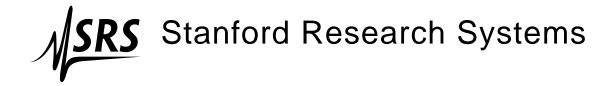
Diode Temperature Monitor

SIM922



Certification

Stanford Research Systems certifies that this product met its published specifications at the time of shipment.

Warranty

This Stanford Research Systems product is warranted against defects in materials and workmanship for a period of one (1) year from the date of shipment.

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General Information

The SIM922 Diode Temperature Monitor, part of Stanford Research Sysetems' Small Instrumentation Modules family, consists of four channels of sensor excitation and readout for precision low-noise diode thermometry. Independent $10\,\mu\text{A}$ DC current sources provide sensor excitations to the four-wire measurement circuits.

Service

Do not install substitute parts or perform any unauthorized modifications to this instrument.

The SIM922 is a single-wide module designed to be used inside the SIM900 Mainframe. Do not turn on the power until the module is completely inserted into the mainframe and locked in place.

iv General Information

Symbols you may Find on SRS Products

Symbol	Description
\sim	Alternating current
	Caution - risk of electric shock
<i></i>	Frame or chassis terminal
A	Caution - refer to accompanying documents
Ţ	Earth (ground) terminal
	Battery
\sim	Fuse
	On (supply)
	Off (supply)



General Information v

Notation

The following notation will be used throughout this manual:

- Front-panel buttons are set as [Button]; [Adjust] is shorthand for "[Adjust] & [Adjust]".
- Front-panel indicators are set as *Overload*.
- Remote command names are set as *IDN?.
- Literal text other than command names is set as OFF.



vi General Information

Specifications

Performance Characteristics

		Min	Тур	Max	Units
Inputs	Number of inputs		4		
	Sensor type	Si	licon d	iode	
	Measurement type		4–wire		
	Excitation	con	stant c	urrent	
		9.999	10	10.001	μA DC,
					±5 ppm/°C
Sensor Characteristics	Sensor units			Volts	±5 ppm/°C V Ω curves points K (typical)
	Input Range	0		2.5	V
	sensor+lead resistance			1400	Ω
	Calibration curves	1 built-in			
		4 user defined		defined cı	ırves
	Curve size (each)			256	points
	Temperature range	1.4		475	K (typical)
			senso	or depend	K (typical)
Measurement	Display resolution		4		
	Interface resolution		1		μV
			1		mK
	Measurement resolution		1.2		μV rms
	Measurement accuracy, $(23 \pm 1)^{\circ}$ C	20	$\mu V + 0$	0.01 %	
	Temperature coefficient	-5		+5	ppm/°C
Operating	Temperature	0		40	°C
	Power		±15,+	-5	V DC
	Supply current	50 (±1	5 V), 2	50 (+5 V)	mA

General Characteristics

Interface	Serial (RS-232) through SIM interface		
Connectors	2 DB–9 (female)		
	4–wire measurement + ground (Ch 1 & 2)		
	4–wire measurement + ground (Ch 3 & 4)		
	DB-15 (male) SIM interface		
Weight	1.4 lbs		
Dimensions	1.5" W × 3.6" H × 7.0" D		



1 Getting Started

This chapter gives you the necessary information to get started quickly with the SIM922 Diode Temperature Monitor.

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1.1	Introduction to the Instrument			
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1 – 2 Getting Started

1.1 Introduction to the Instrument

The SIM922 Diode Temperature Monitor monitors up to four (4) silicon diode thermometers using a precision $10 \,\mu\text{A}$ DC current excitation.

1.1.1 Overview

Each channel has an independent, precision $10\,\mu\text{A}$ current source, so the excitation to the user's sensor remains steady as the SIM922 cycles between measurements. Disabling a channel switches that channel's current source off.

A precision 24-bit analog-to-digital converter is cycled between the channels with a rate of 4 conversions per second. With all channels enabled, a complete cycle is completed every second; disabling some channels yields a corresponding increase in overall cycle rate.

1.2 Front-Panel Operation

The front panel of the SIM922(see Figure 1.1) provides a simple operator interface.





Figure 1.1: The SIM922 front and rear panels.



1.3 Sensor Interface 1 – 3

1.2.1 Excitation

The four channels of the SIM922 Diode Temperature Monitor can be independently enabled or disabled from the front panel. Disabling a channel turns off the $10 \,\mu\text{A}$ excitation current to that sensor, and speeds the readout rate for the remaining (enabled) channels.

To toggle the excitation for a channel, first briefly press [Excitation]. One of the four channel displays will appear highlighted, indicating which channel is selected. Briefly tap [Excitation] to advance the highlighted selection until the desired channel is selected. Then depress *and hold* [Excitation] until the display switches between the numerical value and the word $D \not\vdash F$.

1.2.2 Units

The SIM922 displays the sensor results either as resistance (in ohms) or temperature (in kelvin). Pressing [Units] toggles between these two modes; the active units are indicated by the illuminated K or Ω .

When temperature units are selected, a sensor calibration curve is required. The SIM922 is preprogrammed with a standard curve for Si diode sensors. Each channel also has non-volatile memory to store a separate sensor curve with up to 256 temperature-vs-resistance points. The actual curve to use is selected with the remote interface CURV command.

1.3 Sensor Interface

The sensor interface on the SIM922 consists of two rear-panel DB–9/F connectors, labeled "CHANNELS 1 & 2" and "CHANNELS 3 & 4" (see Figure 1.1). Both connectors follow the same pinout, given in Table 1.1

Signal
I+, Ch 1(3)
I-, Ch 1(3)
ground
I+, Ch 2(4)
I-, Ch 2(4)
V+, Ch 1(3)
V-, Ch 1(3)
V+, Ch 2(4)
V-, Ch 2(4)

Table 1.1: SIM922 Sensor Interface Connector Pin Assignments, DB-9



1 – 4 Getting Started

1.3.1 Four-wire measurement

To avoid sensitivity to wiring lead resistance, the SIM922 is configured for four-wire measurements. The basic circuit for this wiring scheme is shown in Figure 1.2.

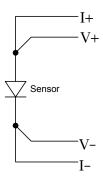


Figure 1.2: Wiring diagram for four-wire readout.

1.3.2 Two-wire measurement

If application-specific constraints limit the number of leads to the sensor, the SIM922 can be wired to measure the sensor resistance with a simple two-wire circuit, shown in Figure 1.3. Note that the lead resistance (past the junction points of the current and voltage leads) will add as a direct resistance error when measuring the sensor.

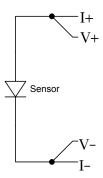


Figure 1.3: Wiring diagram for two-wire readout.

1.4 SIM Interface

The primary connection to the SIM922 Diode Temperature Monitor is the rear-panel DB–15 SIM interface connector. Typically, the SIM922 is mated to a SIM900 Mainframe via this connection, either through one of the internal Mainframe slots, or the remote cable interface.



1.4 SIM Interface 1 – 5

It is also possible to operate the SIM922 directly, without using the SIM900 Mainframe. This section provides details on the interface.

1.4.1 SIM interface connector

The DB–15 SIM interface connector carries all the power and communications lines to the instrument. The connector signals are specified in Table 1.2

		Direction	
Pin	Signal	$Src \Rightarrow Dest$	Description
1	SIGNAL_GND	$MF \Rightarrow SIM$	Ground reference for signal
2	-STATUS	$SIM \Rightarrow MF$	Status/service request (GND=asserted, +5V=idle)
3	RTS	$MF \Rightarrow SIM$	HW Handshake (+5 V=talk; GND=stop)
4	CTS	$SIM \Rightarrow MF$	HW Handshake (+5 V=talk; GND=stop)
5	-REF_10MHZ	$MF \Rightarrow SIM$	10 MHz reference (optional connection)
6	-5V	$MF \Rightarrow SIM$	Power supply (No connection in SIM922)
7	-15V	$MF \Rightarrow SIM$	Power supply (analog circuitry)
8	PS_RTN	$MF \Rightarrow SIM$	Power supply return
9	CHASSIS_GND		Chassis ground
10	TXD	$MF \Rightarrow SIM$	Async data (start bit="0"=+5 V; "1"=GND)
11	RXD	$SIM \Rightarrow MF$	Async data (start bit="0"=+5 V; "1"=GND)
12	+REF ₋ 10MHz	$MF \Rightarrow SIM$	10 MHz reference (optional connection)
13	+5V	$MF \Rightarrow SIM$	Power supply (digital circuitry)
14	+15V	$MF \Rightarrow SIM$	Power supply (analog circuitry)
15	+24V	$MF \Rightarrow SIM$	Power supply (No connection in SIM922)

Table 1.2: SIM Interface Connector Pin Assignments, DB-15

1.4.2 Direct interfacing

The SIM922 is intended for operation in the SIM900 Mainframe, but users may wish to directly interface the module to their own systems without the use of additional hardware.

The mating connector needed is a standard DB–15 receptacle, such as Amp part # 747909-2 (or equivalent). Clean, well-regulated supply voltages of +5, ±15 VDC must be provided, following the pin-out specified in Table 1.2. Ground must be provided on pins 1 and 8, with chassis ground on pin 9. The –STATUS signal may be monitored on pin 2 for a low-going TTL-compatible output indicating a status message.

The SIM922 has no internal protection against reverse polarity, missing supply, or overvoltage on the power supply pins.



1 – 6 Getting Started

1.4.2.1 Direct interface cabling

If the user intends to directly wire the SIM922 independent of the SIM900 Mainframe, communication is usually possible by directly connecting the appropriate interface lines from the SIM922 DB–15 plug to the RS-232 serial port of a personal computer. Connect RXD from the SIM922 directly to RD on the PC, TXD directly to TD, and similarly RTS→RTS and CTS→CTS. In other words, a null-modem style cable is *not* needed.

To interface directly to the DB–9 male (DTE) RS-232 port typically found on contemporary personal computers, a cable must be made with a female DB–15 socket to mate with the SIM922, and a female DB–9 socket to mate with the PC's serial port. Separate leads from the DB–15 need to go to the power supply, making what is sometimes know as a "hydra" cable. The pin-connections are given in Table 1.3.

DB-15/F to SIM922	Name
DB-9/F	1
$3 \longleftrightarrow \overline{7}$	RTS
$4 \longleftrightarrow 8$	CTS
$10 \longleftrightarrow 3$	TxD
$11 \longleftrightarrow 2$	RxD
5	Computer Ground
to P/S	
$7 \longleftrightarrow \overline{-15 \mathrm{V}}$	DC
$14 \longleftrightarrow +15 \text{ V}$	DC
$13 \longleftrightarrow +5 \text{ VE}$	OC .
8,9 ←→ Groun	nd (P/S return current)
1 ←→ Signal	Ground (separate wire to Ground)

Table 1.3: SIM922 Direct Interface Cable Pin Assignments

1.4.2.2 Serial settings

The initial serial port settings at power-on are: 9600 Baud, 8–bits, no parity, 1 stop bit, and RTS/CTS flow control. These may be changed with the BAUD, FLOW, or PARI commands.

The maximum *standard* baud rate that the SIM922 supports is 38400. The minimum baud rate is 110. Above 38400, the SIM922 can be



¹ Although the serial interface lines on the DB-15 do not satisfy the minimum voltage levels of the RS-232 standard, they are typically compatible with desktop personal computers

1.4 SIM Interface 1 – 7

set to the following (non-RS-232-standard) baud rates: 62500, 78125, 104167, 156250. Note that these rates are typically not accessible on a standard PC RS-232 port, but can be used between the SIM922 and the SIM900 Mainframe.



1 – 8 Getting Started



2 Remote Operation

This chapter describes operating the SIM922 over the serial interface. \\

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2 – 2 Remote Operation

2.1 Index of Common Commands

symbol	definition
i,j	Integers
f,g	Floating-point values
С	Channel number $(0-4)$; $c=0$ means "all"
Z	Literal token
S	Arbitrary character sequence (no "," or ";")
(?)	Required for queries; illegal for set commands
var	Parameter always required
{ <i>var</i> }	Required parameter for set commands; illegal for queries
[var]	Optional parameter for both set and query forms

Readout		
VOLT? c [,n]	2 - 9	Voltage Value
TVAL? c [,n]	2 - 9	Temperature Value
SOUT	2 – 9	Stop Streaming
Excitation		
$EXON(?)\ c\ \{,z\ \}$	2 – 9	Excitation On/Off
Display& Configu	uration	
DISX(?) {z}	2 - 10	Display Enable/Disable
$DTEM(?) \{z\}$	2 - 10	Display Temperature
FPLC(?) { <i>i</i> }	2 – 10	Frequency of Power Line Cycle

CINI(?) c {,z,s }	2 – 10 Initialize Sensor Calibration
CAPT c,f,g	2 – 11 Add User Curve Point
CAPT? c,j	2 – 11 Query User Curve Point

CURV(?) c {,z} 2 – 11 Select Sensor Curve

Serial Communications

BAUD(?) { <i>i</i> }	2 – 11 Baud Rate
FLOW(?) { <i>z</i> }	2 – 12 Flow Control
PARI(?) { <i>z</i> }	2 – 12 Parity

Status

*CLS	2 – 12 Clear Status
*STB? [i]	2 – 12 Status Byte
*SRE(?) [<i>i</i> ,] { <i>j</i> }	2 – 12 Service Request Enable
*ESR? [<i>i</i>]	2 – 12 Standard Event Status
*ESE(?) [i,] {i }	2 – 12 Standard Event Status Enable



CESR? [i]	2 – 12 Communication Error Status
CESE(?) [i,]{j}	2 – 13 Communication Error Status Enable
OVSR? [i]	2 – 13 Overload Status
OVSE(?) [i,]{j}	2 – 13 Overload Status Enable
PSTA(?) {z}	2 – 13 Pulse –STATUS Mode

Interface

*RST	2 – 13 Reset
CONS(?) {z}	2 – 13 Console Mode
*IDN?	2 – 14 Identify
*OPC(?)	2 – 14 Operation Complete
LEXE?	2 – 14 Execution Error
LCME?	2 – 15 Device Error
LDDE?	2 – 15 Device Error
LBTN?	2 – 15 Button
$TOKN(?) \{z\}$	2 – 15 Token Mode
$TERM(?) \{z\}$	2 – 16 Response Termination



2 – 4 Remote Operation

2.2 Alphabetic List of Commands

*	
*CLS	2 – 12 Clear Status
*ESE(?) [i,] {j}	2 – 12 Standard Event Status Enable
*ESR? [i]	2 – 12 Standard Event Status
*IDN?	2 – 14 Identify
*OPC(?)	2 – 14 Operation Complete
*RST	2 – 13 Reset
*SRE(?) [i,] {j}	2 – 12 Service Request Enable
*STB? [i]	2 – 12 Status Byte
В	
	2 11 D 1 D
BAUD(?) { <i>i</i> }	2 – 11 Baud Rate
C	
CAPT c,f,g	2 – 11 Add User Curve Point
CAPT? c,j	2 – 11 Query User Curve Point
CESE(?) [i,]{j}	2 – 13 Communication Error Status Enable
CESR? [i]	2 – 12 Communication Error Status
CINI(?) c {,z,s }	2 – 10 Initialize Sensor Calibration
$CONS(?) \{z\}$	2 – 13 Console Mode
$CURV(?) c \{,z\}$	2 – 11 Select Sensor Curve
D	
DISX(?) {z}	2 – 10 Display Enable/Disable
$DTEM(?) \{z\}$	2 – 10 Display Temperature
-	
E	
$EXON(?) \ c \{,z \}$	2 – 9 Excitation On/Off
F	
FLOW(?) {z}	2 – 12 Flow Control
FPLC(?) { <i>i</i> }	2 – 10 Frequency of Power Line Cycle
	2 To Trequency of Fower Zine Cycle
L	
LBTN?	2 – 15 Button
LCME?	2 – 15 Device Error
LDDE?	2 – 15 Device Error
LEXE?	2 – 14 Execution Error
0	
	2 – 13 Overload Status Enable
	2 – 10 Overioau Status Effable



OVSR? [i]	2 – 13 Overload Status
P	
PARI(?) { <i>z</i> }	2 – 12 Parity
PSTA(?) {z}	2 – 13 Pulse –STATUS Mode
S	
SOUT	2 – 9 Stop Streaming
T	
$TERM(?) \{z\}$	2 – 16 Response Termination
$TOKN(?) \{z\}$	2 – 15 Token Mode
TVAL? c [,n]	2 – 9 Temperature Value
V	
VOLT? c [,n]	2 – 9 Voltage Value

2 – 6 Remote Operation

2.3 Introduction

Remote operation of the SIM922 is through a simple command language documented in this chapter. Both set and query forms of most commands are supported, allowing the user complete control of the amplifier from a remote computer, either through the SIM900 Mainframe or directly via RS-232 (see Section 1.4.2.1).

See Table 1.2 for specification of the DB-15 SIM interface connector.

2.3.1 Power-on configuration

The settings for the remote interface are 9600 baud with no parity and hardware flow control, and local echo disabled (CONS 0FF).

Most of the SIM922 instrument settings are stored in non-volatile memory, and at power-on the instrument returns to the state it was last in when power was removed. Exceptions are noted in the command descriptions.

Reset values of parameters are shown in **boldface**.

2.3.2 Buffers

Incoming data from the host interface is stored in a 32-byte input buffer. Characters accumulate in the input buffer until a command terminator (either $\langle CR \rangle$ or $\langle LF \rangle$) is received, at which point the message is parsed and executed. Query responses from the SIM922 are buffered in a 64-byte output queue.

If the input buffer overflows, then all data in *both* the input buffer and the output queue are discarded, and an error is recorded in the CESR and ESR status registers.

2.3.3 Device Clear

The SIM922 host interface can be asynchronously reset to its power-on configuration by sending an RS-232-style (break) signal. From the SIM900 Mainframe, this is accomplished with the SRST command; if directly interfacing via RS-232, then use a serial break signal. After receiving the Device Clear, the interface is reset to 9600 baud and CONS mode is turned 0FF. Note that this *only* resets the communication interface; the basic function of the SIM922 is left unchanged; to reset the instrument, see *RST.

The Device Clear signal will also terminate any streaming outputs from the SIM922 due to a TVAL? or RVAL? query of multiple conversions.



2.4 Commands 2 – 7

2.4 Commands

This section provides syntax and operational descriptions for remote commands.

2.4.1 Command syntax

The four letter mnemonic (shown in CAPS) in each command sequence specifies the command. The rest of the sequence consists of parameters.

Commands may take either set or query form, depending on whether the "?" character follows the mnemonic. Set only commands are listed without the "?", query only commands show the "?" after the mnemonic, and optionally query commands are marked with a "(?)".

Parameters shown in { } and [] are not always required. Parameters in { } are required to set a value, and are omitted for queries. Parameters in [] are optional in both set and query commands. Parameters listed without any surrounding characters are always required.

Do *not* send () or { } or [] as part of the command.

Multiple parameters are separated by commas. Multiple commands may be sent on one command line by separating them with semicolons (;) so long as the input buffer does not overflow. Commands are terminated by either $\langle CR \rangle$ or $\langle LF \rangle$ characters. Null commands and whitespace are ignored. Execution of command(s) does not begin until the command terminator is received.

tokens

Token parameters (generically shown as z in the command descriptions) can be specified either as a keyword or integer value. Command descriptions list the valid keyword options, with each keyword followed by its corresponding integer value. For example, to set the response termination sequence to $\langle CR \rangle + \langle LF \rangle$, the following two commands are equivalent:

TERM CRLF —or— TERM 3

For queries that return token values, the return format (keyword or integer) is specified with the TOKN command.

2 – 8 Remote Operation

2.4.2 Notation

The following table summarizes the notation used in the command descriptions:

symbol	definition
i,j	Integers
f,g	Floating-point values
С	Channel number (0–4); <i>c</i> =0 means "all"
Z	Literal token
s	Arbitrary character sequence (no "," or ";")
(?)	Required for queries; illegal for set commands
var	Parameter always required
{ <i>var</i> }	Required parameter for set commands; illegal for queries
[var]	Optional parameter for both set and query forms



2.4 *Commands* 2–9

2.4.3 Readout commands

VOLT? c [,n]	Voltage Value
	Query the sensor voltage for channel c .
	If c =0, then all four channels are returned in the format: $$, $$, $$, $$.
	If the optional parameter n is provided, then n sequential conversion results are returned to the host. If n =0, the conversion results continue indefinitely. To terminate the stream before n results (or when n =0), issue the SOUT command.
	Note that omitting <i>n</i> is equivalent to <i>n</i> =1.
TVAL? c [,n]	Temperature Value
	Query the sensor temperature value for channel <i>c</i> .
	If c =0, then all four channels are returned in the format: $$, $$, $$, $$.
	If the optional parameter n is provided, then n sequential conversion results are returned to the host. If n =0, the conversion results continue indefinitely. To terminate the stream before n results (or when n =0), issue the SOUT command.
	Note that omitting <i>n</i> is equivalent to <i>n</i> =1.
SOUT	Stop Streaming

2.4.4 Excitation commands

$EXON(?) c \{,z\}$	Excitation On/Off
	Set (query) the Channel c excitation current {to $z=(0FF \ 0, 0N \ 1)$ }.
	If c =0, then all four channel excitation states are set (queried).

Turn off streaming output.

2 – 10 Remote Operation

2.4.5 Display & configuration commands

DISX(?) {z}	Display Enable/Disable
	Set (query) the front panel display $\{\text{to }z=(\text{OFF }0,\text{ON }1)\}.$
	The DISX setting is <i>not</i> stored in non-volatile memory. At power-on, the SIM922 returns to DISX ON.
DTEM(?) {z }	Display Temperature
	Set (query) the display temperature mode {to $z=(0FF \ 0, 0N \ 1)$ }.
	If DTEM OFF, then results are displayed in ohms; otherwise, results are displayed in kelvin.
FPLC(?) { <i>i</i> }	Frequency of Power Line Cycle
	Set (query) the power line rejection frequency {to $j=(50,60)$ }, in Hz.

2.4.6 Sensor calibration commands

In addition to the built-in curve, each channel has a dedicated 256-point non-volatile memory for storing user calibration curves. Once loaded, these curves are retained by the SIM922 though power cycles.

CINI(?) c {,z,s }

Initialize Sensor Calibration

Initialize sensor calibration curve for channel c.

The set form of the command, CINI *c,z,s*, erases the old curve for channel *c*. The second parameter *z*specifies the curve format, as one of:

Z	meaning
LINEAR 0	volts, kelvin
SEMILOGT 1	volts, $log_{10}(kelvin)$ $log_{10}(volts)$, $kelvin$ $log_{10}(volts)$, $log_{10}(kelvin)$
SEMILOGV 2	$log_{10}(volts)$, kelvin
LOGLOG 3	$\log_{10}(\text{volts})$, $\log_{10}(\text{kelvin})$

The third parameter *s* is an arbitrary identification string for this sensor calibration curve. This string can consist of any non-blank characters *except* the comma "," or semicolon ";", and can be up to 15 characters in length.

The query form of the command, CINI? *c*, returns the following response:

 $\langle \text{format} \rangle$, $\langle \text{serial} \rangle$, n

where $\langle \text{format} \rangle$ is the calibration curve format (same as *z* above), $\langle \text{serial} \rangle$ is the identification string (*s* above), and *n* is the number of



2.4 *Commands* 2 – 11

	points currently stored in the curve.
CAPT c,f,g	Add User Curve Point
	Add a new point to the channel c user curve. f is the raw sensor value (in either volts or $\log_{10}(\text{volts})$, depending on curve format), and g is the corresponding temperature value (in either kelvin or $\log_{10}(\text{kelvin})$, again depending on curve format).
	Note that curve points <i>must</i> be added in increasing order of sensor value <i>f</i> .
CAPT? c,j	Query User Curve Point
	Query the value of the channel c user curve, entry point j .
	The response is $\langle sensor \rangle$, $\langle temperature \rangle$, where $\langle sensor \rangle$ is the raw sensor value (in either volts or $log_{10}(volts)$, depending on curve format), and $\langle temperature \rangle$ is the corresponding temperature value (in either kelvin or $log_{10}(kelvin)$, again depending on curve format).
CURV(?) c {,z }	Select Sensor Curve
	Set (query) the sensor curve selection for channel c {to $z=(STAN \ 0, USER \ 1)$ }.
	If <i>c</i> =0, all four channels are set (queried).
	The built-in standard curve is selected by <i>z</i> =STAN. When CURV USER is selected, the user calibration curve (previously loaded with CINI and CAPT) is used.

2.4.7 Serial communication commands

$BAUD(?) \{i\}$ Baud Rate

Set (query) the baud rate $\{\text{to }i\}$.

At power-on, the baud rate defaults to 9600.

Actual baud rate settings depend on implementation details of the SIM922, based on modulo prescalars of the 10 MHz system clock. As a result, queries of BAUD? will in general be slightly different from the set values. For example, after setting BAUD 9600, the query BAUD? will respond 9470. The functional requirement for successful asynchronous serial communication is no greater than $\sim 5\,\%$ mismatch in baud rates.



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FLOW(?) { <i>z</i> }	Flow Control
	Set (query) flow control {to $z=(NONE 0, RTS 1, XON 2)$ }.
	At power-on, the SIM922 defaults to FLOW RTS flow control.
PARI(?) {z }	Parity
	Set (query) parity {to $z = (NONE \ 0, ODD \ 1, EVEN \ 2, MARK \ 3, SPACE \ 4)}.$
	At power-on, the SIM922 defaults to PARI NONE.
2.4.8 Status commands	
	The Status commands query and configure registers associated with status reporting of the SIM922. See Section 2.5 for more details.
*CLS	Clear Status
	*CLS immediately clears the ESR, CESR, and the OVSR.
*STB? [i]	Status Byte
	Reads the Status Byte register [bit i].
	Execution of the *STB? query (without the optional bit <i>i</i>) always causes the –STATUS signal to be deasserted. Note that *STB? <i>i</i> will <i>not</i> clear –STATUS, even if bit <i>i</i> is the only bit presently causing the –STATUS signal.
*SRE(?) [i,] {j }	Service Request Enable
	Set (query) the Service Request Enable register [bit <i>i</i>] {to <i>j</i> }.
*ESR? [i]	Standard Event Status
	Reads the Standard Event Status Register [bit i].
	Upon executing *ESR?, the returned bit(s) of the ESR register are cleared.
*ESE(?) [i,] {j}	Standard Event Status Enable
	Set (query) the Standard Event Status Enable Register [bit <i>i</i>] {to <i>j</i> }.
CESR? [i]	Communication Error Status
	Query Communication Error Status Register [for bit <i>i</i>].
	Upon executing a CESR? query, the returned bit(s) of the CESR register are cleared.



2.4 Commands 2 – 13

CESE(?) [i,]{j}	Communication Error Status Enable	
	Set (query) Communication Error Status Enable Register [bit i] {to j }.	
OVSR? [i]	Overload Status	
	Query Overload Status Register [for bit i].	
	Upon executing a OVSR? query, the returned bit(s) of the OVSR register are cleared.	
OVSE(?) [i,]{j}	Overload Status Enable	
	Set (query) Overload Status Enable Register [bit i] {to j}.	
PSTA(?) {z }	Pulse –STATUS Mode	
	Set (query) the Pulse –STATUS Mode {to $z=(0FF \ 0, 0N \ 1)$ }.	
	When PSTA ON is set, any new service request will only <i>pulse</i> the $-STATUS$ signal low (for a minimum of 1 μ s). The default behavior is to latch $-STATUS$ low until a *STB? query is received.	
	At power-on, PSTA is set to 0FF.	

2.4.9 Interface commands

*RST	Reset		
	Reset the SIM922 to default configuration.		
	The following commands are internally executed upon *RST:		
	• EXON 0, ON		
	• CURV 0, STAN		
	DTEM ON		
	• SOUT		
	• DISX ON		
CONS(?) {z}	Console Mode		
	Set (query) the Console mode {to $z=(0FF \ 0, 0N \ 1)$ }.		
	CONS causes each character received at the Input Buffer to be copied to the Output Queue.		
	At power-on and Device-Clear, CONS is set to 0FF.		

2 – 14 Remote Operation

*IDN?	Identify		
	Read the device identification string.		
	The identification string is formatted as: Stanford_Research_Systems, SIM922, s/n*****, ver#.# where ****** is the 6-digit serial number, and #.# is the firmware revision level.		
*OPC(?)	Operation Complete		
	Operation Complete. Sets the OPC flag in the ESR register.		
	The query form *OPC? writes a 1 in the output queue when complete, but does not affect the ESR register.		
LEXE?	Execution Error		
	Query the last execution error code. Valid codes are:		
	Value Definition		
	 No execution error since last LEXE? Illegal value Wrong token Invalid bit Uninitialized curve Curve full Curve point out-of-order Curve point past end 		



2.4 *Commands* 2 – 15

LCME?	Device Error				
	Query the last command error code. Valid codes are:				
	Value Definition				
	No command error since last LCME? Illegal command Undefined command Illegal query Illegal set Missing parameter(s) Extra parameter(s) Null parameter(s) Parameter buffer overflow Bad floating-point Bad integer Bad integer Bad token value Bad hex block Unknown token				
LDDE?	Device Error Query the last device error code. The only valid code is: 1 — Curve Erased				
LBTN?	Button				
	Query the last button-press code. Valid codes are:				
	Value Definition				
	 no button pressed since last query [Units] [Excitation] 				
TOKN(?) {z}	Token Mode				
	Set (query) the Token Query mode {to $z=(\mathbf{0FF}\ 0, \mathbf{0N}\ 1)$ }.				
	If TOKN ON is set, then queries to the SIM922 that return tokens will return the text keyword; otherwise they return the decimal integer value.				
	Thus, the only possible responses to the TOKN? query are ON and O.				

2 – 16 Remote Operation

$TERM(?) \{z\}$

Response Termination

Set (query) the $\langle \text{term} \rangle$ sequence {to $z=(\text{NONE 0, CR 1, LF 2, CRLF 3, LFCR 4)}}.$

The \(\text{term}\) sequence is appended to all query responses sent by the module, and is constructed of ASCII character(s) 13 (carriage return) and/or 10 (line feed).

At power-on, TERM CRLF is set.



2.5 Status Model 2 – 17

2.5 Status Model

The SIM922 status registers follow the hierarchical IEEE–488.2 format. A block diagram of the status register array is given in Figure 2.1.

There are two categories of registers in the SIM922 status model:

Event Registers: These read-only registers record the occurrence of defined

events. When the event occurs, the corresponding bit is set to 1. Upon querying an event register, any set bits within it are cleared. These are sometimes known as "sticky bits," since once set, a bit can only be cleared by reading its value. Event

register names end with SR.

Enable Registers: These read/write registers define a bitwise mask for their cor-

responding event register. If any bit position is set in an event register while the same bit position is also set in the enable register, then the corresponding summary bit message is set.

Enable register names end with SE.

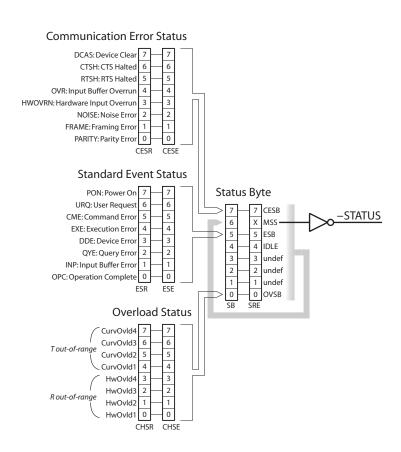


Figure 2.1: Status Register Model for the SIM922 Diode Temperature Monitor.



2 – 18 Remote Operation

2.5.1 Status Byte (SB)

The Status Byte is the top-level summary of the SIM922 status model. When masked by the Service Request Enable register, a bit set in the Status Byte causes the –STATUS signal to be asserted on the rearpanel SIM interface connector.

Typically, –STATUS remains asserted (low) until a *STB? query is received, at which time –STATUS is deasserted (raised)¹. After clearing the –STATUS signal, it will only be re-asserted in response to a *new* status-generating condition.

Weight	Bit	Flag
1	0	OVSB
2	1	undef (0)
4	2	undef (0)
8	3	undef (0)
16	4	IDLE
32	5	ESB
64	6	MSS
128	7	CESB

OVSB: Overload Status Summary Bit. Indicates whether one or more of the enabled flags in the Overload Status Register has become true.

IDLE: Indicates that the Input Buffer is empty and the command parser is idle. Can be used to help synchronize SIM922 query responses.

ESB: Event Status Bit. Indicates whether one or more of the enabled events in the Standard Event Status Register is true.

MSS: Master Summary Status. Indicates whether one or more of the enabled status messages in the Status Byte register is true. Note that while –STATUS is released by the *STB? query, MSS is only cleared when the underlying enabled bit message(s) are cleared.

CESB: Communication Error Summary Bit. Indicates whether one or more of the enabled flags in the Communication Error Status Register has become true.

Bits in the Status Byte are *not* cleared by the *STB? query. These bits are only cleared by reading the underlying event registers, or by clearing the corresponding enable registers.



¹ but see the PSTA command

2.5 Status Model 2 – 19

2.5.2 Service Request Enable (SRE)

Each bit in the SRE corresponds one-to-one with a bit in the SB register, and acts as a bitwise AND of the SB flags to generate the MSS bit in the SB and the –STATUS signal. Bit 6 of the SRE is undefined—setting it has no effect, and reading it always returns 0. This register is set and queried with the *SRE(?) command.

This register is cleared at power-on.

2.5.3 Standard Event Status (ESR)

The Standard Event Status register consists of 8 event flags. These event flags are all "sticky bits" that are set by the corresponding event, and cleared only by reading or with the *CLS command. Reading a single bit (with the *ESR? *i* query) clears only bit *i*.

Weight	Bit	Flag
1	0	OPC
2	1	INP
4	2	QYE
8	3	DDE
16	4	EXE
32	5	CME
64	6	URQ
128	7	PON

OPC: Operation Complete. Set by the *OPC command.

INP: Input Buffer Error. Indicates data has been discarded from the Input Buffer.

QYE: Query Error. Indicates data in the Output Queue has been lost.

DDE: Device Dependent Error. Indicates a SIM922 had a delayed execution error, due to an illegal mode state. The error code can be queried with LDDE?.

EXE: Execution Error. Indicates an error in a command that was successfully parsed. Out-of-range parameters are an example. The error code can be queried with LEXE?.

CME: Command Error. Indicates a parser-detected error. The error code can be queried with LCME?.

URQ: User Request. Indicates a front-panel button was pressed.

PON: Power On. Indicates that an off-to-on transition has occurred

2 – 20 Remote Operation

2.5.4 Standard Event Status Enable (ESE)

The ESE acts as a bitwise AND with the ESR register to produce the single bit ESB message in the Status Byte Register (SB). It can be set and queried with the *ESE(?) command.

This register is cleared at power-on.

2.5.5 Communication Error Status (CESR)

The Communication Error Status register consists of 8 event flags; each of which is set by the corresponding event, and cleared only by reading or with the *CLS command. Reading a single bit (with the CESR? *i* query) clears only bit *i*.

Bit	Flag
0	PARITY
1	FRAME
2	NOISE
3	HWOVRN
4	OVR
5	RTSH
6	CTSH
7	DCAS
	0 1 2 3 4 5 6

PARITY: Parity Error. Set by serial parity mismatch on incoming data byte.

FRAME: Framing Error. Set when an incoming serial data byte is missing the STOP bit.

NOISE: Noise Error. Set when an incoming serial data byte does not present a steady logic level during each asynchronous bit-period window.

HWOVRN: Hardware Overrun. Set when an incoming serial data byte is lost due to internal processor latency. Causes the Input Buffer to be flushed, and resets the command parser.

OVR: Input Buffer Overrun. Set when the Input Buffer is overrun by incoming data. Causes the Input Buffer to be flushed, and resets the command parser.

RTSH: Undefined for the SIM922. Command Error. Indicates a parser-detected error.

CTSH: Undefined for the SIM922.

DCAS: Device Clear. Indicates the SIM922 received the Device Clear signal (an RS-232 (break)). Clears the Input Buffer and Output Queue, and resets the command parser.



2.5 Status Model 2 – 21

2.5.6 Communication Error Status Enable (CESE)

The CESE acts as a bitwise AND with the CESR register to produce the single bit CESB message in the Status Byte Register (SB). It can be set and queried with the CESE(?) command.

This register is cleared at power-on.

2.5.7 Overload Status (OVSR)

The Overload Status register consists of 8 event flags; each of which is set by the corresponding event, and cleared only by reading or with the *CLS command. Reading a single bit (with the OVSR? *i* query) clears only bit *i*.

Weight	Bit	Flag
1	0	HwOvld1
2	1	HwOvld2
4	2	HwOvld3
8	3	HwOvld4
16	4	CurvOvld1
32	5	CurvOvld2
64	6	CurvOvld3
128	7	CurvOvld4

HwOvldn: Hardware Overload. Indicates channel n resistance measured

in excess of $\sim 1500 \,\Omega$.

CurvOvldn: Curve Out-of-range. Indicates channel n resistance measure-

ment falls outside the bounds of the selected calibration curve.

2.5.8 Channel Status Enable (OVSE)

The OVSE acts as a bitwise AND with the OVSR register to produce the single bit OVSB message in the Status Byte Register (SB). It can be set and queried with the OVSE(?) command.

This register is cleared at power-on.

