| Call Send(pad, gpibad, "CALC:LIM:LOW TOODOD, NLend) | 'Comparator ON |
| | |
| Call ibonl(pad, 0) | |
| End Sub | |
| | |
| | |
| | |
| | |

8.8 Sample Programs

Specifications Chapter 9

9.1 General Specifications

| Measurement functions | Four-terminal resistance measurement | $0.1~\mu\Omega$ (20m Ω range) to 110.000 M Ω |
|---------------------------------|--|---|
| | Low-power four-terminal resistance measurement | 10 $\mu\Omega$ (2 Ω range) to 2.00000 k Ω |
| | Temperature measurement (Pt) | -10.0 to 99.9°C |
| | Temperature measurement (analog input) | 0 to 2 V |
| | Temperature measurement (3444/3445+3909 via RS-232C) | -50.0°C to 500.0°C |
| Range switching function | Auto-ranging (AUTO indicator) | and Manual setting |
| Temperature correction function | Reference temperature setting range | -10 to +99.9°C |
| | Temperature coefficient setting range | -9999 to +9999 ppm |
| | Displayed values | -99,999 to +999,999 dgt |
| | Correction formula $R_{t0} = \frac{R_t}{1 + \alpha_{t0} \times (t - t_0)}$ | $\begin{array}{lll} R_t & \text{Actual measured resistance} & [\Omega] \\ R_{t0} & \text{Corrected resistance} & [\Omega] \\ t_0 & \text{Reference temp.} & [^\circ\text{C}] \\ t & \text{Ambient temperature} & [^\circ\text{C}] \\ \alpha_{t0} & \text{Temperature coefficient at } t_0 [1/^\circ\text{C}] \end{array}$ |
| Temperature | Display | Temp. increase ∆t |
| conversion function | Cold-state winding resistance setting range (R ₁) | 00.0000 m Ω to 110.000 M Ω |
| | Cold-state temperature setting range (t_1) | -10.0 to 99.9°C |
| | Reciprocal temp. coefficient setting range (k) | -999.9 to +999.9 |
| | Conversion formula | ∆t Temperature increase[°C] |
| | $\Delta t = \frac{R_2}{R_1} \left(k + t_1 \right) - \left(k + t_a \right)$ | t ₁ Winding temp. (cool state) when measuring initial resistance R1[°C] |
| | <u> </u> | t_a Ambient temp. at final measurement[°C] R ₁ Winding resistance at temp. t1 (cool state)[Ω] |
| | | R_2 Winding resistance at final measurement [Ω] |
| | | k Reciprocal of temp. coefficient of conductor material at 0°C[°C] |

9.1 General Specifications

| Zero-Adjust function | Zero-Adjus | st range | 1 | | 1,000 dgt in each range | | | | | | | |
|--|---|--|---------------|---|--|---------|---------|------------------------------|----------------------------|----------------------|-----------|----------|
| Sampling rate | SLOW2, S | SLOW2, SLOW1, MEDIUM or FAST | | | | | | | | | | |
| Self-Calibration Function | AUTO | MEDIL | JM and | FAST | Self-calibration occurs every 30 minutes | | | | | | | |
| Function (MEDIUM and FAST sampling) | | 2 and 1 | Self | Self-calibration occurs at every sample | | | | | | | | |
| (Occurs at power-on, and after switching | MANUAL | MEDIU | DIUM and FAST | | | -calibr | ation ι | upon ir | nput fro | om EX | (T I/O | terminal |
| measurement settings) | | SLOW SLOW | | | Self | -calibr | ation o | occurs | at eve | ery sai | mple | |
| Measurement fault detection | Function | Function Open-circuit SOURCE and SENSE wiring faults can always be observed. ERR output is present at the EXT I/O ter measurement fault is detected ErrCurr is displayed when the SOURCE ErrHi is displayed when the SENSE-H lir ErrLo is displayed when the SENSE-L lir | | | | | | O term RCE lii -H line | inal w ne is c is op | /hen a open en | t-current | |
| | Output timing SYNC or ASYNC SYNC: Synchronous with EOC output ASYNC: Asynchronous with EOC output | | | | | | | | | | | |
| Overflow detection function | OF or -OF appears when input exceeds the specified display range | | | | | | | | | | | |
| Offset Voltage Compensation function | ON or OF | = | | | | | | | | | | |
| Trigger function | Internal trig | gger | Trigg | ering o | occurs | intern | ally w | hen a | meası | ireme | nt is fi | nished |
| | External tr | igger | Trigg | TRIG a ering c kev, E | occurs | by an | - | | wing: TRG o | or GE | T com | mand |
| | When :INI before trig | | | • | | | | | | | | |
| Delay function | AUTO or MANUAL | | | | | | | | | | | |
| AUTO | Normal resistance measurement (Offset Voltage Compensation OFF) | | | | | | | | | | | |
| | Range [Ω] | | 200 m | | 20 | 200 | 2 k | | 100 k | 1 M | 10 M | 100 M |
| | Delay [ms] | 30 | 30 | 3 | 3 | 3 | 3 | 3 | 10 | 100 | 500 | 1000 |
| | Normal res | sistance | meas | ureme | ent (Of | fset Vo | oltage | Comp | ensati | on ON | 1) | |
| | Range [Ω | - | 200 m | | 20 | 200 | 2 k | 20 k | | | | |
| | Delay [ms] | 100 | 100 | 100 | 100 | 100 | 100 | 100 | J | | | |
| | Low-Power mode (Offset Voltage Compensation OFF) | | | | | | | | | | | |
| | Range [Ω] | - | 20 | 200 | 2 k | | | | | | | |
| | Delay [ms] 3 3 3 15 | | | | | | | | | | | |
| | Low-Powe | | • | | - | mpen | sation | ON) | | | | |
| | Range [Ω] | | 20 | 200 | 2 k | | | | | | | |
| | Delay [ms] | 100 | 100 | 100 | 100 | J | | | | | | |
| MANUAL | Delay: 0.0 | 00 to 9. | 999s | | | | | | | | | |

| Averaging | No. of samples to average | 2 to 100, OF | F | | | | | |
|-------------------------|---------------------------|--|---|--|--|--|--|--|
| | Averaging method | Integrating average However, with external triggering and continuous measure ON (Free-Run), the default averaging method is Moving Average | | | | | | |
| | Average (of meas | urements D1 to D6) with Averaging Samples set to 2. | | | | | | |
| | | | 1st Sample 2nd Sample 3rd Sample | | | | | |
| | Free-Run (Moving | | (D1+D2)/2 | (D2+D3)/2 | (D3+D4)/2 | | | |
| | Non-Free-Run (inte | egrating Avg.) | (D1+D2)/2 | (D3+D4)/2 | (D5+D6)/2 | | | |
| Statistical calculation | Setting | ON or OFF | | | | | | |
| | Calculations | Value (serial | | Deviation of S | serial no.), Maximum ample, Overall dices | | | |
| | Data importing | porting Statistical calculation occurs by any of the follor TRIG key, EXT I/O TRIG terminal, *TRG or GE | | | | | | |
| | Data count | Up to 30000 | | | | | | |
| Key-Lock function | ON or OFF | | | | | | | |
| Remote/Local function | Operation | is lit. | sHIFT →AUT | | s enabled, REMOTE es from Remote to | | | |
| Line frequency setting | 50 or 60 Hz | | | | | | | |
| SAVE/LOAD | Storage capacity | (No. of sets | of settings) 30 | | | | | |
| | Saved settings | Range Low-Power Measureme Zero-Adjus Temp. Corr ON/OFF Reference Temperatur Temp. Con ON/OFF Initial Resis Initial Temp Constant | Measurement Resistance ent Range t ON/OFF t Value rection Function Temperature re Coefficient version Function stance berature Calculation ON/O ate | ON/OFF Trigger S Delay AU Delay (tir Averagin No. of sa Key-Lock Compara Compara Compara Compara Method BIN ON/4 Each BIN BIN Thre FF BIN Com External | g ON/OFF imples to average ator ON/OFF ator Beeper ator Thresholds ator Comparison OFF I No. ON/OFF | | | |

9.1 General Specifications

| Comparator | Decision | Hi IN Lo | Display Value > Upper Threshold, or OF Upper Threshold \geq Display Value \geq Lower Threshold Lower Threshold > Display Value, or -OF | | | | |
|------------------|--|----------------------|--|--|--|--|--|
| | Absolute value decision | Display Upper/Lov | Absolute Value ver Threshold range: 0 to 999,999 dgt | | | | |
| | Relative value decision | | {(Measured Resistance) – (Reference Value)} / (Reference Value) -99.999% to 99.999% e Value setting: 0 to 999,999 dgt (%) setting: 00.000 to 99.999% | | | | |
| | Beeper | OFF, IN, Hi/Lo | | | | | |
| BIN measurements | Decision | IN | Upper Threshold \geq Display Value \geq Lower Threshold | | | | |
| | Absolute value decision | Display Upper/Lov | Absolute Value ver Threshold range: 0 to 999,999 dgt | | | | |
| | Relative value decision | | Absolute Value Value setting:0 to 999,999 dgt (%) setting: 00.000 to 99.999% | | | | |
| | BINs | 10 | | | | | |
| Reset function | Reset | Returns al | Il settings except SAVE data to factory defaults | | | | |
| | System Reset (Remote Command only) | Returns al | Il settings including SAVE data to factory defaults | | | | |

| Operating temperature and humidity | 0 to 40°C, 80% RH or less (non-condensating) |
|--|---|
| Storage temperature and humidity | -10 to 50°C, 80% RH or less (non-condensating) |
| Temperature and humidity range for guaranteed accuracy | 23 ±5°C, 80% RH or less (non-condensating) |
| Period of guaranteed accuracy | 1 year |
| Operating environment | Indoors, Up to 2000 m (6562 ft) ASL |
| Rated supply voltage | 100 to 240 V AC (with allowance for $\pm 10\%$ variation in line voltage) |
| Rated supply frequency | 50/ 60 Hz |
| Power consumption | 30 VA |
| Insulation withstand potential | 1.39 kV AC for 15s, Cutoff current 10 mA, between all power terminals and protective ground |
| Dimensions | Approx. 215W x 80H x 295D mm (8.46"W x 3.15"H x11.61"D) (sans protrusions) |
| Mass | Approx. 2.6 kg (91.7oz.) |
| Applicable Standards Safety | EN61010-1:2001 Overvoltage category II 300 V (anticipated transient overvoltage 2500 V) |
| EMC | EN61326:1997+A1:1998+A2:2001 EN61000-3-2:2000 EN61000-3-3:1995+A1:2001 Effect of radiated radio-frequency electromagnetic field: 1%f.s. at 3 V/m Effect of conducted radio-frequency electromagnetic field: 0.5%f.s. at 3V |
| Accessories | 9287 CLIP TYPE LEAD 1 9451 TEMPERATURE PROBE 1 Instruction Manual 1 Power Cord (2-line + ground) 1 EXT I/O Male Connector 1 |
| Options | 9452 CLIP TYPE LEAD 9453 FOUR TERMINAL LEAD 9454 ZERO ADJUSTMENT BOARD 9455 PIN TYPE LEAD (for ultra precision) 9461 PIN TYPE LEAD 9465 PIN TYPE LEAD 9467 LARGE CLIP TYPE LEAD 9300 CONNECTION CABLE (available soon) |
| | 9637 RS-232C CABLE (9-pin to 9-pin, crossover) 9638 RS-232C CABLE (9-pin to 25-pin, crossover) 9151-02 GP-IB CONNECTOR CABLE (2 m) 9151-04 GP-IB CONNECTOR CABLE (4 m) |
| | 9670 PRINTER (Sanei Electric Model BL-80RS II) 9671 AC ADAPTER (for 9670, Sanei Electric Model BL-100W) 9672 BATTERY PACK (for 9670) 9673 BATTERY CHARGER (for 9672) 9237 RECORDING PAPER (80 mm x 25 m, 4 rolls, for 9670) 9638 RS-232C CABLE (for 3541-9670) |

9.2 Accuracy

9.2 Accuracy

Resistance Measurement

- After zero adjustment
- No temperature correction
- Add temperature coefficient ±(1/10 of measurement accuracy) °C from 0 to 18 and from 28 to 40°C
- Warm-up time is 60 minutes (accuracy specifications are double from 30 to 60 min)
- For FAST and MEDIUM sampling, execute self-calibration after warm-up.

Temperature variation after warm-up should be within ±2°C.

• Add the value calculated below to the rdg error for resistance measurement accuracy when temperature correction is enabled:

$$\frac{-100 \alpha_{to} \Delta t}{1 + \alpha_{to} \times (t + \Delta t - t_0)}$$
 [%]

- t_0 Reference temp. [°C]
- t Ambient temp. [°C]
- $\begin{array}{lll} \Delta t & \text{Temp. measurement accuracy} \\ \alpha_{t0} & \text{Temp. coefficient at } t_0 & [1/^{\circ}C] \end{array}$
- Open-terminal voltage specifications in the following table may be momentarily exceeded when the probe is removed from the test object.

Resistance Measurement Function

| 1-year accuracy (23 ±5°C) (rdg = read value, f.s. = max. value, dgt. = resolu | | | | | | | | arts per million) |
|---|-------------------------|----|----------|--------------|----------------|-------------------|-------------|---------------------|
| Dence* | Denge* Displayed Values | | SLOW2 | SLOW1 | MEDIUM | FAST | Measurement | Open- |
| Range* | Displayed Values | | : | ±(ppm of rdg | . + ppm of f.s | s.) | Current | Terminal Voltage |
| 20m Ω | 20.0000 to -0.2000 | mΩ | 1000+150 | 1000+170 | 1000+200 | 1000+250 | 1 A ±5% | 5 Vmax |
| $200 \text{m}\Omega$ | 200.000 to -02.000 | mΩ | 1000+60 | 1000+80 | 1000+120 | 1000+170 | 1 A ±5% | 5 Vmax |
| 2 Ω | 2000.00 to -020.00 | mΩ | 140+40 | 140+60 | 140+100 | 140+150 | 100 mA ±5% | 2.6 Vmax |
| 20Ω | 20.0000 to -0.2000 | Ω | 100+40 | 100+60 | 100+100 | 100+150 | 10 mA ±5% | 2.6 Vmax |
| 200Ω | 200.000 to -02.000 | Ω | 80+15 | 80+30 | 80+40 | 80+100 | 10 mA ±5% | 2.6 Vmax |
| 2 kΩ | 2000.00 to -020.00 | Ω | 70+15 | 70+30 | 70+40 | 70+100 | 1 mA ±5% | 2.6 Vmax |
| 20k Ω | 20.0000 to -0.2000 | kΩ | 70+15 | 70+30 | 70+40 | 70+100 | 100 μA ±5% | 2.6 Vmax |
| 100 kΩ | 110.000 to -02.000 | kΩ | 70+30 | 70+60 | 70+80 | 70+200 | 100 μA ±5% | 13 Vmax |
| 1MΩ | 1100.00 to -020.00 | kΩ | 80+30 | 80+60 | 80+80 | 150+100 | 10 μA ±5% | 13 Vmax |
| 10MΩ | 11.0000 to -0.2000 | MΩ | 400+60 | 400+90 | 400+140 | 3000+200 | 1 μA ±5% | 13 Vmax |
| 100MΩ | 110.000 to -02.000 | MΩ | 2000+200 | 2000+230 | 2000+250 | 30000(3%) +300 | 100 nA ±5% | 13 Vmax |

*: 100 k Ω range and above are calculated as f.s. = 100,000 dgt.

Low Power Resistance Measurement Function

| 1-year a | accuracy (23 ±5°C) | | (rdę | g = read value | , f.s. = max. | value, dgt. = | resolution, ppm: | parts per millior |
|----------|--------------------|----|---------|----------------|---------------|---------------|------------------|-------------------|
| Range | Displayed Values | | SLOW2 | SLOW1 | MEDIUM | FAST | Measurement | Open- Terminal |
| - 0- | | | | ±(ppm of rdg | Current | Voltage * | | |
| 2Ω | 2000.00 to -020.00 | mΩ | 110+100 | 110+120 | 110+150 | 110+200 | 10 mA ±5% | 60 mVmax |
| 20Ω | 20.0000 to -0.2000 | Ω | 110+100 | 110+120 | 110+150 | 110+200 | 1 mA ±5% | 60 mVmax |
| 200Ω | 200.000 to -02.000 | Ω | 110+100 | 110+120 | 110+150 | 110+200 | 100 μA ±5% | 60 mVmax |
| 2 kΩ | 2000.00 to -020.00 | Ω | 110+100 | 110+120 | 110+150 | 200+200 | 10 μA ±5% | 60 mVmax |

*: When using external triggering, open-terminal voltage is limited to 20 mV maximum from when INDEX goes High until the next trigger input.

Temperature Measurement

| Temperature Sensor | |
|---------------------------|-----|
| HIOKI 9451 (PT500 (at 25° | C)) |

Accuracy

Pt Sensor

| Range of Guaranteed Accuracy | -10.0 to 39.9°C | 40.0 to 99.9°C |
|---------------------------------|-----------------------|-----------------------|
| Resolution | 0.1°C | 0.1°C |
| 6-Month Accuracy | ±0.30% rdg ±0.5.0°C*1 | ±0.30% rdg ±1.0°C*1 |
| 1-Year Accuracy | ±0.45% rdg ±0.8.0°C*1 | ±0.45% rdg ±1.5.0°C*1 |

*1: Accuracy is in combination with 9451 TEMPERATURE PROBE. Accuracy of instrument alone is ±0.2°C for 6 months (±0.3°C for 1 year). Add temperature coefficient ±0.02/°C to above accuracy for ambient temperature ranges 0 to 18 and 28 to 40°C.

Temperature measurement (analog input)

Accuracy

| 1-Year | |
|-------------|--------------------|
| Input Range | 0 to 2 V |
| Display | -99.9°C to 999.9°C |
| Resolution | 1 mV or better |
| Accuracy | ±1% rdg ±3 mV *2 |

*2: Temperature accuracy conversion method (Only 3541 instrument)

 $1\% \times (T_R - T_{0V}) + 0.3\% \times (T_{1V} - T_{0V})$

 $T_{1V} \ldots$ temperature @ 1-V input

 $T_{0V} \dots$ temperature @ 0-V input

T_R..... current temperature

Add temperature coefficient ($\pm 0.1\%$ rdg ± 0.3 mV)/°C to above accuracy for ambient temperature ranges 0 to 18 and 28 to 40°C.

Sampling _____

Resistance and Low-Power Resistance Measurement

| During | |
|-------------|--|
| measurement | |

(Trigger to EOC=ON)

| | | | | [ms] |
|----------------|--------|-------|--------|----------|
| Line Frequency | SLOW2 | SLOW1 | MEDIUM | FAST |
| 50Hz | 455±10 | 155±5 | 21±1 | 0.60±0.3 |
| 60 Hz | 449±10 | 149±5 | 17±1 | 0.60±0.3 |

 DELAY = 0 ms, OVC = OFF, TC = OFF, Statistical Calculation = OFF, Comparator = Hi/Lo

• With FAST and MEDIUM sampling settings, AUTO self-calibration (if enabled) occurs for 55 ±10 ms every 30 minutes.

During importing

(from INDEX=OFF to INDEX=ON)

| | | | | [|
|----------------|--------|-------|--------|----------|
| Line Frequency | SLOW2 | SLOW1 | MEDIUM | FAST |
| 50Hz | 400±10 | 100±5 | 20.0±1 | 0.30±0.1 |
| 60 Hz | 400±10 | 100±5 | 16.7±1 | 0.30±0.1 |

[ms]

Temperature Measurement

Sampling Rate: 400 ±10 ms

Chapter 10

Maintenance and Service

10.1 Inspection, Repair and Cleaning



NOTE

- Calibration and repair of this instrument should be performed only under the supervision of qualified technicians knowledgeable about the dangers involved.
- If damage is suspected, check the "Troubleshooting" section before contacting your dealer or Hioki representative.
- If no measurement value is displayed even when the probes are shorted together, an internal fuse may have blown. Blown internal fuses are not user-replaceable, so if this occurs, please contact your dealer or Hioki representative.

Transporting

Pack the instrument so that it will not sustain damage during shipping, and include a description of existing damage. We cannot accept responsibility for damage incurred during shipping.

Before returning for repair

| Symptom | Check Items | Countermeasure |
|---|---|---|
| The display does not appear when you turn the power on. | Is the power cord disconnected? | Reconnect the power cord. |
| Keys do not operate. | Is the unit in the key-locked state? | Disable the key-lock state. 5.10 Key-Lock Function (page 67) |
| | Is the instrument being remotely controlled externally using GP-IB? | Set GP-IB to local. |
| | Is the instrument being remotely controlled externally using RS-232C? | Set RS-232C to local. |
| An error is displayed. | | ✤ 10.2 Error Display (page 168) |
| Operation is abnormal. | | External electrical noise may occasionally cause malfunctions. If operation seems abnormal, try executing a Reset. 5.14 Reset Function (page 73) |



To clean the instrument, wipe it gently with a soft cloth moistened with water or mild detergent. Never use solvents such as benzene, alcohol, acetone, ether, ketones, thinners or gasoline, as they can deform and discolor the case.

10.2 Error Display

| Display | | Description |
|---------|--|--|
| Err02 | Zero-Adjust Range Error | The value before zero-adjustment exceeded 1,000 dgt. |
| Err10 | Execution Error | The data portion of a remote command is invalid. |
| Err11 | Command Error | The command portion of a remote command is invalid. |
| Err80 | Manual Adjustment Range Error | The valid adjustment range was exceeded during adjustment. |
| Err90 | ROM Error | An internal program error occurred. Repair is required. |
| Err91 | RAM Error | An internal RAM error occurred. Repair is required. |
| Err92 | EEPROM (Adjustment Data) Error | Adjustment data is corrupted. Repair is required. |
| Err95 | Resistance A/D Communications Error | The A/D converter used for resistance measurement is damaged. Repair is required. |
| Err96 | Temperature A/D Communications Error | The A/D converter used for temperature measurement is damaged. Repair is required. |
| ErrCur | Constant-Current Fault | |
| ErrHi | SENSE-H Open Circuit | |
| ErrLo | SENSE-L Open Circuit | |
| | Constant-Current Fault, SENSE-H (simultaneously. | Open Circuit and SENSE-L Open Circuit are occurring |

Appendix

Appendix 1 Four-Terminal (Voltage-Drop) Method

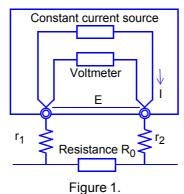
The Four-Terminal method is essential for measuring very small resistance values.

With two-terminal measurements (Fig. 1), the resistance of the test leads is included in the measured resistance, resulting in measurement errors.

The four-terminal method (Fig. 2) consists of current source terminals to provide constant current, and voltage detection terminals to detect voltage drop.

Because of the high input impedance of the voltmeter, measurement requires practically no current flow through the leads connecting the voltage detection terminals to the test object, practically eliminating the effects of lead and contact resistance on the measurement.

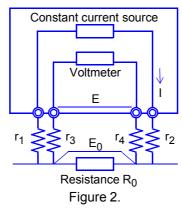
Two-Terminal Measurement Method



Measurement current I flows through test object resistance R_0 as well as lead resistances r_1 and r_2 .

The voltage to be measured is obtained by E = I(r_1 +R $_0$ + r_2), which includes lead resistances r_1 and r_2 .

Four-Terminal Measurement Method



All of measurement current I flows through test object resistance R_0 . So the voltage drop across r_3 and r_4 is practically nil, and voltage E across the measurement terminals and voltage E_0 across test object resistance R_0 are essentially equal, allowing test object resistance to be measured without being affected by r_1 to r_4 .

Appendix 2 Temperature Correction Function (TC)

Temperature correction employs the temperature coefficient of a material to convert its resistance measured at one temperature to the value it would have at any other temperature, for display. Because resistance is fundamentally temperature-dependent, measuring it without considering the temperature can provide meaningless results.

Resistances R_t and R_{t0} below are the resistance values of the test object (having resistance temperature coefficient at t₀°C of α_{t0}) at t°C and t₀°C.

 $R_{t} = R_{t0} \times \{1 + \alpha_{t0} \times (t - t_{0})\}$

 R_t Actual measured resistance [Ω]

- R_{t0} Corrected resistance [Ω]
 - t₀ Reference temperature [°C]
 - t Ambient temperature [°C]
 - α_{t0} Temperature coefficient at t₀ [1/°C]
- **Example** If a copper test object (with resistance temperature coefficient of 3930 ppm) measures 100 Ω at 30°C, its resistance at 20°C is calculated as follows:

$$R_{t0} = \frac{R_1}{1 + \alpha_{t0} \times (t - t_0)}$$

= $\frac{100}{1 + (3930 \times 10^{-6}) \times (30 - 20)}$
= 96.22

Refer to the following for temperature correction settings and execution method:

- Making Temperature Correction Settings (Reference Temperature and Temperature Coefficient) (Page 58)
- Enabling/Disabling Temperature Correction (Page 59)
- Reference (Page 171)

NOTE

- The temperature probe detects only ambient temperature; not surface temperature.
- Before measuring, allow the instrument and temperature probe to warm up completely, place the temperature probe as close to the test object as possible, and allow sufficient time for them to stabilize at ambient temperature.

Reference_

| Material | Content [%] | Density (x10 ³) [kg/m ³] | Conductivity | Temp. Coeff. (20°C) [ppm] |
|-----------------------------|---|--|------------------------------|------------------------------|
| Annealed copper wire | Cu>99.9 | 8.89 | 1.00 to 1.02 | 3810 to 3970 |
| Hard-drawn copper wire | Cu>99.9 | 8.89 | 0.96 to 0.98 | 3770 to 3850 |
| Cadmium copper wire | Cd 0.7 to 1.2 | 8.94 | 0.85 to 0.88 | 3340 to 3460 |
| Silver copper | Ag 0.03 to 0.1 | 8.89 | 0.96 to 0.98 | 3930 |
| Chrome copper | Cr 0.4 to 0.8 | 8.89 | 0.04 to 0.05 0.80 to 0.85 | 20 30 |
| Carlson alloy wire | Ni 2.5 to 4.0 Si 0.5 to 1.0 | | 0.25 to 0.45 | 980 to 1770 |
| Annealed aluminum wire | Al>99.5 | 2.7 | 0.63 to 0.64 | 42 |
| Hard-drawn aluminum wire | Al>99.5 | 2.7 | 0.60 to 0.62 | 40 |
| Aldrey wire | Si 0.4 to 0.6 Mg 0.4 to 0.5 Al remaining portion | | 0.50 to 0.55 | 36 |

Conductive Properties of Metals and Alloys

Copper Wire Conductivity

| Diameter [mm] | Annealed copper wire | Tinned annealed copper wire | Hard-drawn copper wire |
|------------------------|-------------------------|--------------------------------|---------------------------|
| 0.01 to less than 0.26 | 0.98 | 0.93 | — |
| 0.26 to less than 0.50 | 0.993 | 0.94 | 0.96 |
| 0.50 to less than 2.00 | 1.00 | 0.96 | 0.96 |
| 2.00 to less than 8.00 | 1.00 | 0.97 | 0.97 |

The temperature coefficient changes according to temperature and conductivity, so if the temperature coefficient at 20°C is α_{20} and the temperature coefficient for conductivity C at t°C is α_{ct} , α_{ct} is determined as follows near ambient temperature.

$$\alpha_{ct} = \frac{1}{\frac{1}{\alpha_{20} \times C} + (t - 20)}$$

For example, the temperature coefficient of international standard annealed copper is 3930 ppm @20°C. For tinned annealed copper wire (with diameter from 0.10 to less than 0.26 mm), the temperature coefficient α_{20} at 20°C is calculated as follows:

$$\alpha_{20} = \frac{1}{\frac{1}{0.00393 \times 0.93} + (20 - 20)} \approx 3650 \text{ ppm}$$

Appendix 3 Temperature Conversion Function (Δt)

Utilizing the temperature-dependent nature of resistance, the temperature conversion function converts resistance measurements for display as temperatures. This method of temperature conversion is described here.

According to IEC standard 60034, the resistance law may be applied to determine temperature increase as follows:

$$\Delta t = \frac{R_2}{R_1} (k + t_1) - (k + t_a)$$

Г

- ∆t Temperature increase [°C]
- t_1 Winding temp. [°C, cool state] when measuring initial resistance R_1
- t_a Ambient temp. [°C] at final measurement
- R_1 Winding resistance [Ω] at temp. t_1 (cool state)
- R_2 Winding resistance [Ω] at final measurement
- k Reciprocal [°C] of temp. coefficient of conductor material at 0°C
- **Example** With initial resistance R_1 of 200 m Ω at initial temperature t_1 of 20°C, and final resistance R_2 of 210 m Ω at current ambient temperature t_a of 25°C, the temperature increase value is calculated as follows:

$$\Delta t = \frac{R_2}{R_1} (k + t_1) - (k + t_a)$$

= $\frac{210 \times 10^{-3}}{200 \times 10^{-3}} (235 + 20) - (235 + 25)$

 $= 7.75^{\circ}C$

Therefore, the current temperature t_{R} of the resistive body can be calculated as follows:

$$t_R = t_a + \Delta t = 25 + 7.75 = 32.75^{\circ}$$
C

For a test object that is not copper or aluminum with a temperature coefficient of α_{t0} , the constant k can be calculated using the formula shown for the temperature correction function and the above formula, as follows:

$$k = \frac{1}{\alpha_{t0}} - t_0$$

For example, the temperature coefficient of copper at 20° C is 3930 ppm, so the constant k in this case is as follows, which shows almost the same value as the constant for copper 235 defined by the IEC standard.

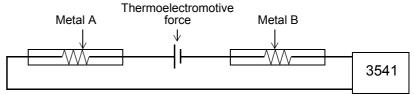
$$k = \frac{1}{3930 \times 10^{-6}} - 20 = 234.5$$

Appendix 4 Effect of Thermoelectromotive Force

Thermoelectromotive force is the potential difference that occurs at the junction of two dissimilar metals, which if sufficiently large, can cause erroneous measurements. Because this instrument functions by measuring potential difference while applying a constant direct current through the test object, the effect of thermoelectromotive force can affect measurements. The amplitude of thermoelectromotive force depends on the temperature of the measurement environment, with the force generally being greater at higher temperature.

Thermoelectromotive force typically occurs at any junction of dissimilar metals, including between the test probe tips and the test object.

The following diagram illustrates thermoelectromotive force.



Measurement discrepancy caused by thermoelectromotive force:

Example If the amplitude of electromotive force is 10 μ V and the resistance to be measured is 2 Ω , the measurement current of the LP 2 Ω range is 10 mA, and

the actual measured value displayed on the instrument is as follows: (2 Ω x 10 mA + 10 μ V) ÷ 10 mA = 2.00100 Ω

The effect of this thermoelectromotive force can be suppressed by enabling this instrument's Offset Voltage Compensation (OVC) function.

In the 2 Ω range and higher, a measurement R_{ON} is first taken with measurement current on, then the current is switched off and another measurement R_{OFF} is taken, with the true measurement value calculated by R_{ON} – R_{OFF} for display.

In the 20m Ω and 200m Ω ranges, the following value is displayed as the true resistance obtained from the value $R_P(>0)$ measured with measurement current flowing in the positive direction and the value $R_N(<0)$ measured with measurement current flowing in the negative direction.

$$\frac{R_p - R_N}{2}$$
 (R_N is a negative value)

Appendix 4 Effect of Thermoelectromotive Force

With inductive test objects such as a power transformers or solenoid coils, the following stabilization time is required to achieve a steady-state level after current is applied.

When using the Offset Voltage Compensation (OVC) function, presume 10 times the calculation voltage when setting the delay.

$$t = -\frac{L}{R} \ln\left(1 - \frac{IR}{V_0}\right)$$

L Inductance of test object

- R Resistance of test object + test leads + contacts
- I Measurement current (refer to 9.2 Accuracy (Page 164))
- V_O Open-terminal voltage (refer to 9.2 Accuracy (Page 164))

Appendix 5 JEC 2137-Compliant Resistance Measurement of Inductive Machines

Standard JEC 2137 specifies the determination of resistance values according to the following formula:

$$\begin{split} R_{t_R} &= R_{t_T} \times \frac{t_R + k}{t_T + k} & \text{Formula 1} \\ R_{tR} & \text{Winding resistance at reference temperature } t_R \\ R_{tT} & \text{Measured value of winding resistance at } t_T \\ t_0 & \text{Reference temperature } [^{\circ}C] \\ t_T & \text{Temperature of winding during measurement } [^{\circ}C] \\ k & \text{Constant (235 for copper wire)} \end{split}$$

Transforming Formula 1 provides the following:

$$\frac{R_{t_R}}{R_{t_T}} = \frac{t_R + k}{t_T + k} = \frac{1}{1 + \frac{1}{t_R + k}(t_T - t_R)}$$
 Formula 2

On the other hand, Formula 3 shows the temperature correction process with the 3541.

So the temperature coefficient to be set is determined as shown in Formula 4.

$$R_{t_R} = \frac{R_{t_T}}{1 + \alpha_{t_R} \times (t_T - t_R)}$$
 Formula 3
$$\alpha_{t_R} = \frac{1}{t_R + k}$$
 Formula 4

For example, if the reference temperature is 20°C, set the temperature coefficient for the instrument as follows.

$$\alpha_{t_R} = \frac{1}{t_R + k} = \frac{1}{20 + 235} = 3922 \text{ [ppm/deg]}$$

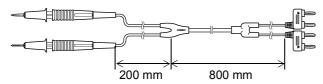
Appendix 6 Test Lead Options

9452 CLIP TYPE LEAD

The probes have pincer-type tips.

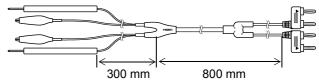
terminals and connectors.

Bifurcation-to-probe length: approx. 200 mm Plug-to-bifurcation length: approx. 800 mm



9453 FOUR TERMINAL LEAD

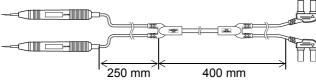
The SOURCE leads of this four-terminal lead set have Allows reliable four-terminal measurements even on covered alligator clips, and the SENSE leads have test objects with small contacts such as relay standard test probes. Use for measuring printed circuit board pattern resistance, and where SOURCE and SENSE leads need to be connected separately. Bifurcation-to-probe length: approx. 300 mm Plug-to-bifurcation length: approx. 800 mm



9455 PIN TYPE LEAD

The probe tips have a four-terminal structure These probes are designed to be pressed on flat even with very small test objects.

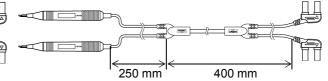
Bifurcation-to-probe length: approx. 250 mm Plug-to-bifurcation length: approx. 400 mm



9461 PIN TYPE LEAD

designed for checking for floating IC leads on printed contact surfaces unsuitable for clipping, or for test circuit boards. Correct measurements are obtained objects with small contact areas such as relay terminals and connectors.

> Bifurcation-to-probe length: approx. 250 mm Plug-to-bifurcation length: approx. 400 mm

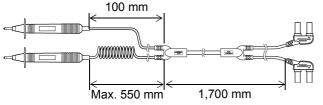


9465 PIN TYPE LEAD

These leads are ideal for large test objects for which These leads are designed to attach to test object with clip leads are unsuitable.

Four-terminal measurements are made just by can be made just by clipping. pressing the tips on the test object.

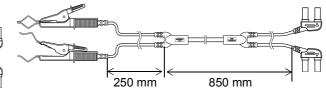
Bifurcation-to-probe length: approx. 100 mm (Coiled-cord lead: approx. 550 mm max.) Plug-to-bifurcation length: approx. 1700 mm



9467 LARGE CLIP TYPE LEAD

large diameter contacts. Four-terminal measurements

Bifurcation-to-probe length: approx. 250 mm Plug-to-bifurcation length: approx. 850 mm Maximum clip diameter: approx. 29 mm



Appendix 6 Test Lead Options

9454 ZERO ADJUSTMENT BOARD

The Zero-Adjust board is used to provide zeroadjustment when using the 9461 PIN TYPE LEAD and 9465 PIN TYPE LEAD. This board has a 2-layer structure consisting of a printed board and steel plate, so the pin-type leads can be shorted together only by pressing the pin tips into the specified contact holes. This board is not used for the 9465 PIN TYPE LEAD. Dimensions: 214W x 24H x 8D mm

| ()• | 0 | ٥ | 0 | 0 | 0 | 0 | 0 | ٥ | ا | 0 | 0 | 0 | ٥ | 0 | 0 | ٥ | ۰ | • 🚱 |
|-------------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|-----|

WARNING

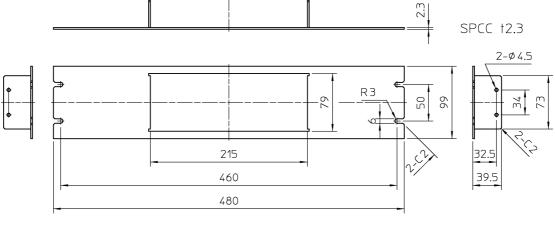
Appendix 7 Rack Mounting

By removing the screws on the sides, this instrument can be installed in a rack mounting plate.

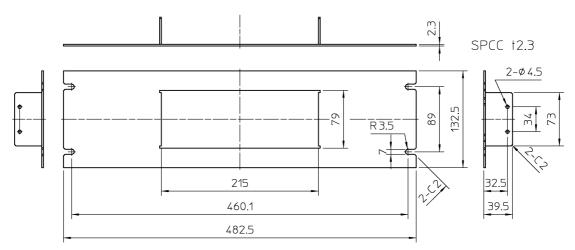
Observe the following precautions regarding the mounting screws to avoid instrument damage and electric shock accidents.

- When installing the Rack Mounting Plate, the screws must not intrude more than 6 mm into either side of the instrument.
- When removing the Rack Mounting Plate to return the instrument to stand-alone use, replace the same screws that were installed originally. (Feet: M3 x 6 mm, Sides: M4 x 6 mm)

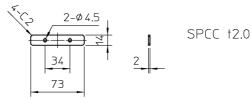
Rack Mounting Plate Template Diagram and Installation Procedure



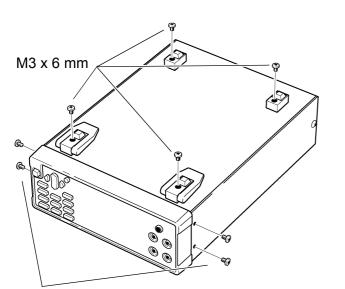
Rack Mounting Plate (JIS)



Rack Mounting Plate (EIA)

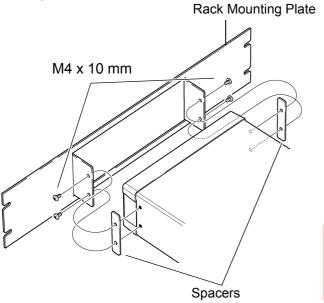


Spacer (Two Required)



1. Remove the feed from the bottom of the instrument, and the screws from the sides (four near the front).

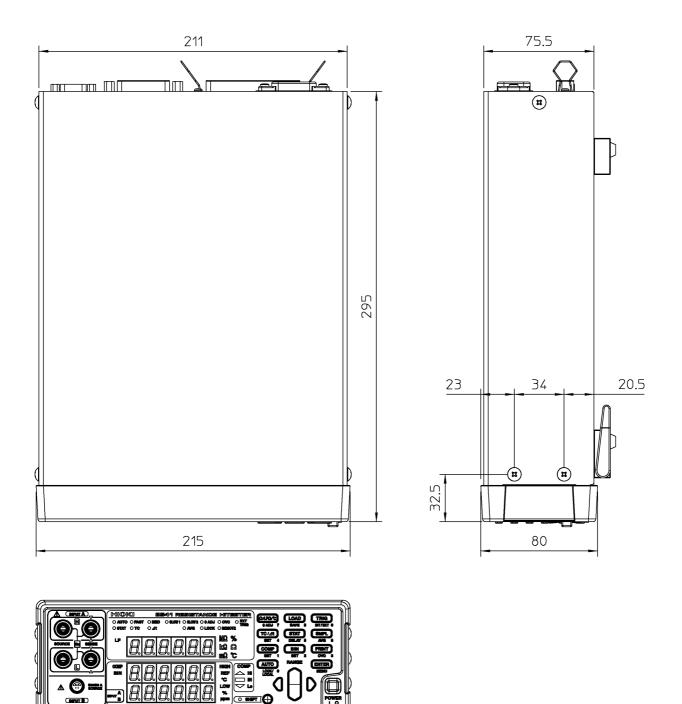
M4 x 6 mm



2. Installing the spacers on both sides of the instrument, affix the Rack Mounting Plate with the M4 x 10 mm screws.

When installing into the rack, reinforce the installation with a commercially available support stand.

Appendix 8 Dimensional Diagram



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ΗΙΟΚΙ

DECLARATION OF CONFORMITY

| Manufacturer's Name: | HIOKI E.E. CORPORATION |
|-------------------------|---|
| Manufacturer's Address: | 81 Koizumi, Ueda, Nagano 386-1192, Japan |
| Product Name: | RESISTANCE HITESTER |
| Model Number: | 3541 |
| Accessories: | 9287 CLIP TYPE LEAD 9451 TEMPERATURE PROBE |
| Options: | 9452 CLIP TYPE LEAD 9453 FOUR TERMINAL LEAD 9455 PIN TYPE LEAD 9461 PIN TYPE LEAD 9465 PIN TYPE LEAD 9467 LARGE CLIP TYPE LEAD |

The above mentioned products conform to the following product specifications:

EN61010-1:2001

| Safety: | |
|---------|--|
| EMC: | |
| | |
| | |

EN61326:1997+A1:1998+A2:2001 Class B equipment Minimum immunity test requirement

EN61000-3-2:2000 EN61000-3-3:1995+A1:2001

Supplementary Information:

The products herewith comply with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC.

HIOKI E.E. CORPORATION

i Kicki

Yuji Hioki

President

3541A999-00

<u>17 October 2003</u>

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